

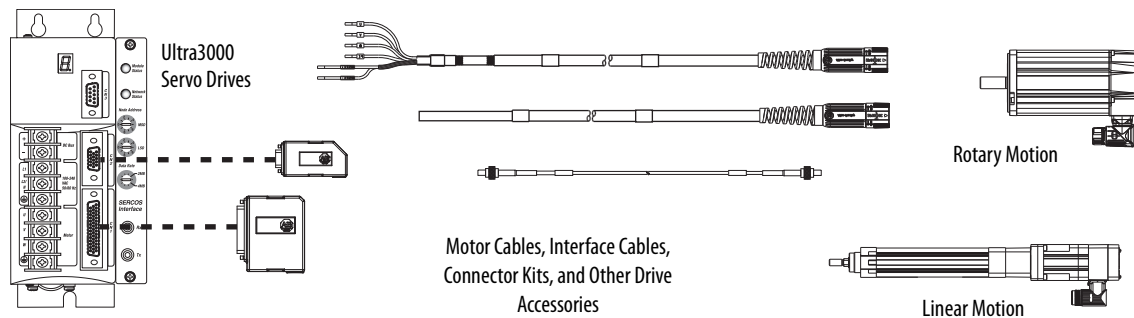
Ultra3000 Drive Systems

Catalog Numbers

2098-DSD-005, 2098-DSD-010, 2098-DSD-020, 2098-DSD-005X, 2098-DSD-010X, 2098-DSD-020X,
 2098-DSD-005-SE, 2098-DSD-010-SE, 2098-DSD-020-SE, 2098-DSD-005-DN, 2098-DSD-010-DN, 2098-DSD-020-DN,
 2098-DSD-005X-DN, 2098-DSD-010X-DN, 2098-DSD-020X-DN,

2098-DSD-030, 2098-DSD-075, 2098-DSD-150, 2098-DSD-030X, 2098-DSD-075X, 2098-DSD-150X,
 2098-DSD-030-SE, 2098-DSD-075-SE, 2098-DSD-150-SE, 2098-DSD-030-DN, 2098-DSD-075-DN, 2098-DSD-150-DN,
 2098-DSD-030X-DN, 2098-DSD-075X-DN, 2098-DSD-150X-DN,

2098-DSD-HV030, 2098-DSD-HV050, 2098-DSD-HV100, 2098-DSD-HV150, 2098-DSD-HV220,
 2098-DSD-HV030X, 2098-DSD-HV050X, 2098-DSD-HV100X, 2098-DSD-HV150X, 2098-DSD-HV220X,
 2098-DSD-HV030-SE, 2098-DSD-HV050-SE, 2098-DSD-HV100-SE, 2098-DSD-HV150-SE, 2098-DSD-HV220-SE,
 2098-DSD-HV030-DN, 2098-DSD-HV050-DN, 2098-DSD-HV100-DN, 2098-DSD-HV150-DN, 2098-DSD-HV220-DN,
 2098-DSD-HV030X-DN, 2098-DSD-HV050X-DN, 2098-DSD-HV100X-DN, 2098-DSD-HV150X-DN, 2098-DSD-HV220X-DN



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Introduction

This publication assumes that the drive family for your application is Ultra™ 3000 and that you have already determined your motor catalog number. To revisit those decisions, refer to the Kinetix® Motion Control Selection Guide, publication [GMC-SG001](#), or Motion Analyzer software.

The purpose of this publication is to assist you in identifying the drive system components and accessory items you'll need for your Ultra3000 drive and motor/actuator combination. Diagrams in this publication illustrate how many of the common drive accessory items are used in a typical system, but refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for detailed accessory descriptions and specifications.

Also provided are drive/motor or drive/actuator system combinations that include the following:

- Motor/cable combinations table
- Drive and motor/actuator performance specification table
- Torque/speed curves with each motor matched to the drive with optimum performance

Performance specification data and curves reflect nominal system performance of a typical system with motor/drive at rated ambient temperature and line voltage. For additional information on ambients, line conditions, and valid combinations not shown in this publication, refer to Motion Analyzer software.

IMPORTANT These system combinations do not include all possible motor/drive combinations. Please refer to Motion Analyzer software to verify compatibility. Download is available at <http://www.ab.com/motion/software/analyzer.html>.

Determine What You Need

For each Ultra3000 drive system, you need to know the drive and motor/actuator catalog numbers to determine the motor power and feedback cable catalog numbers. Interface cables and connector kits are also required. Optional equipment includes Bulletin 2090 AC line filter, shunt resistor, and others. Example diagrams of the required equipment listed on this page are shown on [page 4](#).

Ultra3000 Drive Modules

| Ultra3000 Drives Cat. No. | Input Voltage | Output Power (continuous) | Output Current (continuous) | Features |
|---------------------------|---------------|---------------------------|-----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 2098-DSD-005x-xx | 200V Class | 0.5 kW | 1.8 A, rms | <ul style="list-style-type: none"> Requires an external 12...24V power supply for proper operation of the digital I/O. Requires an external +5V power supply to maintain logic power when the AC line voltage is removed. ⁽¹⁾ |
| 2098-DSD-010x-xx | | 1.0 kW | 3.5 A, rms | |
| 2098-DSD-020x-xx | | 2.0 kW | 7.1 A, rms | |
| 2098-DSD-030x-xx | | 3.0 kW | 10.6 A, rms | |
| 2098-DSD-075x-xx | | 7.5 kW | 24.7 A, rms | |
| 2098-DSD-150x-xx | | 15 kW | 45.9 A, rms | |
| 2098-DSD-HV030x-xx | 400V Class | 3.0 kW | 5.0 A, rms | Requires an external 12...24V power supply for proper operation of the digital I/O. |
| 2098-DSD-HV050x-xx | | 5.0 kW | 7.8 A, rms | |
| 2098-DSD-HV100x-xx | | 10 kW | 16.3 A, rms | |
| 2098-DSD-HV150x-xx | | 15 kW | 24.0 A, rms | |
| 2098-DSD-HV220x-xx | | 22 kW | 33.2 A, rms | |

(1) Use external 24V I/O power supply to feed drive-mounted breakout boards (catalog numbers 2090-U3CBB-DM12 and 2090-U3CBB-DM44) with 24...5V DC converter.

Ultra3000 Servo Drive Communication Interface

| Drive Type | Drive Cat. No. | Command Interface |
|----------------------------------------|--------------------------------------------|-----------------------------------|
| SERCOS interface drive | 2098-DSD-xxx-SE and 2098-DSD-HVxxx-SE | Fiber-optic SERCOS module |
| Analog drive | 2098-DSD-xxx and 2098-DSD-HVxxx | Analog command interface |
| Digital drive with DeviceNet interface | 2098-DSD-xxx-DN and 2098-DSD-HVxxx-DN | DeviceNet communication interface |
| Indexing drive | 2098-DSD-xxxX and 2098-DSD-HVxxxX | Standalone control |
| Indexing DeviceNet interface drives | 2098-DSD-xxxX-DN and 2098-DSD-HVxxxX-DN | |

Refer to the Kinetix Servo Drives Specifications Technical Data, publication [GMC-TD003](#), for detailed descriptions and additional specifications for the Ultra3000 drive family.

Required Drive Accessories

| Drive Accessory | Description | Cat. No. |
|------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------|
| 24V power supply | 12...24V DC for control power and motor brakes. | 1606-XLxxx |
| Drive-mounted breakout boards (required for flying-lead cables) | Motor feedback (CN2) connections. | 2090-UXBB-DM15 |
| | Serial interface (CN3) connections. | 2090-UXBB-DM09 |
| | I/O (CN1) connections. These kits apply to all Ultra3000 drives and (catalog numbers 2098-DSD-005, 2098-DSD-010, and 2098-DSD-020) in applications where 5V DC control power (if required) is user-supplied. | 2090-U3BB-DM12 ⁽¹⁾ 2090-U3BB2-DM44 |
| | I/O (CN1) connections. These kits apply to only 2098-DSD-005, 2098-DSD-010, and 2098-DSD-020 drives in applications where a 24...5V DC converter for control power is required. | 2090-U3CBB-DM12 ⁽¹⁾ 2090-U3CBB-DM44 |
| SERCOS fiber-optic cables (required as needed for SERCOS applications) | Plastic, in-cabinet duty. | 2090-SCEPX-x |
| | Plastic, on-machine duty. | 2090-SCNPX-x |
| | Plastic, outdoor and conduit duty. | 2090-SCVPX-x |
| | Glass, outdoor and conduit duty. | 2090-SCVGX-x |
| Serial interface cable (required for non-SERCOS applications) | Ultra3000 serial interface to personal computer. | 2090-UXPC-D09xx |
| Motor power and feedback cables | Refer to the specific drive/motor combination for the motor cables required for your system. | |

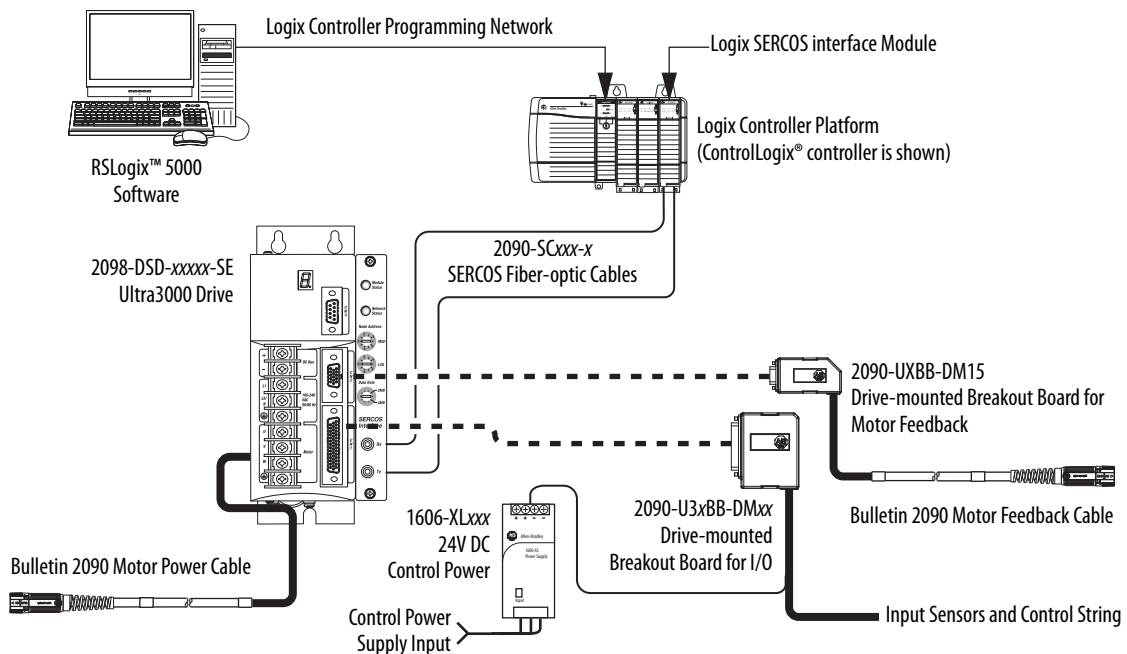
(1) The 12-pin board is intended for use with SERCOS drives, but may be used in non-SERCOS applications with minimal I/O requirements.

Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for detailed descriptions and specifications of these servo drive accessories.

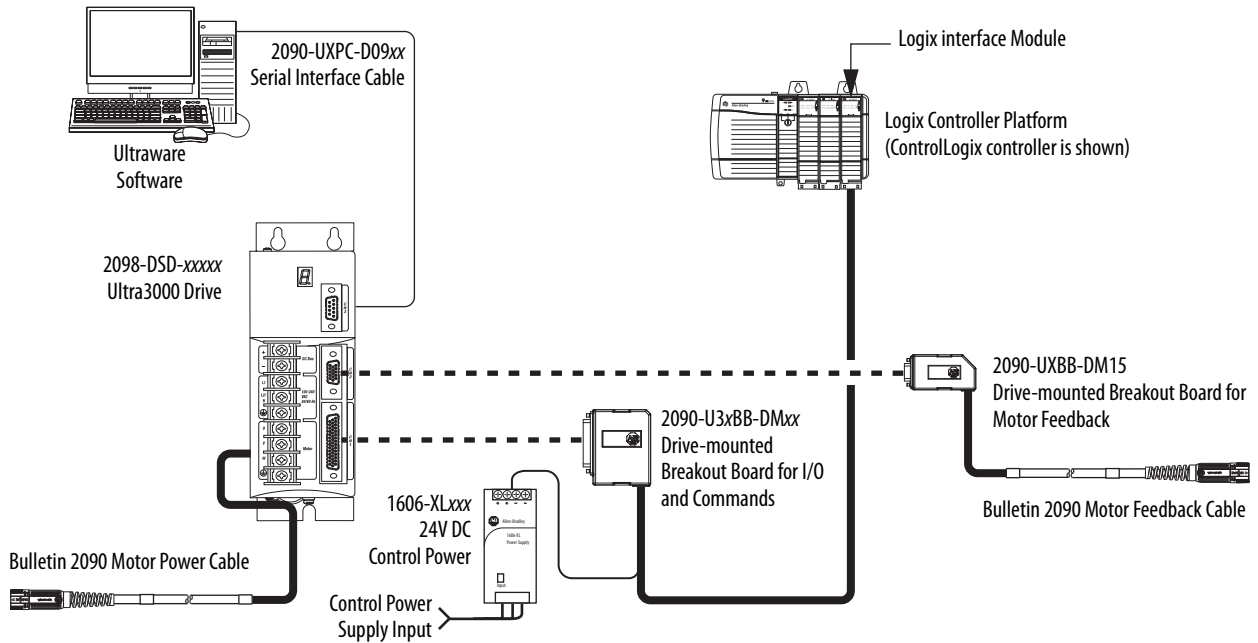
Ultra3000 System Examples

These system examples illustrate how the required drive modules and accessories are used in a typical system.

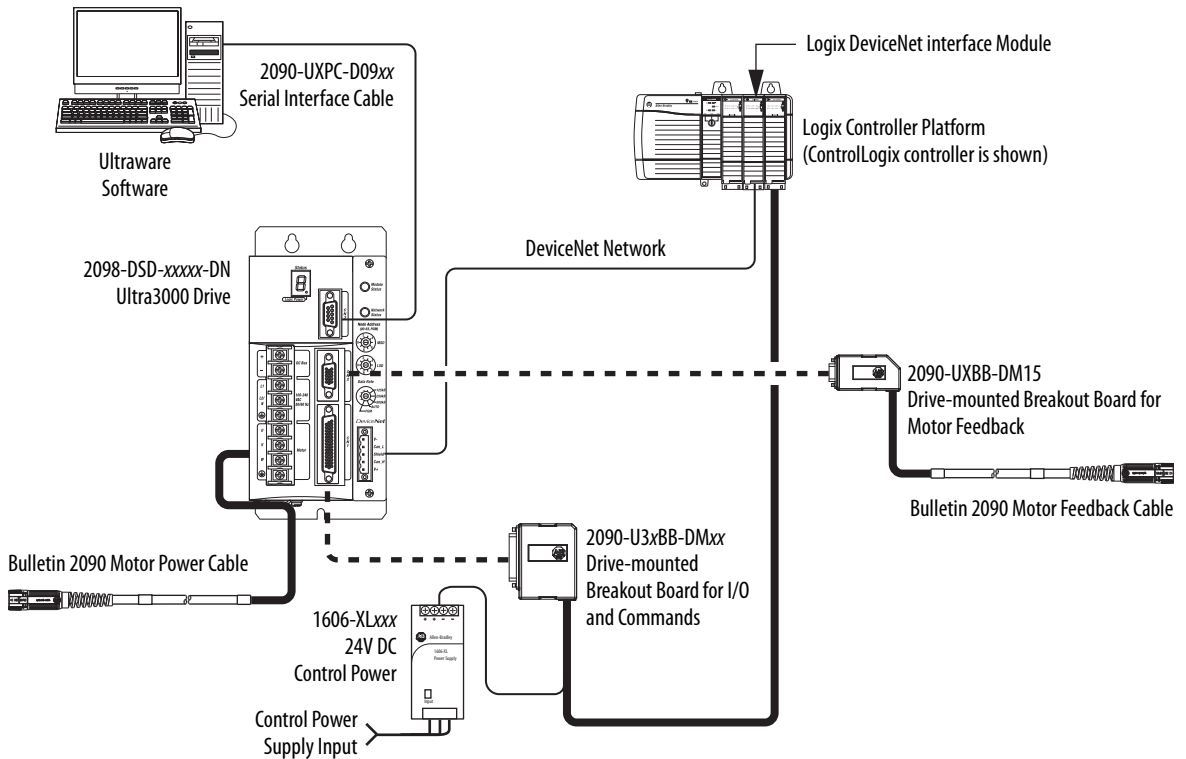
Ultra3000 System Example (SERCOS interface)



Ultra3000 System Example (analog or indexing)



Ultra3000 System Example (DeviceNet interface)

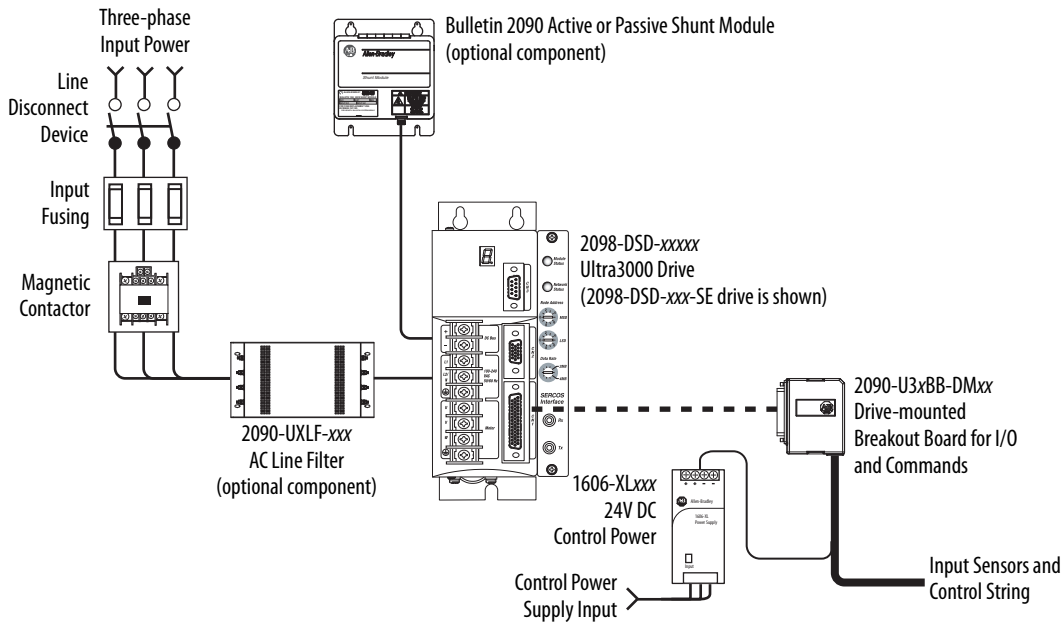


Optional Drive Accessories

| Drive Accessory | Description | Cat. No. |
|-------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------|-------------------------------------|
| Drive to 1756-M02AE module interface cable | Single-axis (CN1) flying-lead drive to Logix module cable. | 2090-U3CC-D44xx |
| | Two-axis (CN1) pre-wired drive to Logix module cable. | 2090-U3AE-D44xx |
| Drive-mounted breakout board for serial interface (applies to flying-lead cables as an alternative to serial interface cable) | 9-pin (CN3) breakout board for serial interface. | 2090-UxBB-DM09 |
| Panel-mounted breakout boards (applies to flying-lead cables as an alternative to drive-mounted breakout boards) | DIN rail mounted terminal block and cable for 15-pin (CN2) motor feedback connections. | 2090-UXBK-D15xx |
| | DIN rail mounted terminal block and cable for 44-pin (CN1) I/O connections. | 2090-U3BK-D44xx |
| 2090 AC line filters | AC line conditioning for EMC. Applies to 200V-class drives. | 2090-UXLF-xxx |
| | AC line conditioning for EMC. Applies to 400V-class drives. | 2090-UXLF-HVxxx |
| 2090 shunt modules | Applies to 2098-DSD-HV030, 2098-DSD-HV050, and 2098-DSD-HV100 drives. ⁽¹⁾ | 2090-SRxxx-xx |
| | Applies to 2098-DSD-075 and 2098-DSD-150 drives. | 2090-UCSR-P900 |
| | Applies to 2098-DSD-030 drives. | 9101-1183 |
| | Applies to 2098-DSD-005, 2098-DSD-010, and 2098-DSD-020 drives. | 2090-UCSR-A300 |
| Resistive brake module (RBM) | Physically and electrically separate the drive power output from its corresponding motor. | 2090-XBxxx-xx |
| RBM interface cables | Motor power, RBM to drive. | 2090-UXNRB-10F1P3 |
| | | 2090-UXNRB-8F1P4 |
| | | 2090-UXNRB-6F1P5 |
| External auxiliary encoder | Allen-Bradley® sine/cosine and incremental external encoders. | Bulletin 842A, 844D, 845H, and 845T |

(1) Refer to Rockwell Automation Encompass™ partners for 2098-DSD-HV150 and 2098-DSD-HV220 passive shunt solutions.

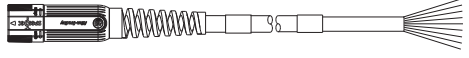
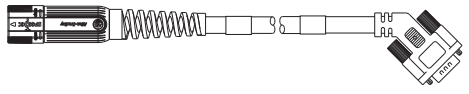
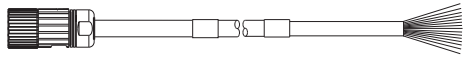


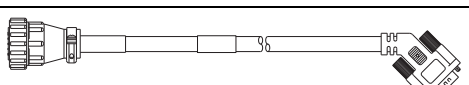
Ultra3000 Input Power Example



Motor-end cable connector kits, for use when building your own cables, are also available. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for detailed descriptions and specifications of optional servo drive accessories.

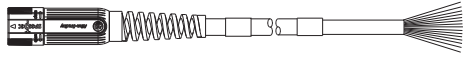
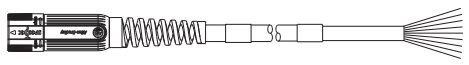
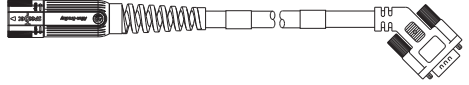
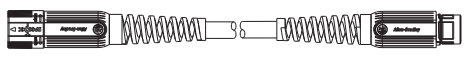
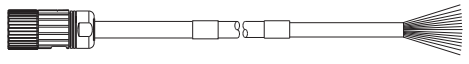

2090-Series Motor/Actuator Cables Overview

Feedback Cable Descriptions (standard, non-flex)

| Standard Cable Cat. No. | Description | Cable Configuration | | Motor/Actuator Connector |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------|-----------|-----------------------------|
| | | Motor/Actuator End | Drive End | |
| 2090-CFBM7DF-CEAxx | <ul style="list-style-type: none"> Drive-end flying-leads (DF) High-resolution or resolver applications (CE) |  | | SpeedTec DIN (M7) |
| 2090-CFBM7DD-CEAxx | <ul style="list-style-type: none"> Drive-end 15-pin connector (DD) High-resolution or resolver applications (CE) |  | | |
| 2090-XXNFMF-Sxx | <ul style="list-style-type: none"> Drive-end flying-leads High-resolution or incremental applications |  | | Threaded DIN (M4) |
| 2090-CFBM4E2-CATR | <ul style="list-style-type: none"> Drive-end bayonet (E2), transition (TR) cable ⁽¹⁾ Motor-end threaded DIN (M4) All feedback types (CA) |  | | |
| 2090-CFBM6DF-CBAAxx | <ul style="list-style-type: none"> Drive-end flying-leads (DF) High-resolution, battery backup or Incremental applications (CB) |  | | Circular Plastic (M6) |
| 2090-CFBM6DD-CCAxx | <ul style="list-style-type: none"> Drive-end 15-pin connector (DD) Incremental applications only (CC) |  | | |

(1) Threaded DIN connector (motor end) and bayonet connector for 2090-XXNFMF-Sxx cable.

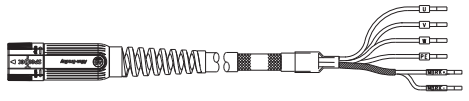
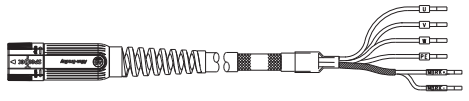
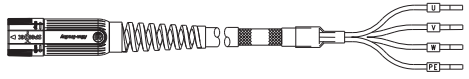
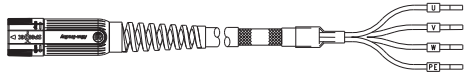
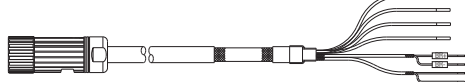
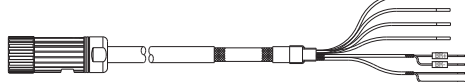
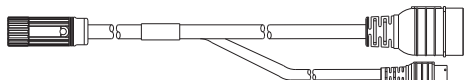
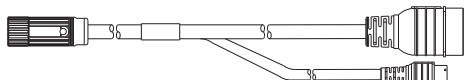
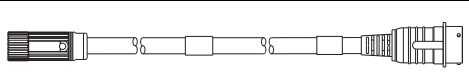
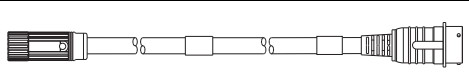
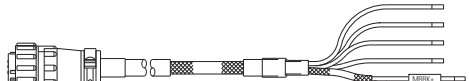
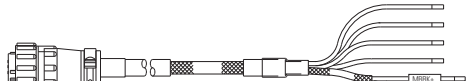
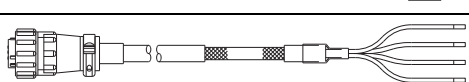
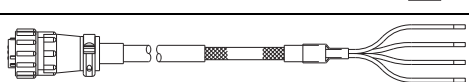
Feedback Cable Descriptions (continuous-flex)

| Continuous-flex Cable Cat. No. | Description | Cable Configuration | | Motor/Actuator Connector |
|-----------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|-----------|-----------------------------|
| | | Motor/Actuator End | Drive End | |
| 2090-CFBM7DF-CDAFxx | <ul style="list-style-type: none"> Drive-end flying-leads (DF) High-resolution or incremental applications (CD) |  | | SpeedTec DIN (M7) |
| 2090-CFBM7DF-CEAFxx | <ul style="list-style-type: none"> Drive-end flying-leads (DF) High-resolution or resolver applications (CE) |  | | |
| 2090-CFBM7DD-CEAFxx | <ul style="list-style-type: none"> Drive-end 15-pin connector (DD) High-resolution or resolver applications (CE) |  | | |
| 2090-CFBM7E7-CDAFxx | <ul style="list-style-type: none"> Drive-end (male) connector, extension (E7) ⁽¹⁾ Motor-end SpeedTec DIN cable plug (M7) |  | | |
| 2090-CFBM7E7-CEAFxx | |  | | |
| 2090-CFBM4DF-CDAFxx | <ul style="list-style-type: none"> Drive-end flying-leads High-resolution or incremental applications |  | | Threaded DIN (M4) |

(1) SpeedTec DIN connector (motor end) and male connector for extending SpeedTec or threaded DIN cable.

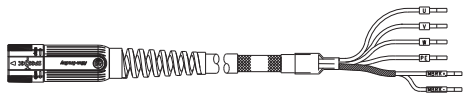
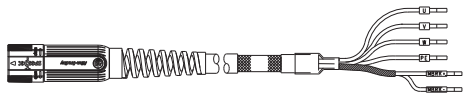
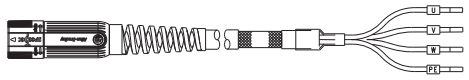
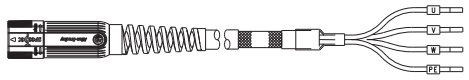
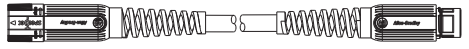
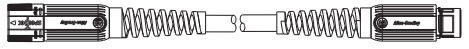
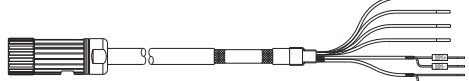
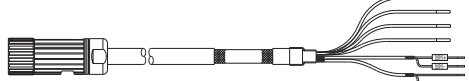
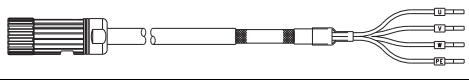
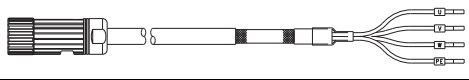
IMPORTANT Feedback cables with the CE designation, for example 2090-CFBM7DF-CEAxx, are intended for high-resolution encoder or resolver applications and have fewer conductors than feedback cables with the CD designation, for example 2090-CFBM7DF-CDAFxx, which are intended for high-resolution or incremental encoder applications.

Power/Brake Cable Descriptions (standard, non-flex)

| Standard Cable Cat. No. | Description | Cable Configuration | | Motor/Actuator Connector |
|-------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|--------------------------|
| | | Motor/Actuator End | Drive End | |
| 2090-CPBM7DF-xxAAxx | <ul style="list-style-type: none"> • Drive-end flying-leads (DF) • Power/brake wires (PB) |  |  | SpeedTec DIN (M7) |
| 2090-CPWM7DF-xxAAxx | <ul style="list-style-type: none"> • Drive-end flying-leads (DF) • Power wires only (PW) |  |  | |
| 2090-XXNPMF-xxSxx | <ul style="list-style-type: none"> • Drive-end flying-leads • Power/brake wires |  |  | |
| 2090-CPBM4E2-xxTR | <ul style="list-style-type: none"> • Drive-end bayonet (E2), transition (TR) cable ⁽¹⁾ • Motor-end threaded DIN (M4) • Power/brake wires (PB) |  |  | Threaded DIN (M4) |
| 2090-CPWM4E2-xxTR | <ul style="list-style-type: none"> • Drive-end bayonet (E2), transition (TR) cable ⁽¹⁾ • Motor-end threaded DIN (M4) • Power wires only (PW) |  |  | |
| 2090-CPBM6DF-16AAxx | <ul style="list-style-type: none"> • Drive-end flying-leads (DF) • Power/brake wires (PB) |  |  | Circular Plastic (M6) |
| 2090-CPWM6DF-16AAxx | <ul style="list-style-type: none"> • Drive-end flying-leads (DF) • Power wires only (PW) |  |  | |

(1) Threaded DIN connector (motor end) and bayonet connector for 2090-XXNFMP-Sxx cable.

Power/Brake Cable Descriptions (continuous-flex)

| Continuous-flex Cable Cat. No. | Description | Cable Configuration | | Motor/Actuator Connector |
|--------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|--------------------------|
| | | Motor/Actuator End | Drive End | |
| 2090-CPBM7DF-xxAFxx | <ul style="list-style-type: none"> • Drive-end flying-leads (DF) • Power/brake wires (PB) |  |  | SpeedTec DIN (M7) |
| 2090-CPWM7DF-xxAFxx | <ul style="list-style-type: none"> • Drive-end flying-leads (DF) • Power wires only (PW) |  |  | |
| 2090-CPBM7E7-xxAFxx | <ul style="list-style-type: none"> • Drive-end (male) connector, extension (E7) ⁽¹⁾ • Motor-end SpeedTec DIN cable plug (M7) |  |  | |
| 2090-CPBM4DF-xxAFxx | <ul style="list-style-type: none"> • Drive-end flying-leads (DF) • Power/brake wires (PB) |  |  | Threaded DIN (M4) |
| 2090-CPWM4DF-xxAFxx | <ul style="list-style-type: none"> • Drive-end flying-leads (DF) • Power wires only (PW) |  |  | |

(1) SpeedTec DIN connector (motor end) and male connector for extending SpeedTec or threaded DIN cable.

Ultra3000 (200V class) Drives with MP-Series Low Inertia Motors

This section provides system combination information for the Ultra3000 (200V class) drives when matched with MP-Series™ low-inertia motors. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

IMPORTANT The MP-Series low-inertia motors on this page are equipped with DIN connectors (specified by 7 in the catalog number) and are not compatible with cables designed for motors equipped with bayonet connectors (specified by 2 in the catalog number). The motors with bayonet connectors (for example, MPL-A310P-xx2xAA) are being discontinued and require 2090-XXNxMP (bayonet) cables. For help with migration or to select bayonet cables, contact your Rockwell Automation® sales representative.

Bulletin MPL Motor Cable Combinations

| Motor Cat. No. (200V class) | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MPL-A1510V-xx7xAA, MPL-A1520U-xx7xAA, MPL-A1530U-xx7xAA | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-CFBM7DF-CEAAxx ^{(2) (3)} or 2090-CFBM7DD-CEAAxx (standard, non-flex) 2090-CFBM7DF-CEAFxx or 2090-CFBM7DD-CEAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPL-A210V-xx7xAA, MPL-A220T-xx7xAA, MPL-A230P-xx7xAA | | |
| MPL-A310F-xx7xAA, MPL-A310P-xx7xAA, MPL-A320H-xx7xAA, MPL-A320P-xx7xAA, MPL-A330P-xx7xAA | | |
| MPL-A420P-xx7xAA, MPL-A430H-xx7xAA | | |
| MPL-A4530F-xx7xAA, MPL-A4540C-xx7xAA | | |
| MPL-A430P-xx7xAA | 2090-CPxM7DF-14AAxx (standard, non-flex) 2090-CPxM7DF-14AFxx (continuous-flex) | 2090-XXNFMF-5xx (standard, non-flex) ⁽⁴⁾ 2090-CFBM7DF-CDAFxx (continuous-flex) Incremental Feedback |
| MPL-A4530K-xx7xAA, MPL-A4540F-xx7xAA, MPL-A4560F-xx7xAA | | |
| MPL-A520K-xx7xAA | 2090-CPxM7DF-10AAxx (standard, non-flex) 2090-CPxM7DF-10AFxx (continuous-flex) | |
| MPL-A540K-xx7xAA, MPL-A560F-xx7xAA | 2090-CPxM7DF-08AAxx (standard, non-flex) 2090-CPxM7DF-08AFxx (continuous-flex) | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) with flying-lead cables on the drive end. Refer to Required Drive Accessories on [page 4](#).

(2) Applies to Ultra3000 drives and MPL-A3xxx-M/S...MPL-A5xxx-M/S motors with absolute high-resolution feedback.

(3) Applies to Ultra3000/5000 drives and MPL-A15xxx-V/E...MPL-A2xxx-V/E motors with absolute high-resolution feedback.

(4) Applies to Ultra3000 drives and MPL-A15xxx-H...MPL-A45xxx-H motors with incremental feedback.

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

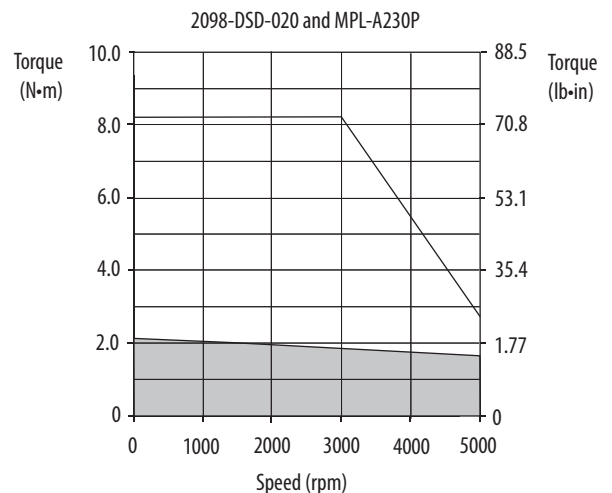
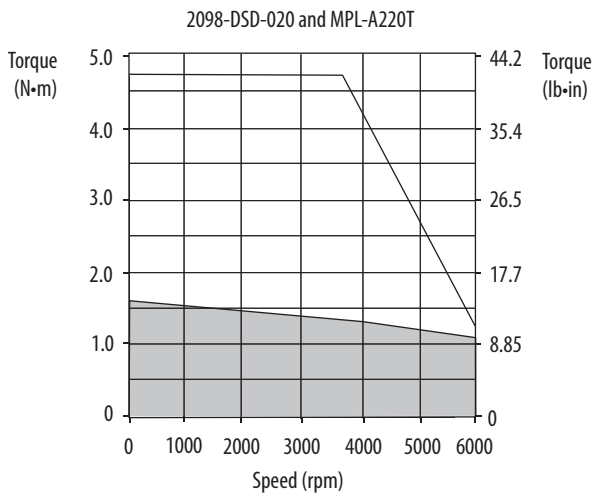
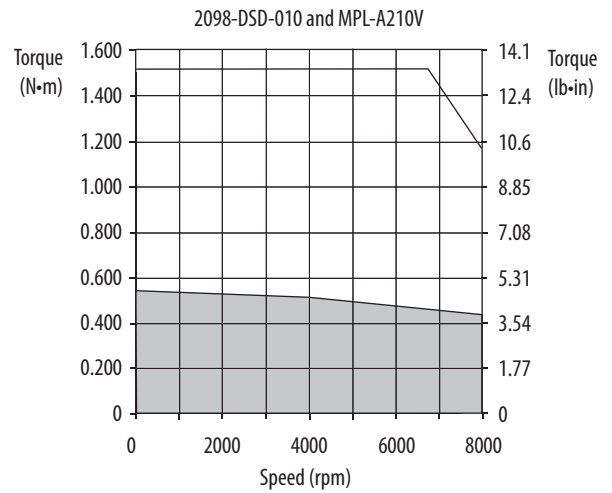
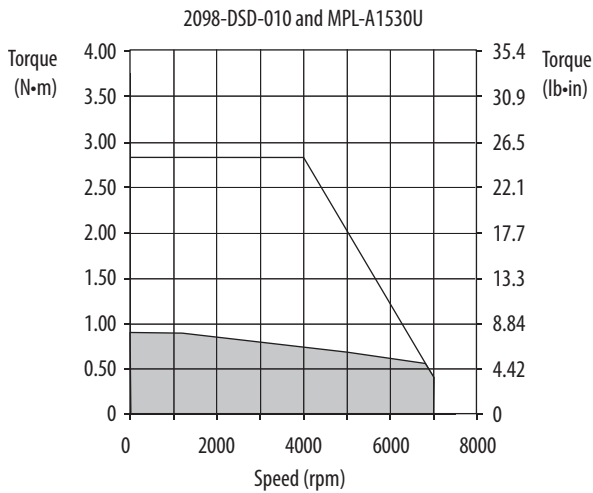
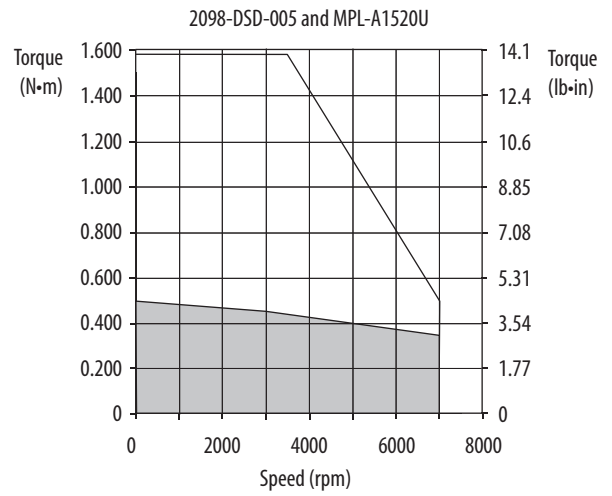
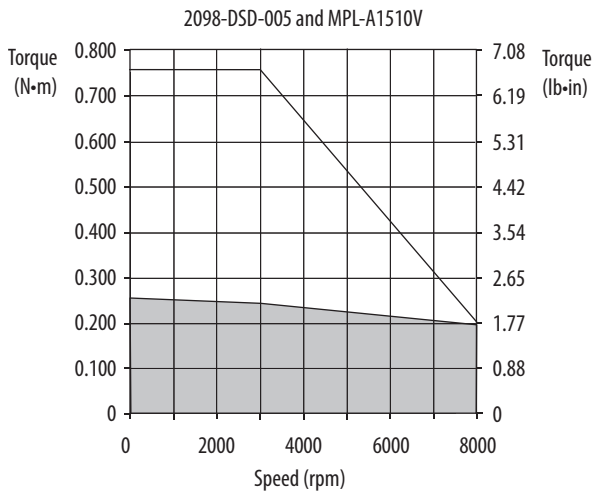
Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin MPL Motor Performance Specifications with Ultra3000 (200V class) Drives

| Rotary Motor | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A 0-pk | System Peak Stall Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 200V-class Drives |
|--------------|----------------|-------------------------------------------|-----------------------------------------------|-------------------------------------|-----------------------------------------|--------------------------|--------------------------------|
| MPL-A1510V | 8000 | 1.05 | 0.26 (2.3) | 3.40 | 0.77 (6.8) | 0.16 | 2098-DSD-005 |
| MPL-A1520U | 7000 | 1.80 | 0.49 (4.3) | 6.10 | 1.58 (13.9) | 0.27 | 2098-DSD-005 |
| MPL-A1530U | 7000 | 2.82 | 0.90 (8.0) | 10.1 | 2.82 (24.9) | 0.39 | 2098-DSD-010 |
| MPL-A210V | 8000 | 3.09 | 0.55 (4.8) | 10.2 | 1.52 (13.5) | 0.37 | 2098-DSD-010 |
| MPL-A220T | 6000 | 4.54 | 1.61 (14.2) | 15.5 | 4.74 (41.9) | 0.62 | 2098-DSD-020 |
| MPL-A230P | 5000 | 5.40 | 2.10 (18) | 23.0 | 8.2 (72.5) | 0.86 | 2098-DSD-020 |
| MPL-A310F | 3000 | 2.50 | 1.24 (11) | 7.5 | 2.94 (26) | 0.46 | 2098-DSD-005 |
| | | 3.20 | 1.58 (14) | 9.3 | 3.61 (32) | | 2098-DSD-010 |
| MPL-A310P | 5000 | 2.50 | 0.79 (6.9) | 7.5 | 1.92 (17) | 0.73 | 2098-DSD-005 |
| | | 4.85 | 1.58 (14) | 14 | 3.61 (32) | | 2098-DSD-010 |
| MPL-A320H | 3500 | 5.0 | 2.48 (22) | 15 | 6.44 (57) | 1.0 | 2098-DSD-010 |
| | | 6.1 | 3.05 (27) | 19.3 | 7.91 (70) | | 2098-DSD-020 |
| MPL-A320P | 5000 | 5.0 | 1.69 (15) | 15 | 3.95 (35) | 1.3 | 2098-DSD-010 |
| | | 9.0 | 3.05 (27) | 29.5 | 7.91 (70) | | 2098-DSD-020 |
| MPL-A330P | 5000 | 12.0 | 4.18 (37) | 30 | 9.60 (85) | 1.8 | 2098-DSD-030 |
| | | | | 38 | 11.1 (98) | | 2098-DSD-075 |
| MPL-A420P | 5000 | 12.7 | 4.74 (42) | 30 | 10.2 (90) | 2.0 | 2098-DSD-030 |
| | | | | 46 | 13.5 (120) | | 2098-DSD-075 |
| MPL-A430H | 3500 | 12.2 | 6.21 (55) | 30 | 14.7 (130) | 1.8 | 2098-DSD-030 |
| | | | | 45 | 19.8 (175) | | 2098-DSD-075 |
| MPL-A430P | 5000 | 15.0 | 5.42 (48) | 30 | 10.2 (90) | 2.2 | 2098-DSD-030 |
| | | 16.8 | 5.99 (53) | 67 | 19.8 (175) | | 2098-DSD-075 |
| MPL-A4530F | 2800 | 13.4 | 8.36 (74) | 30 | 17.5 (155) | 1.9 | 2098-DSD-030 |
| | | | | 42 | 20.3 (180) | | 2098-DSD-075 |
| MPL-A4530K | 4000 | 15.0 | 6.21 (55) | 30 | 11.3 (100) | 2.5 | 2098-DSD-030 |
| | | 19.5 | 8.13 (72) | 62 | 20.3 (180) | | 2098-DSD-075 |
| MPL-A4540C | 1500 | 9.4 | 10.2 (90) | 29 | 27.1 (240) | 1.5 | 2098-DSD-020 |
| MPL-A4540F | 3000 | 15.0 | 8.25 (73) | 30 | 15.8 (140) | 2.6 | 2098-DSD-030 |
| | | 18.4 | 10.2 (90) | 58 | 27.1 (240) | | 2098-DSD-075 |
| MPL-A4560F | 3000 | 22.0 | 14.1 (125) | 66 | 34.4 (305) | 3.0 | 2098-DSD-075 |
| MPL-A520K | 4000 | 23.3 | 10.7 (95.0) | 65 | 24.3 (215) | 3.5 | 2098-DSD-075 |
| MPL-A540K | 4000 | 41.5 | 19.4 (172) | 120 | 48.6 (430) | 5.5 | 2098-DSD-150 |
| MPL-A560F | 3000 | 42.0 | 26.8 (237) | | 61.0 (540) | 5.3 | 2098-DSD-150 |

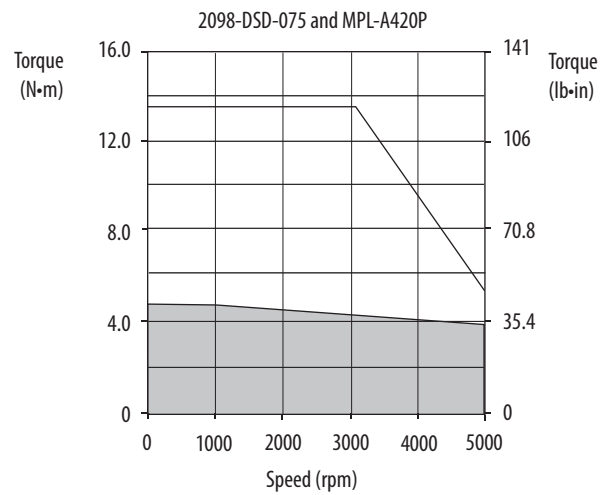
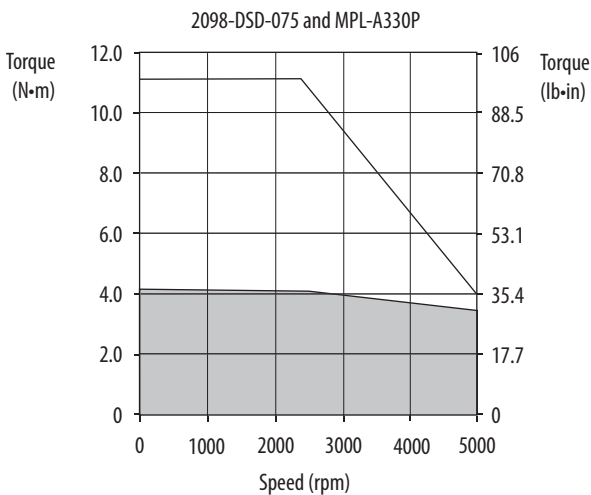
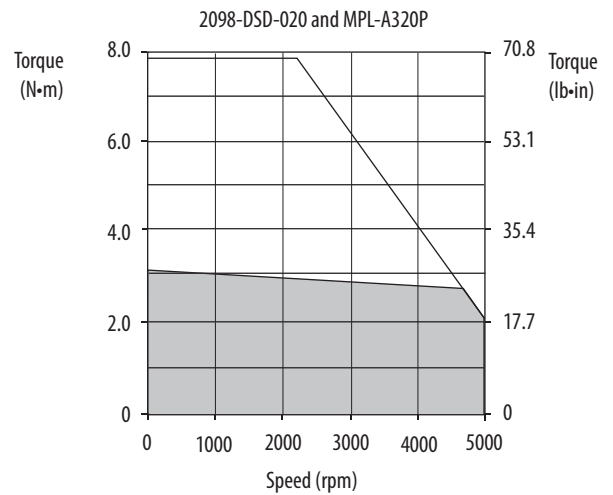
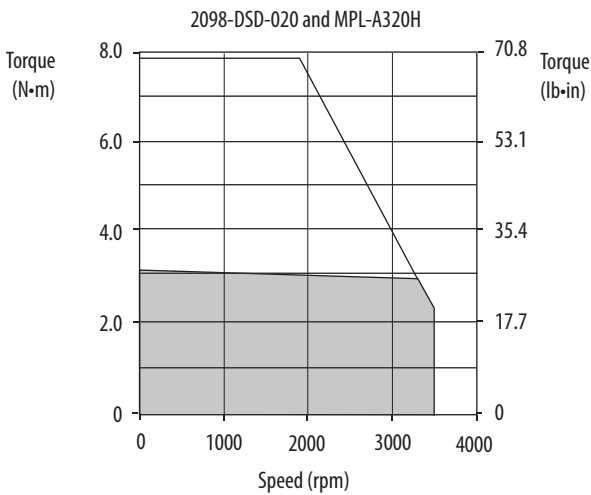
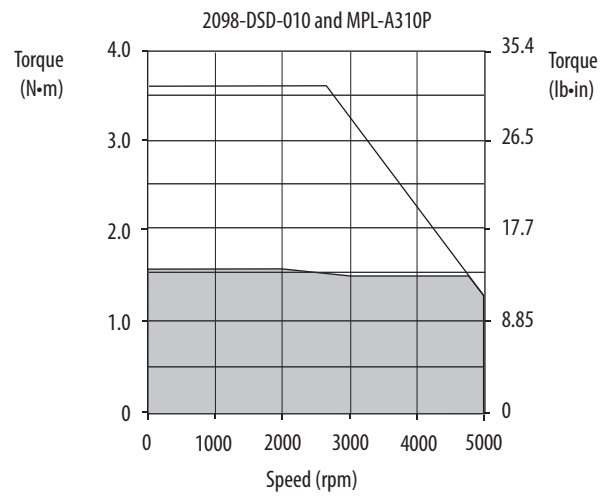
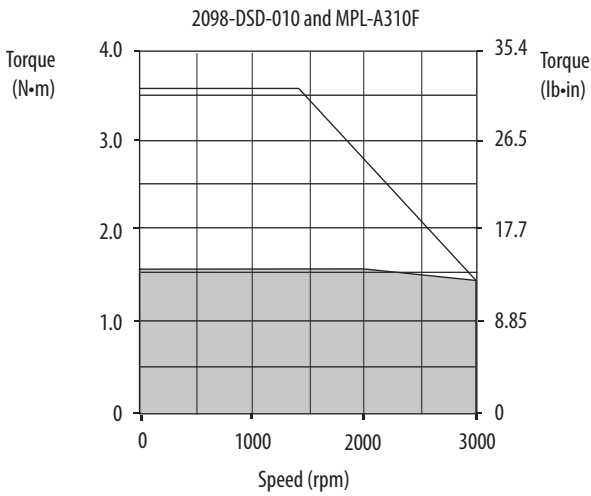
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (200V class) Drives/MP-Series Low Inertia Motor Curves



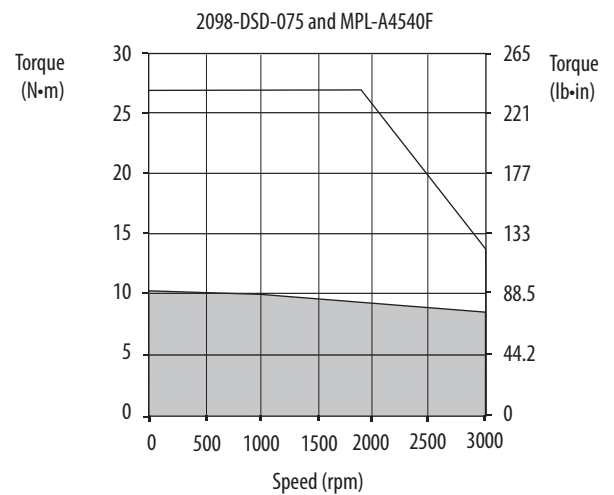
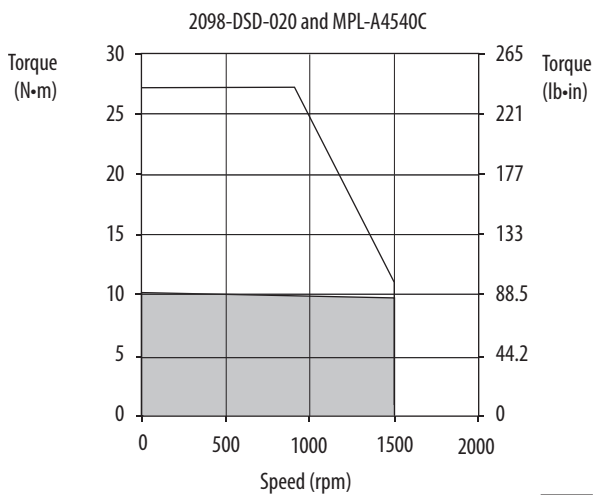
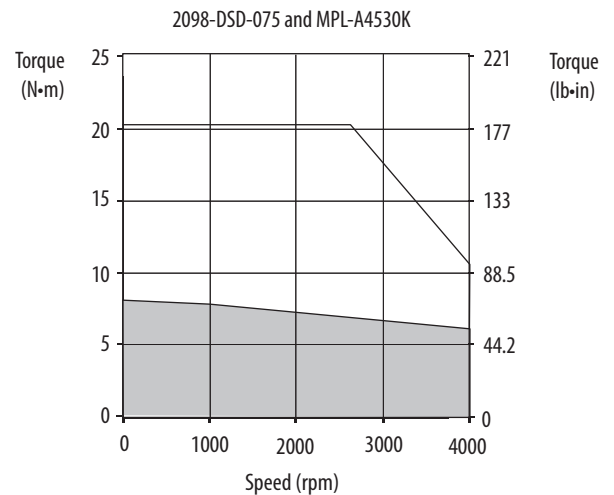
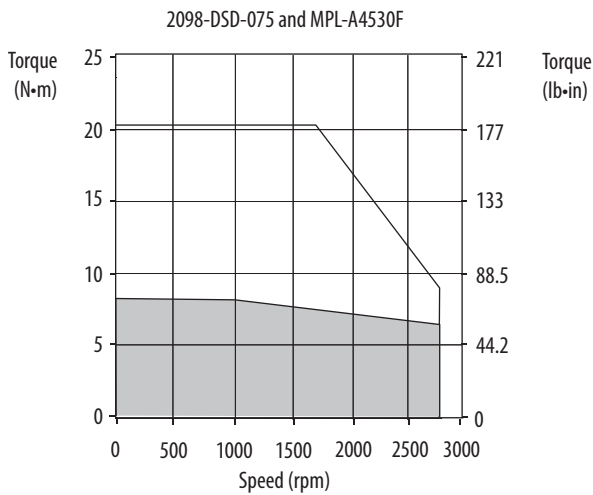
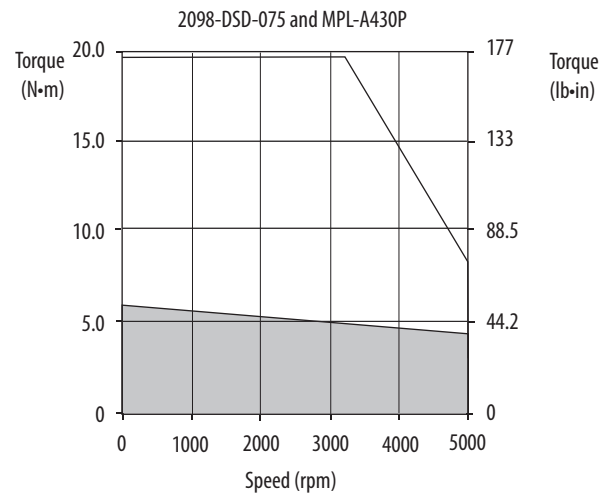
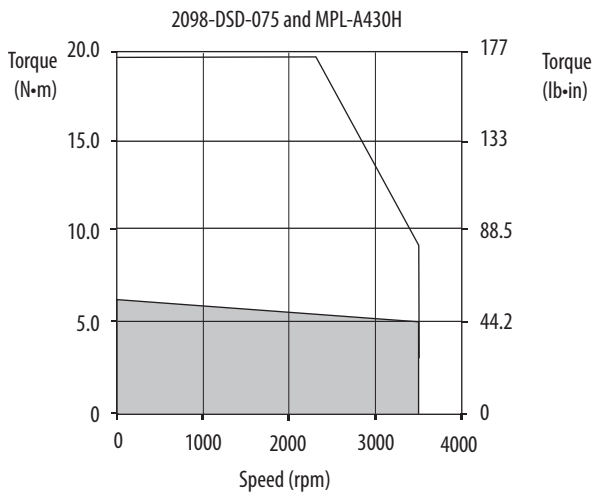
= Intermittent operating region
 = Continuous operating region

Ultra3000 (200V class) Drives/MP-Series Low Inertia Motor Curves (continued)



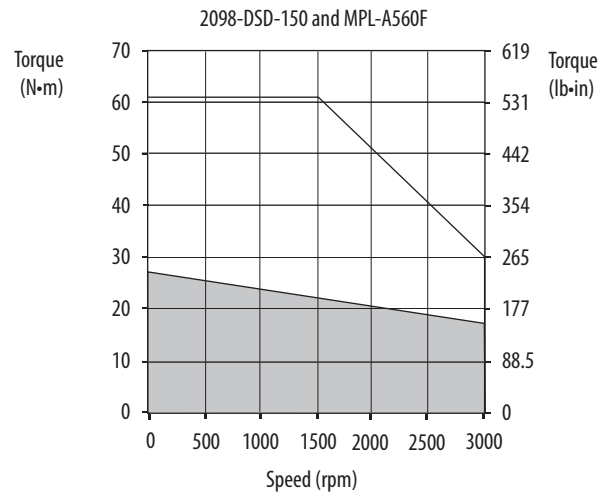
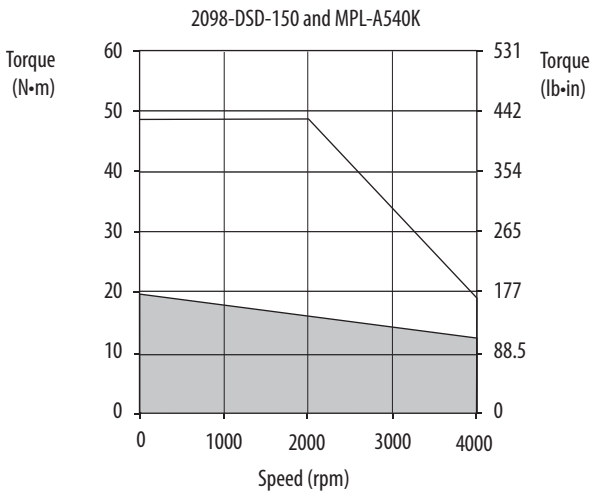
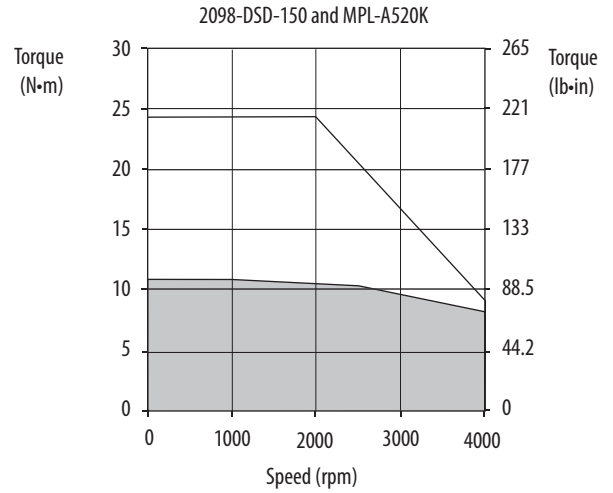
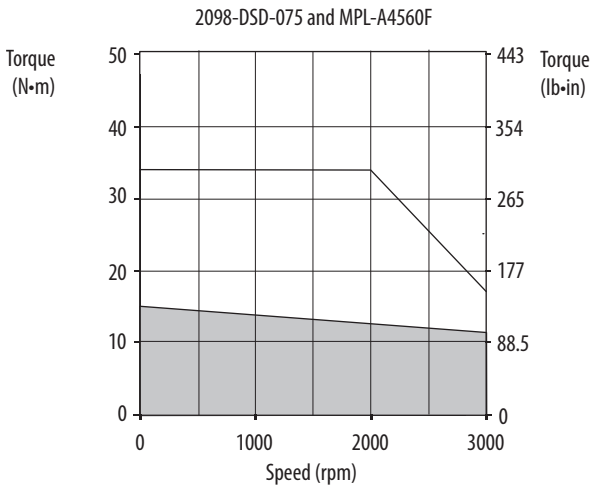
= Intermittent operating region
 = Continuous operating region

Ultra3000 (200V class) Drives/MP-Series Low Inertia Motor Curves (continued)



= Intermittent operating region
 = Continuous operating region

Ultra3000 (200V class) Drives/MP-Series Low Inertia Motor Curves (continued)



= Intermittent operating region
 = Continuous operating region

Ultra3000 (400V class) Drives with MP-Series Low Inertia Motors

This section provides system combination information for the Ultra3000 (400V class) drives when matched with MP-Series low-inertia motors. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

IMPORTANT The MP-Series low-inertia motors on this page are equipped with DIN connectors (specified by 7 in the catalog number) and are not compatible with cables designed for motors equipped with bayonet connectors (specified by 2 in the catalog number). The motors with bayonet connectors (for example, MPL-A310P-xx2xAA) are being discontinued and require 2090-XXNxMP (bayonet) cables. For help with migration or to select bayonet cables, contact your Rockwell Automation sales representative.

Bulletin MPL Motor Cable Combinations

| Motor Cat. No. (400V class) | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|-------------------------------------------------------------------------------|-----------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MPL-B1510V-xx7xAA, MPL-B1520U-xx7xAA, MPL-B1530U-xx7xAA | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-CFBM7DF-CEAAxx or ^{(2) (3)} 2090-CFBM7DD-CEAAxx (standard, non-flex) 2090-CFBM7DF-CEAFxx or 2090-CFBM7DD-CEAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPL-B210V-xx7xAA, MPL-B220T-xx7xAA, MPL-B230P-xx7xAA | | |
| MPL-B310P-xx7xAA, MPL-B320P-xx7xAA, MPL-B330P-xx7xAA | | |
| MPL-B420P-xx7xAA, MPL-B430P-xx7xAA | | |
| MPL-B4530F-xx7xAA, MPL-B4530K-xx7xAA, MPL-B4540F-xx7xAA, MPL-B4560F-xx7xAA | | |
| MPL-B520K-xx7xAA | 2090-CPxM7DF-14AAxx (standard, non-flex) 2090-CPxM7DF-14AFxx (continuous-flex) | 2090-XXNFMF-Sxx (standard, non-flex) ⁽⁴⁾ 2090-CFBM7DF-CDAFxx (continuous-flex) Incremental Feedback |
| MPL-B540D-xx7xAA, MPL-B540K-xx7xAA, MPL-B560F-xx7xAA | | |
| MPL-B580F-xx7xAA, MPL-B580J-xx7xAA, MPL-B640F-xx7xAA | 2090-CPxM7DF-10AAxx (standard, non-flex) 2090-CPxM7DF-10AFxx (continuous-flex) | 2090-XXNFMF-Sxx (standard, non-flex) ⁽⁴⁾ 2090-CFBM7DF-CDAFxx (continuous-flex) Incremental Feedback |
| MPL-B660F-xx7xAA, MPL-B680D-xx7xAA, MPL-B960B-xx7xAA, MPL-B980B-xx7xAA | 2090-CPxM7DF-08AAxx (standard, non-flex) 2090-CPxM7DF-08AFxx (continuous-flex) | |
| MPL-B680F-xx7xAA, MPL-B860D-xx7xAA, MPL-B880C-xx7xAA, | 2090-CPBM7DF-06AAxx (standard, non-flex) | |
| MPL-B880D-xx7xAA, MPL-B960C-xx7xAA, MPL-B980C-xx7xAA, | 2090-CPBM7DF-04AAxx (standard, non-flex) | |
| | | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) with flying-lead cables on the drive end. Refer to Required Drive Accessories on [page 4](#).

(2) Applies to Ultra3000 drives and MPL-B3xxx-M/S...MPL-B9xxx-M/S motors with absolute high-resolution feedback.

(3) Applies to Ultra3000/5000 drives and MPL-B15xxx-V/E...MPL-B2xxx-V/E motors with absolute high-resolution feedback.

(4) Applies to Ultra3000 drives and MPL-B15xxx-H...MPL-B45xxx-H motors with incremental feedback.

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin MPL Motor Performance Specifications with Ultra3000 (400V class) Drives

| Rotary Motor | Speed, max rpm | System Continuous Stall Current A (0-pk) | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A (0-pk) | System Peak Stall Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 400V-class Drives |
|--------------|----------------|------------------------------------------|--------------------------------------------|------------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPL-B1510V | 8000 | 0.95 | 0.26 (2.3) | 3.10 | 0.77 (6.80) | 0.16 | 2098-DSD-HV030 |
| MPL-B1520U | 7000 | 1.80 | 0.49 (4.3) | 6.10 | 1.58 (13.9) | 0.27 | 2098-DSD-HV030 |
| MPL-B1530U | 7000 | 2.0 | 0.90 (8.0) | 7.20 | 2.82 (24.9) | 0.39 | 2098-DSD-HV030 |

Bulletin MPL Motor Performance Specifications with Ultra3000 (400V class) Drives (continued)

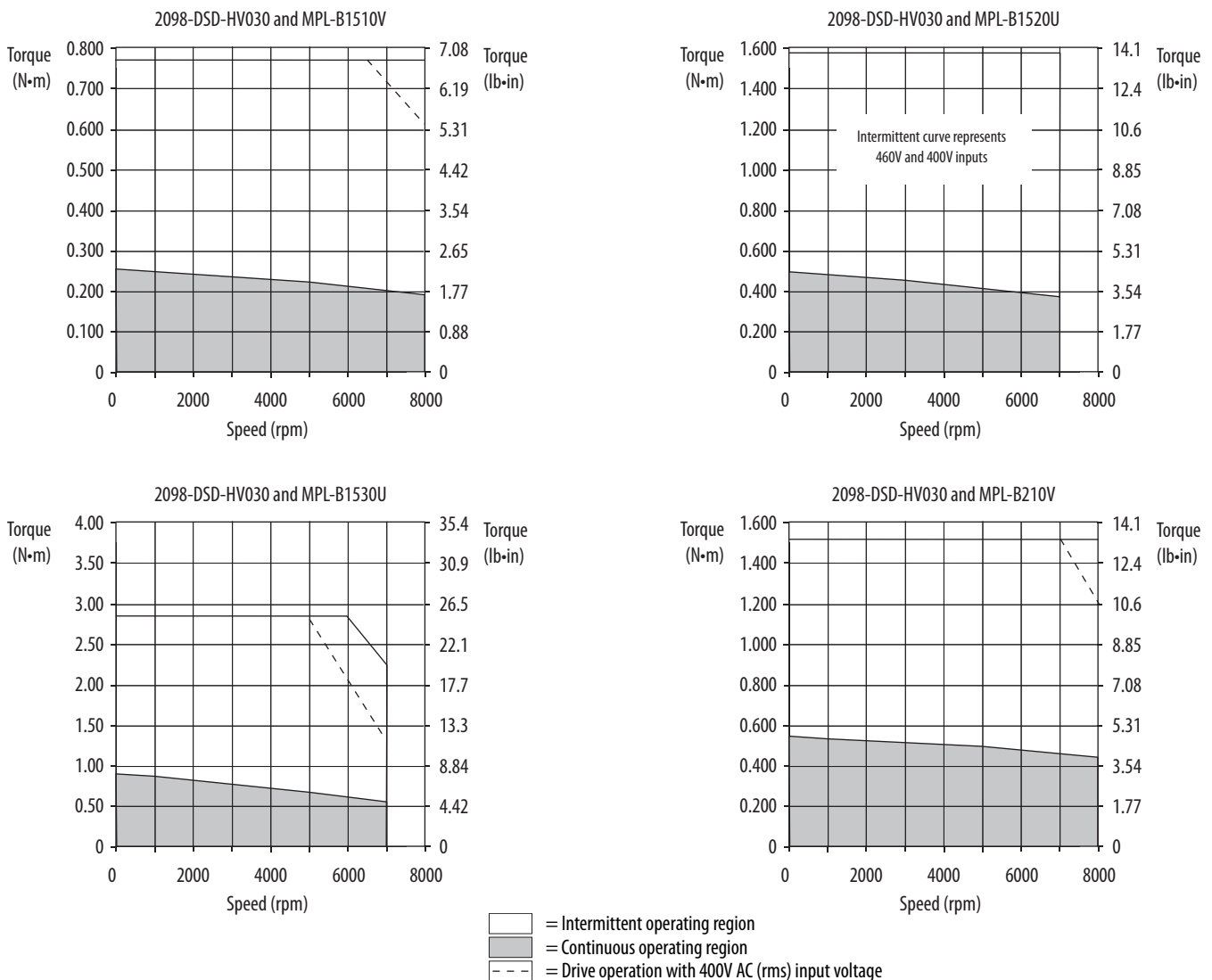
| Rotary Motor | Speed, max rpm | System Continuous Stall Current A (0-pk) | System Continuous Stall Torque N·m (lb-in) | System Peak Stall Current A (0-pk) | System Peak Stall Torque N·m (lb-in) | Motor Rated Output kW | Ultra3000 400V-class Drives |
|--------------|-------------------|------------------------------------------------|--------------------------------------------------|------------------------------------------|--------------------------------------------|-----------------------------|--------------------------------|
| MPL-B210V | 8000 | 1.75 | 0.55 (4.8) | 5.80 | 1.52 (13.5) | 0.37 | 2098-DSD-HV030 |
| MPL-B220T | 6000 | 3.30 | 1.61 (14.2) | 11.3 | 4.74 (41.9) | 0.62 | 2098-DSD-HV030 |
| MPL-B230P | 5000 | 2.60 | 2.10 (18.6) | 11.3 | 8.20 (73.0) | 0.86 | 2098-DSD-HV030 |
| MPL-B310P | 5000 | 2.4 | 1.58 (14) | 7.1 | 3.61 (32) | 0.77 | 2098-DSD-HV030 |
| MPL-B320P | 5000 | 4.5 | 2.94 (26) | 13.0 | 7.91 (70) | 1.5 | 2098-DSD-HV030 |
| MPL-B330P | 5000 | 6.1 | 4.18 (37) | 14.0 | 8.59 (76) | 1.8 | 2098-DSD-HV030 |
| | | | | 17.0 | 11.1 (98) | | 2098-DSD-HV050 |
| MPL-B420P | 5000 | 6.4 | 4.74 (42) | 14.0 | 8.59 (76) | 1.9 | 2098-DSD-HV030 |
| | | | | 22.0 | 12.9 (114) | | 2098-DSD-HV050 |
| | | | | 23.0 | 13.5 (120) | | 2098-DSD-HV100 |
| MPL-B430P | 5000 | 9.2 | 6.55 (58) | 22.0 | 12.9 (114) | 2.2 | 2098-DSD-HV050 |
| | | | | 31.0 | 19.8 (175) | | 2098-DSD-HV100 |
| MPL-B4530F | 3000 | 7.0 | 8.25 (73) | 14.0 | 13.5 (120) | 2.1 | 2098-DSD-HV030 |
| | | 7.1 | 8.36 (74) | 21.0 | 20.3 (180) | | 2098-DSD-HV050 |
| MPL-B4530K | 4000 | 11.0 | 8.36 (74) | 22.0 | 14.5 (128) | 2.6 | 2098-DSD-HV050 |
| | | | | 31.0 | 20.3 (180) | | 2098-DSD-HV100 |
| MPL-B4540F | 3000 | 9.1 | 10.2 (90) | 22.0 | 22.0 (195) | 2.6 | 2098-DSD-HV050 |
| | | | | 26.0 | 27.1 (240) | | 2098-DSD-HV100 |
| MPL-B4560F | 3000 | 11.0 | 13.1 (116) | 22.0 | 21.0 (186) | 3.2 | 2098-DSD-HV050 |
| | | 11.8 | 14.1 (125) | 36.0 | 34.4 (305) | | 2098-DSD-HV100 |
| MPL-B520K | 4000 | 11.0 | 10.3 (91) | 22.0 | 15.8 (140) | 3.5 | 2098-DSD-HV050 |
| | | 11.5 | 10.7 (95) | 33.0 | 23.2 (205) | | 2098-DSD-HV100 |
| MPL-B540D | 2000 | 10.5 | 19.4 (172) | 22.0 | 39.2 (346) | 3.4 | 2098-DSD-HV050 |
| | | | | 23.0 | 41.0 (362) | | 2098-DSD-HV100 |
| MPL-B540K | 4000 | 20.5 | 19.4 (172) | 46.0 | 33.9 (300) | 5.4 | 2098-DSD-HV100 |
| | | | | 60.0 | 45.2 (400) | | 2098-DSD-HV150 |
| MPL-B560F | 3000 | 20.6 | 26.8 (237) | 46.0 | 50.4 (446) | 5.5 | 2098-DSD-HV100 |
| | | | | 68.0 | 67.8 (600) | | 2098-DSD-HV150 |
| MPL-B580F | 3000 | 26.0 | 34.0 (301) | 68.0 | 70.5 (623) | 7.1 | 2098-DSD-HV150 |
| | | | | 94.0 | 87.0 (769) | | 2098-DSD-HV220 |
| MPL-B580J | 3800 | 32.0 | 34.0 (301) | 68.0 | 62.4 (552) | 7.9 | 2098-DSD-HV150 |
| | | | | 94.0 | 81.0 (717) | | 2098-DSD-HV220 |
| MPL-B640F | 3000 | 32.1 | 36.7 (325) | 65.0 | 72.3 (640) | 6.1 | 2098-DSD-HV220 |
| MPL-B660F | 3000 | 34.0 | 40.7 (360) | 68.0 | 73.4 (650) | 6.1 | 2098-DSD-HV150 |
| | | 38.5 | 48.0 (425) | 94.0 | 96.0 (850) | | 2098-DSD-HV220 |
| MPL-B680D | 2000 | 34.0 | 62.8 (556) | 94.0 | 154.2 (1365) | 9.3 | 2098-DSD-HV220 |
| MPL-B680F | 3000 | 48.0 | 58.2 (515) | 94.0 | 101.7 (900) | 7.5 | 2098-DSD-HV220 |
| MPL-B860D | 2000 | 47.5 | 83.1 (735) | 94.0 | 151 (1335) | 12.5 | 2098-DSD-HV220 |
| MPL-B880C | 1500 | 47.5 | 109.9 (973) | 94.0 | 197 (1742) | 12.6 | 2098-DSD-HV220 |

Bulletin MPL Motor Performance Specifications with Ultra3000 (400V class) Drives (continued)

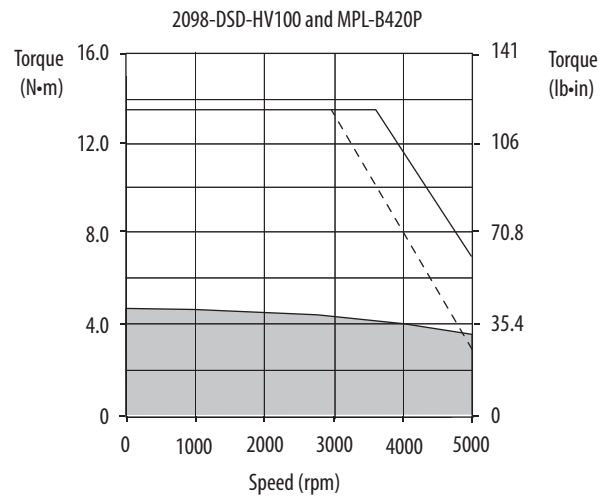
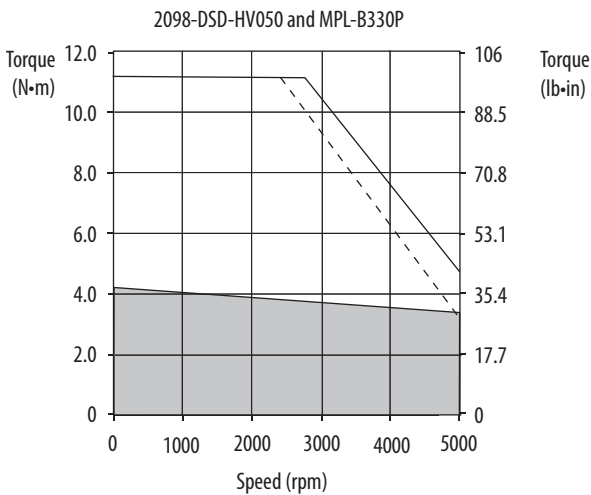
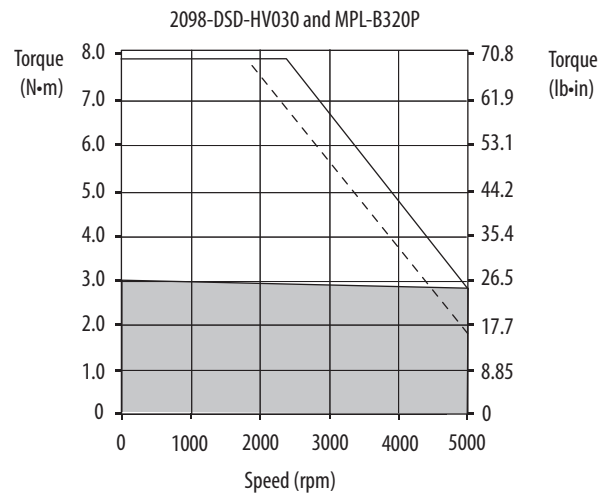
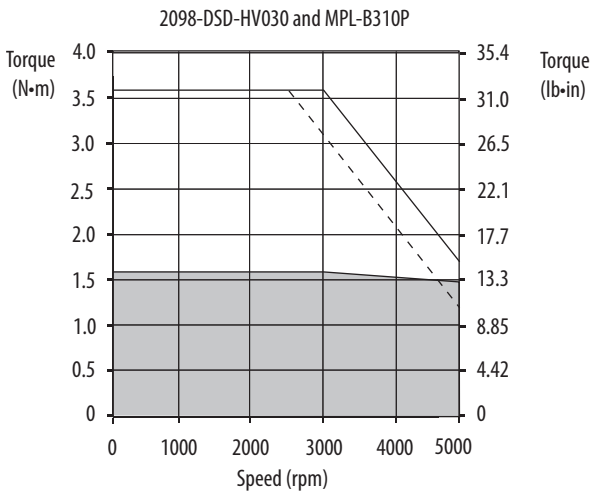
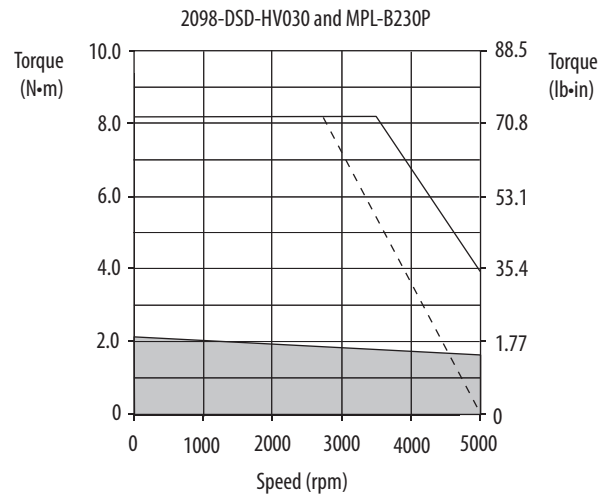
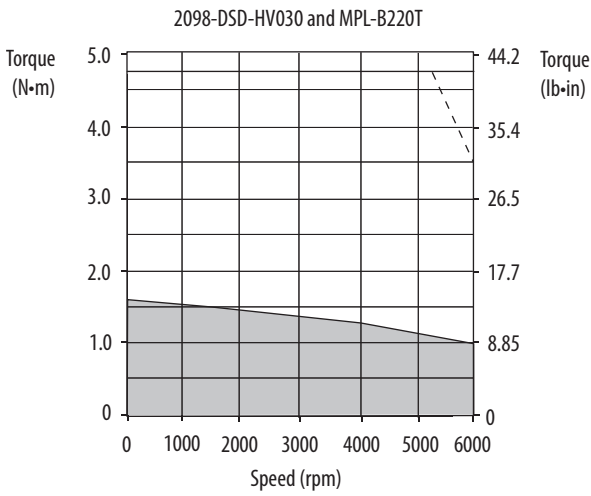
| Rotary Motor | Speed, max rpm | System Continuous Stall Current A (0-pk) | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A (0-pk) | System Peak Stall Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 400V-class Drives |
|--------------|----------------|------------------------------------------|--------------------------------------------|------------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPL-B880D | 2000 | 47.0 | 77.4 (685) | 94.0 | 144 (1275) | 12.6 | 2098-DSD-HV220 |
| MPL-B960B | 1200 | 42.5 | 130 (1150) | 94.0 | 231 (2050) | 12.7 | 2098-DSD-HV220 |
| MPL-B960C | 1500 | 41.5 | 112 (990) | 94.0 | 181 (1600) | 14.8 | 2098-DSD-HV220 |
| MPL-B980B | 1000 | 40.0 | 163 (1440) | 94.0 | 278 (2460) | 15.2 | 2098-DSD-HV220 |
| MPL-B980C | 1500 | 47.5 | 118.6 (1050) | 94.0 | 213 (1890) | 16.8 | 2098-DSD-HV220 |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (400V class) Drives/MP-Series Low Inertia Motor Curves

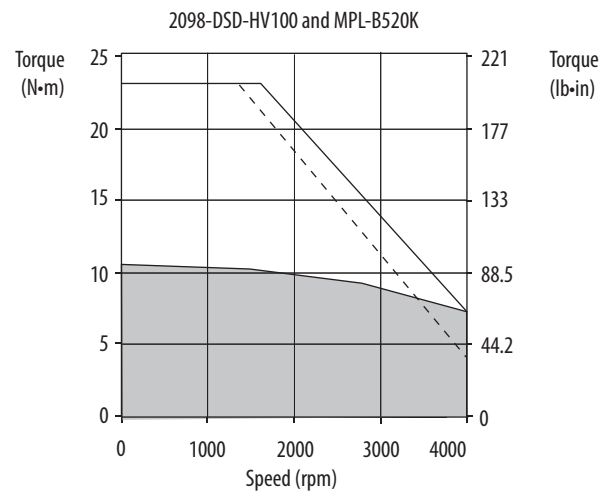
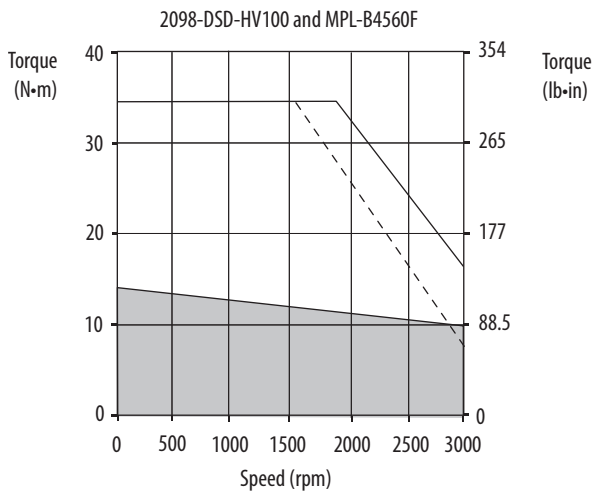
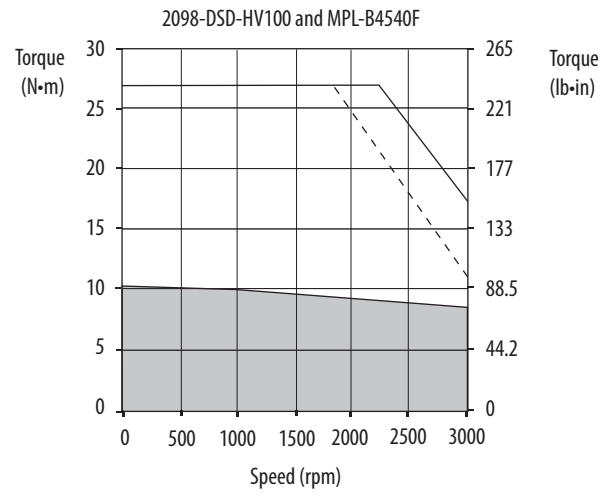
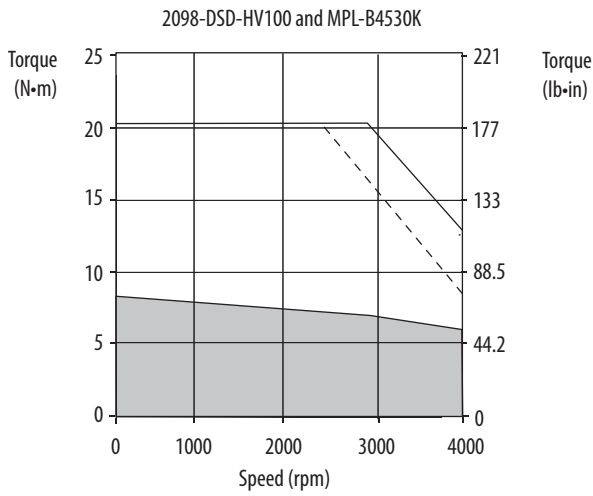
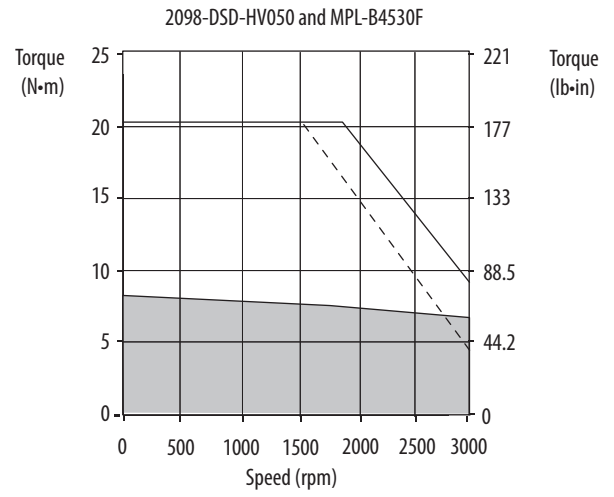
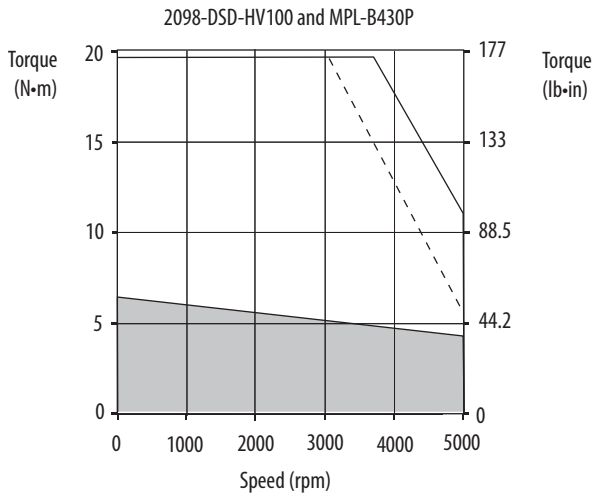


Ultra3000 (400V class) Drives/MP-Series Low Inertia Motors (continued)



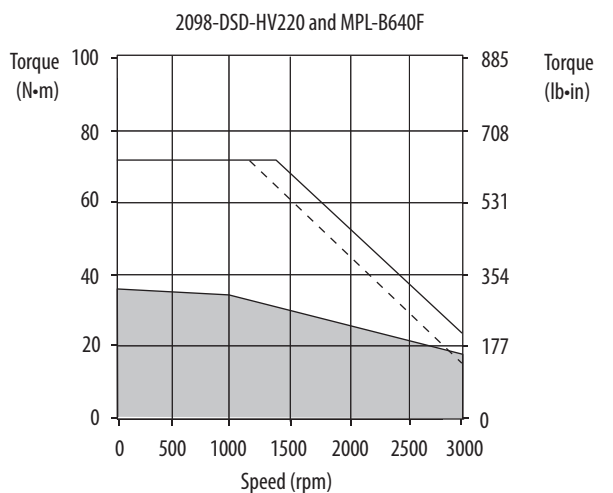
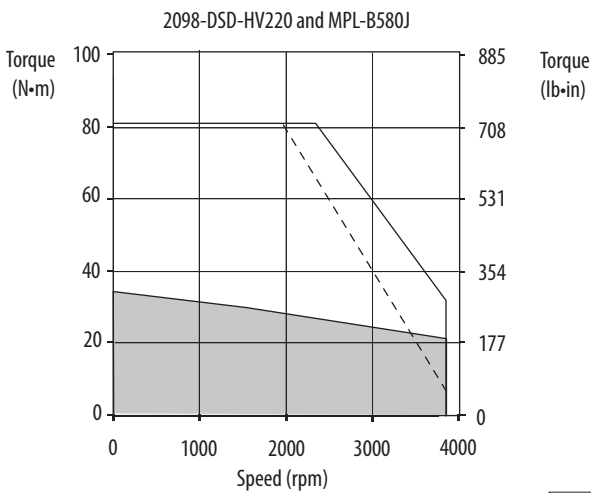
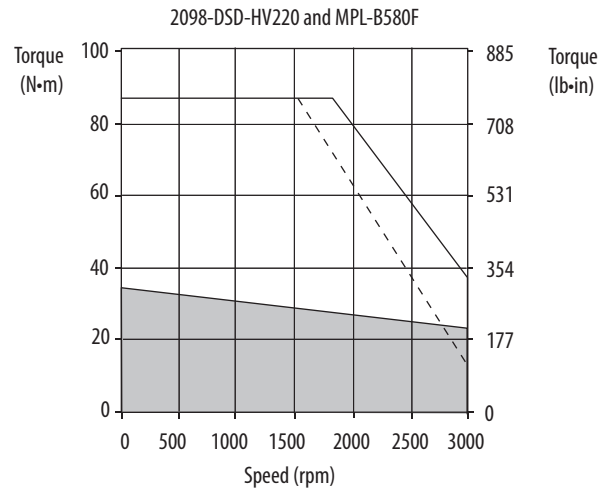
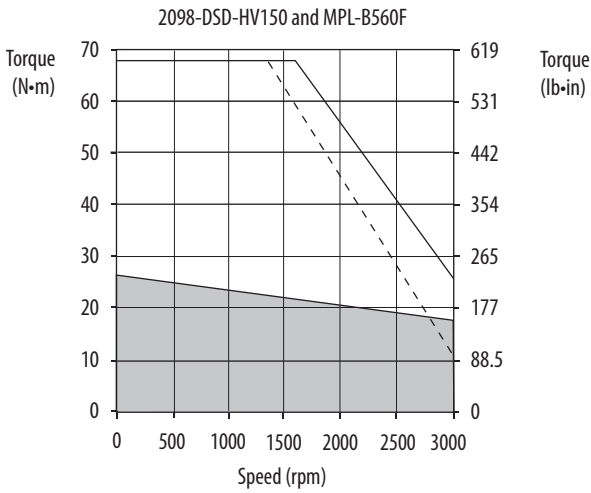
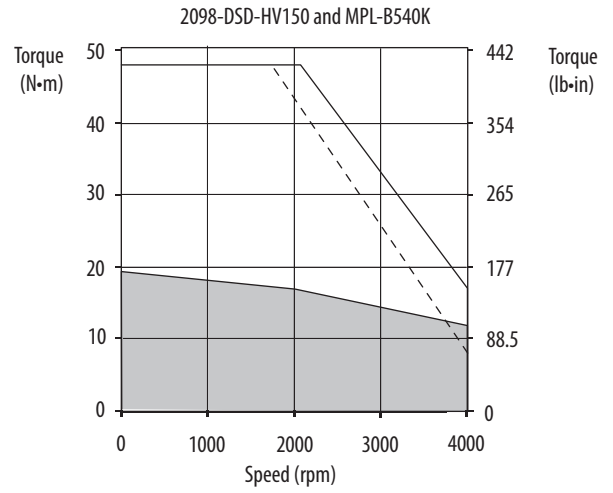
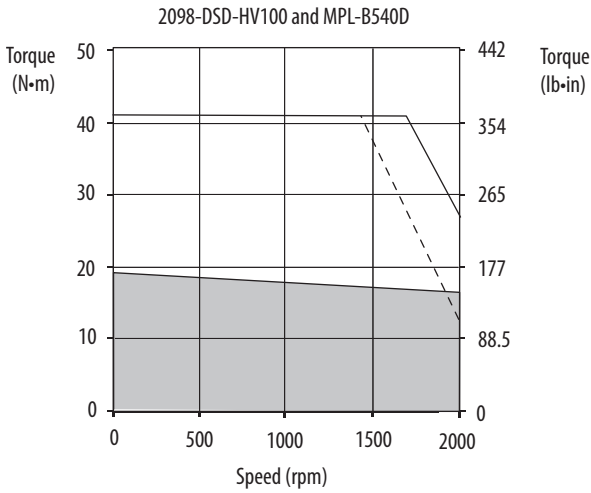
- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Low Inertia Motors (continued)



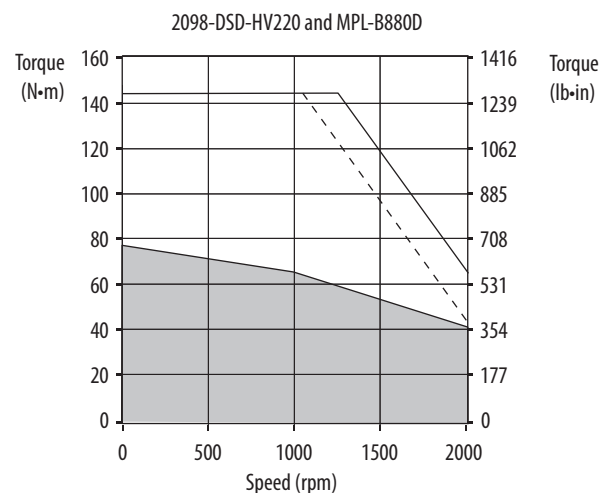
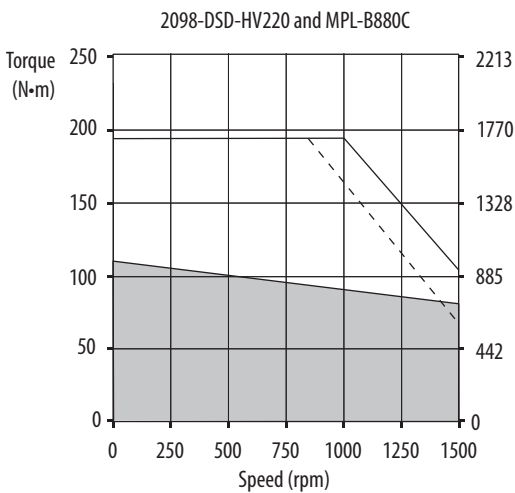
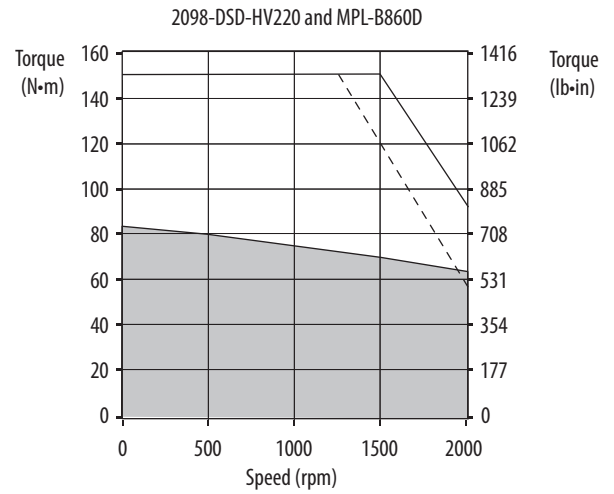
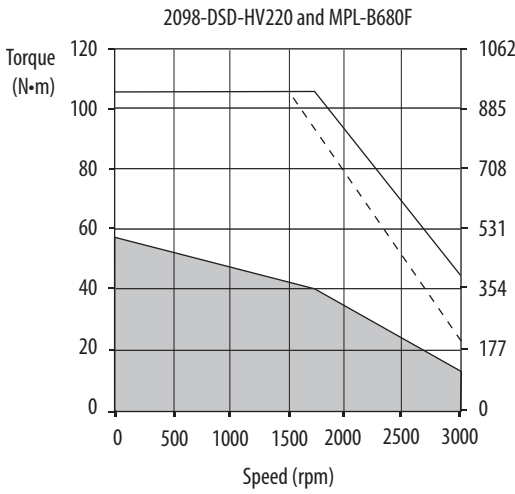
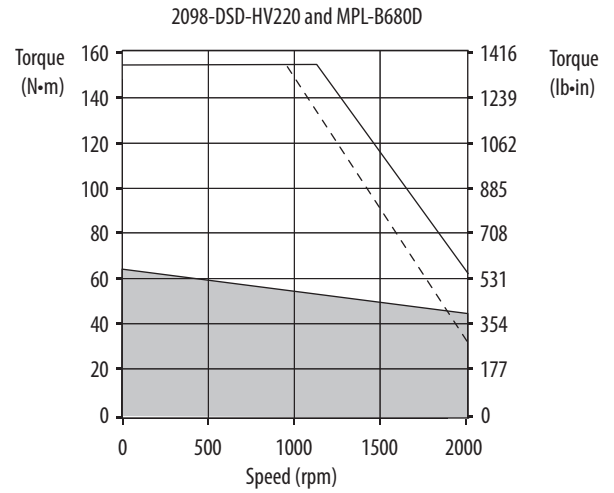
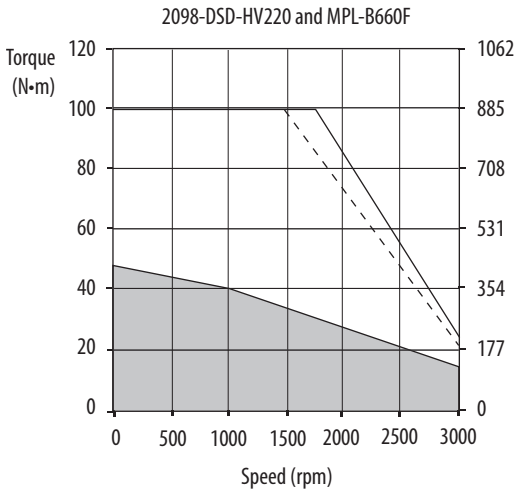
= Intermittent operating region
 = Continuous operating region
 = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Low Inertia Motors (continued)



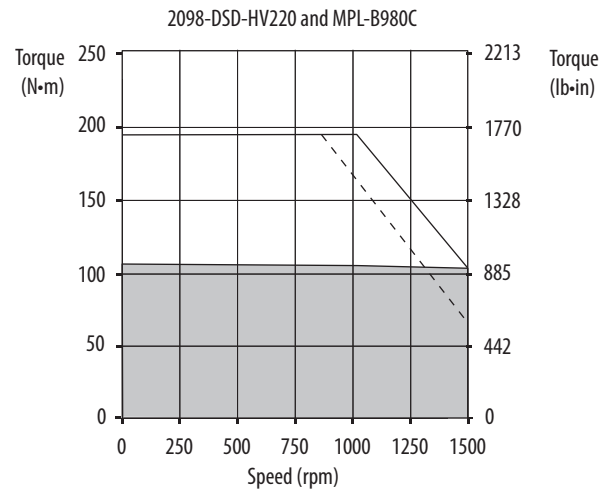
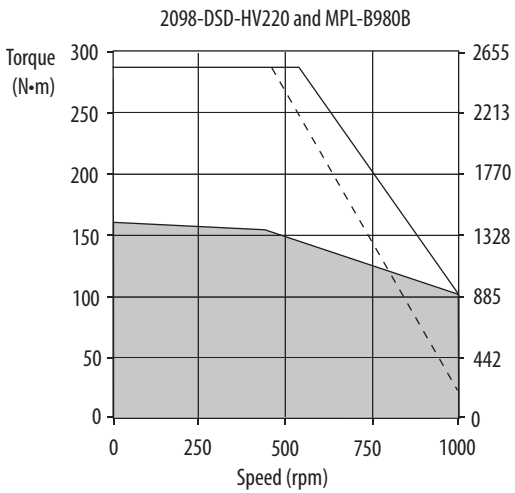
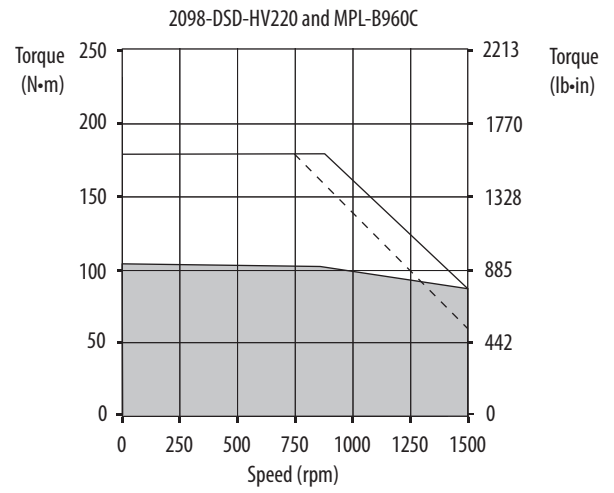
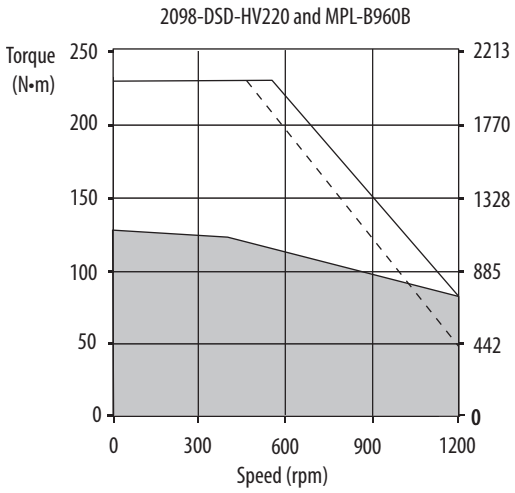
- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Low Inertia Motors (continued)



- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Low Inertia Motors (continued)



- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (200V class) Drives with MP-Series Medium Inertia Motors

This section provides system combination information for the Ultra3000 (200V class) drives when matched with MP-Series medium-inertia motors. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

Bulletin MPM Motor Cable Combinations

| Motor Cat. No. (200V class) | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|------------------------------------------------|-----------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MPM-A1151M, MPM-A1152F, MPM-A1153F | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-CFBM7DF-CEAAxx or 2090-CFBM7DD-CEAAxx (standard, non-flex) 2090-CFBM7DF-CEAFxx or 2090-CFBM7DD-CEAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPM-A1302F | 2090-CPxM7DF-14AAxx (standard, non-flex) 2090-CPxM7DF-14AFxx (continuous-flex) | |
| MPM-A1304F | 2090-CPxM7DF-12AAxx (standard, non-flex) | |
| MPM-A1651F | 2090-CPxM7DF-10AAxx (standard, non-flex) 2090-CPxM7DF-10AFxx (continuous-flex) | |
| MPM-A1652F, MPM-A1653F | 2090-CPxM7DF-08AAxx (standard, non-flex) 2090-CPxM7DF-08AFxx (continuous-flex) | |
| MPM-A2152F, MPM-A2153F, MPM-A2154C, MPM-A2154E | 2090-CPBM7DF-06AAxx (standard, non-flex) | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) with flying-lead cables on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

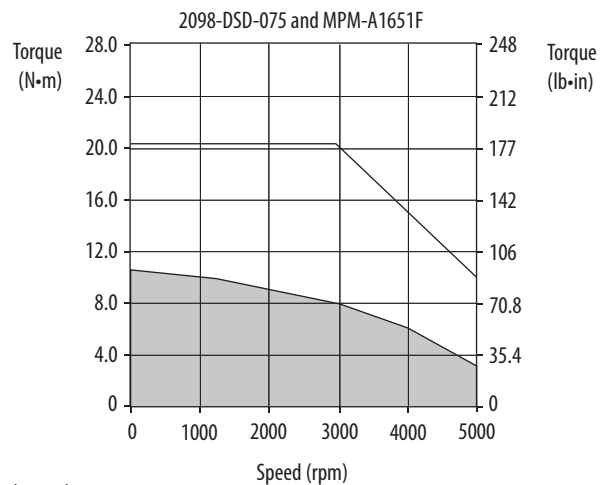
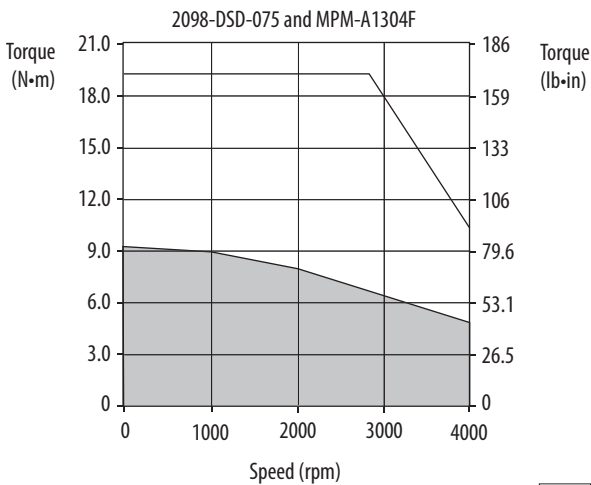
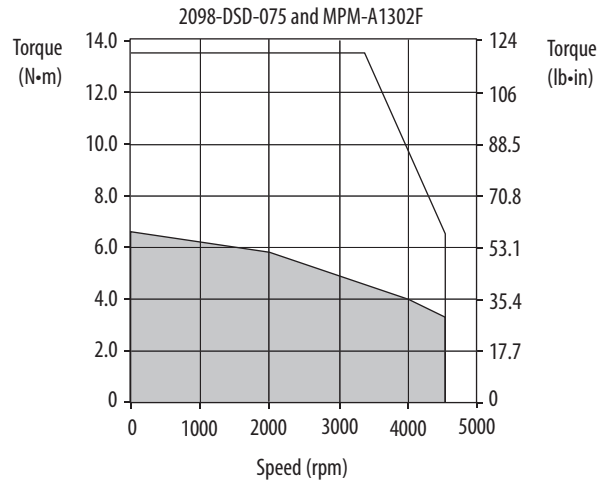
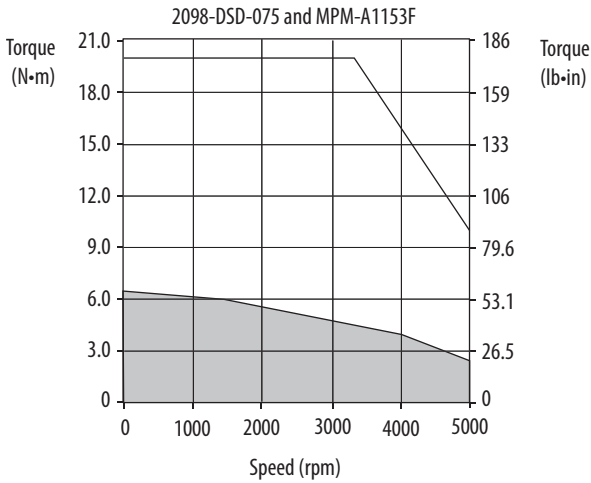
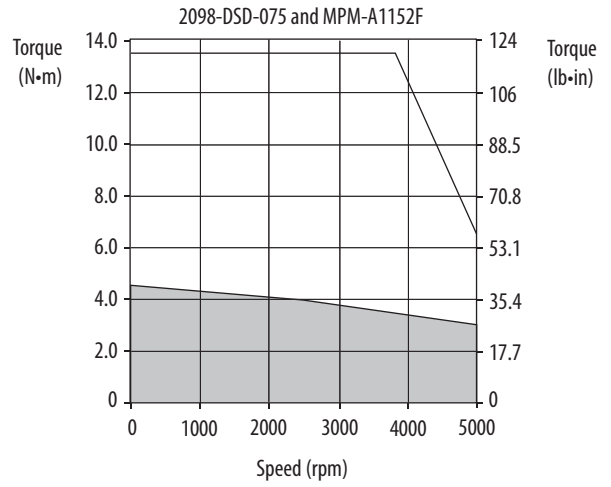
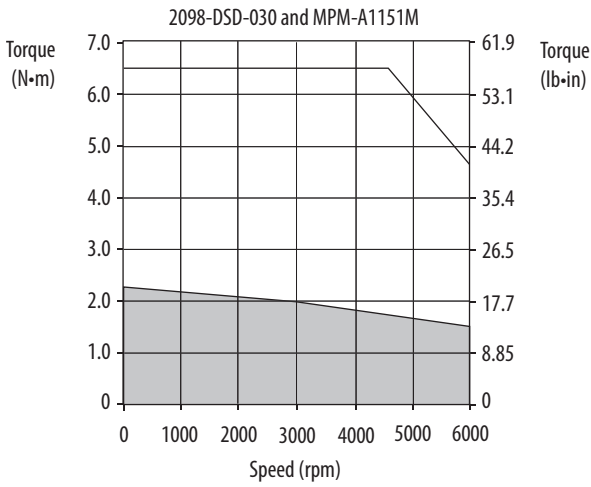
Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin MPM Motor Performance Specifications with Ultra3000 (200V class) Drives

| Rotary Motor | Speed, base rpm | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb-in) | System Peak Stall Current A 0-pk | System Peak Stall Torque N·m (lb-in) | Motor Rated Output kW | Ultra3000 200V-class Drives |
|--------------|-----------------|----------------|----------------------------------------|--------------------------------------------|----------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPM-A1151M | 4500 | 6000 | 10.3 | 2.3 (20.3) | 30.5 | 6.6 (58.4) | 0.90 | 2098-DSD-030 |
| MPM-A1152F | 3000 | 5000 | 14.9 | 4.7 (41.6) | 44.8 | 13.5 (119) | 1.40 | 2098-DSD-075 |
| MPM-A1153F | 3000 | 5000 | 18.6 | 6.5 (57.5) | 64.5 | 19.8 (175) | 1.45 | 2098-DSD-075 |
| MPM-A1302F | 3000 | 4500 | 19.8 | 6.6 (58.4) | 50.2 | 13.5 (119) | 1.65 | 2098-DSD-075 |
| MPM-A1304F | 3000 | 4000 | 22.5 | 9.2 (81.4) | 48.3 | 19.3 (171) | 2.20 | 2098-DSD-075 |
| MPM-A1651F | 3000 | 5000 | 30.96 | 10.7 (94.7) | 75.0 | 20.4 (180) | 2.50 | 2098-DSD-075 |
| MPM-A1652F | 3000 | 4000 | 33.54 | 13.4 (119) | 103.2 | 36.0 (318) | 4.03 | 2098-DSD-150 |
| MPM-A1653F | 3000 | 4000 | 42.4 | 18.6 (165) | 119.1 | 41.9 (371) | 5.10 | 2098-DSD-150 |
| MPM-A2152F | 3000 | 4000 | 59.04 | 26.9 (238) | 125.8 | 56.0 (495) | 5.20 | 2098-DSD-150 |
| MPM-A2153F | 3000 | 3600 | 59.65 | 35.2 (311) | 120.4 | 58.0 (513) | 5.80 | 2098-DSD-150 |
| MPM-A2154C | 1500 | 2000 | 58.68 | 55.5 (491) | 127.3 | 106 (938) | 6.50 | 2098-DSD-150 |
| MPM-A2154E | 2250 | 3000 | 59.67 | 44.0 (389) | 128.2 | 83.9 (742) | 7.00 | 2098-DSD-150 |

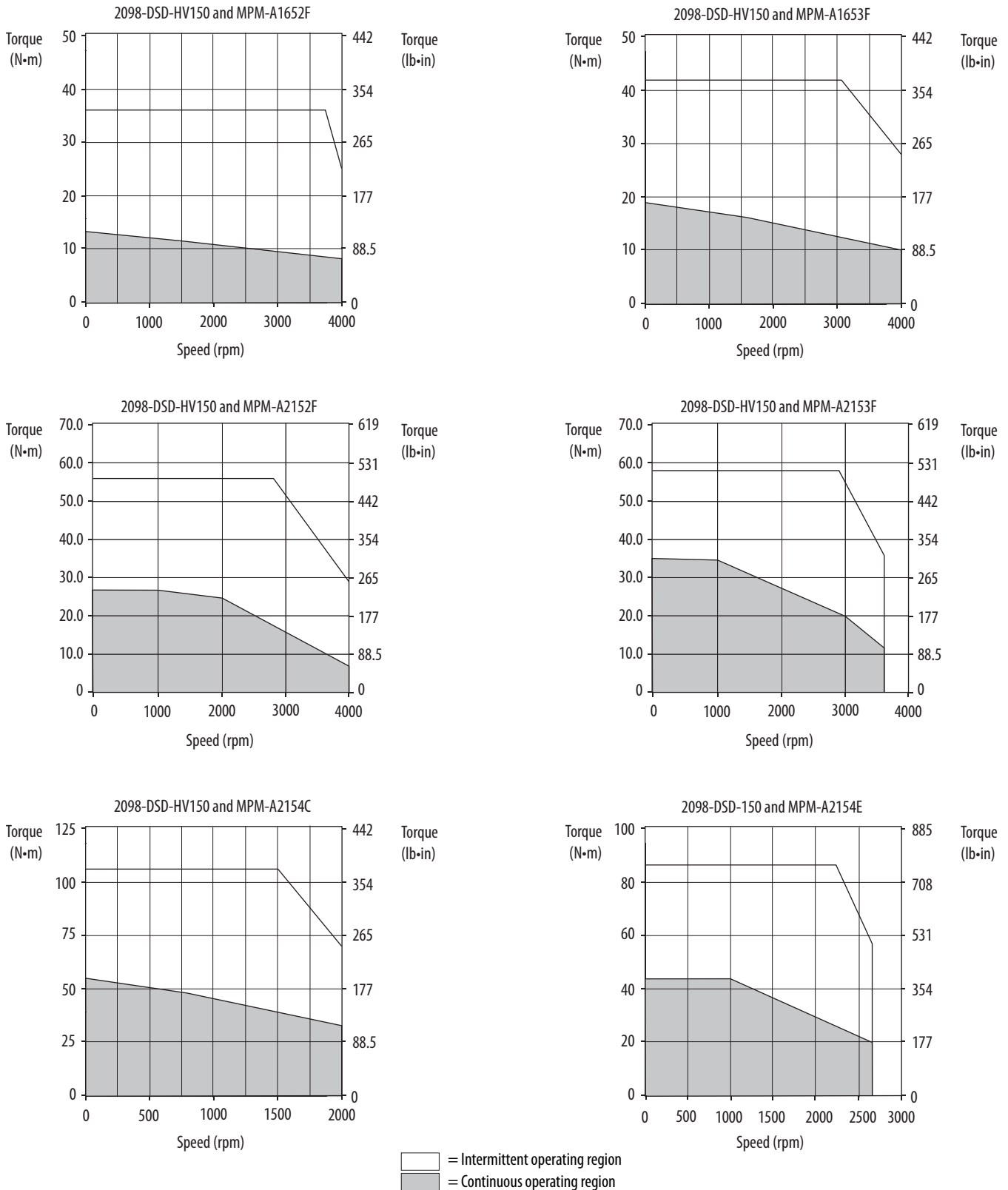
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (200V class) Drives/MP-Series Medium Inertia Motor Curves



= Intermittent operating region
 = Continuous operating region

Ultra3000 (200V class) Drives/MP-Series Medium Inertia Motor Curves (continued)



Ultra3000 (400V class) Drives with MP-Series Medium Inertia Motors

This section provides system combination information for the Ultra3000 (400V class) drives when matched with MP-Series medium-inertia motors. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

Bulletin MPM Motor Cable Combinations

| Motor Cat. No. (400V class) | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|---------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MPM-B1151x, MPM-B1152x, MPM-B1153E, MPM-B1153F | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-CFBM7DF-CEAAxx or 2090-CFBM7DD-CEAAxx (standard, non-flex) 2090-CFBM7DF-CEAFxx or 2090-CFBM7DD-CEAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPM-B1302F, MPM-B1302M, MPM-B1304C, MPM-B1304E | | |
| MPM-B1651C, MPM-B1652C | | |
| MPM-B1153T | 2090-CPxM7DF-14AAxx (standard, non-flex) 2090-CPxM7DF-14AFxx (continuous-flex) | |
| MPM-B1302T, MPM-B1304M | | |
| MPM-B1651F, MPM-B1653C | | |
| MPM-B1651M, MPM-B1652E, MPM-B1652F, MPM-B1653E | 2090-CPxM7DF-10AAxx (standard, non-flex) 2090-CPxM7DF-10AFxx (continuous-flex) | |
| MPM-B2152C, MPM-B2153B | | |
| MPM-B1653F | 2090-CPxM7DF-08AAxx (standard, non-flex) 2090-CPxM7DF-08AFxx (continuous-flex) | |
| MPM-B2152F, MPM-B2152M, MPM-B2153E, MPM-B2153F, MPM-B2154B, MPM-B2154E, MPM-B2154F | | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) with flying-lead cables on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin MPM Motor Performance Specifications with Ultra3000 (400V class) Drives

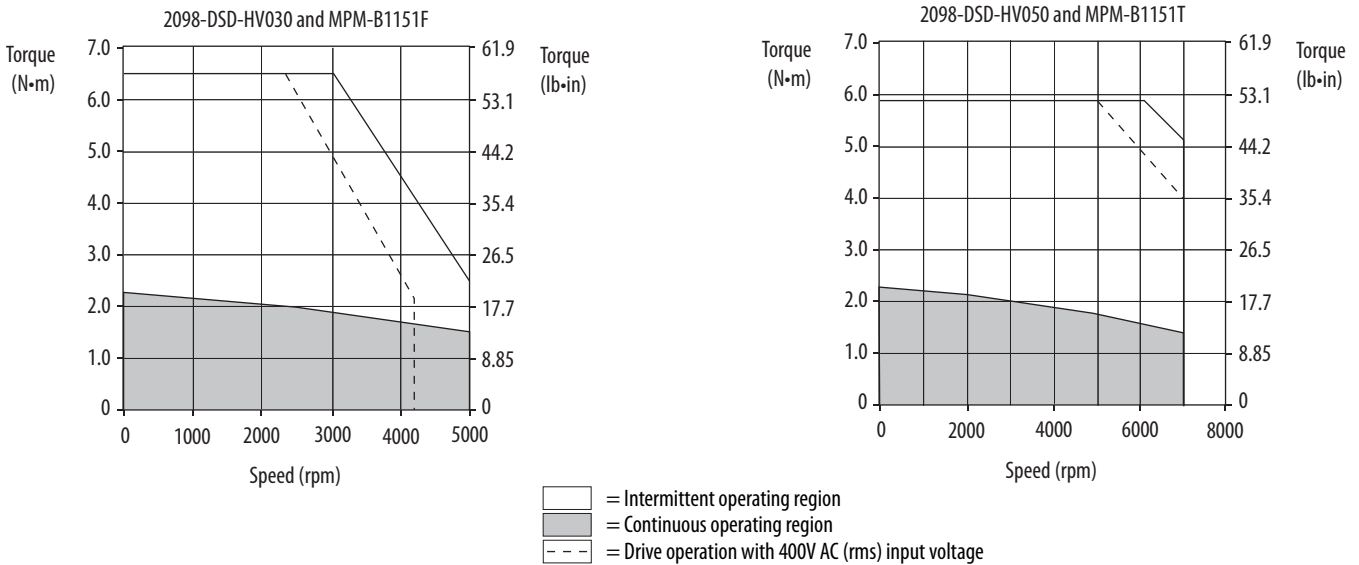
| Rotary Motor | Speed, base rpm | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb-in) | System Peak Stall Current A 0-pk | System Peak Stall Torque N·m (lb-in) | Motor Rated Output kW | Ultra3000 400V-class Drives |
|--------------|-----------------|----------------|----------------------------------------|--------------------------------------------|----------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPM-B1151F | 3000 | 5000 | 2.71 | 2.3 (20.3) | 9.9 | 6.6 (58.4) | 0.75 | 2098-DSD-HV030 |
| MPM-B1151T | 6000 | 7000 | 5.62 | 2.3 (20.3) | 14.0 | 4.4 (38.9) | 0.90 | 2098-DSD-HV030 |
| | | | | | 20.5 | 5.8 (51.3) | | 2098-DSD-HV050 |
| MPM-B1152C | 1500 | 3000 | 3.61 | 5.0 (44.2) | 12.4 | 13.5 (119) | 1.20 | 2098-DSD-HV030 |
| MPM-B1152F | 3000 | 5200 | 6.17 | 5.0 (44.2) | 14.0 | 9.6 (84.9) | 1.40 | 2098-DSD-HV030 |
| | | | | | 21.1 | 13.3 (118) | | 2098-DSD-HV050 |
| MPM-B1152T | 6000 | 7000 | 11.02 | 5.0 (44.2) | 22.0 | 8.6 (76.1) | 1.40 | 2098-DSD-HV050 |
| | | | | | 37.8 | 13.5 (119) | | 2098-DSD-HV100 |
| MPM-B1153E | 2250 | 3500 | 6.21 | 6.5 (57.5) | 14.0 | 13.8 (122) | 1.40 | 2098-DSD-HV030 |
| | | | | | 21.6 | 19.7 (174) | | 2098-DSD-HV050 |
| MPM-B1153F | 3000 | 5500 | 9.20 | 6.4 (56.6) | 22.0 | 14.6 (129) | 1.40 | 2098-DSD-HV050 |
| | | | | | 32.0 | 19.7 (174) | | 2098-DSD-HV100 |
| MPM-B1153T | 6000 | 7000 | 15.95 | 6.4 (56.6) | 46.0 | 14.8 (131) | 1.45 | 2098-DSD-HV100 |
| | | | | | 55.4 | 16.5 (146) | | 2098-DSD-HV150 |
| MPM-B1302F | 3000 | 4500 | 8.57 | 6.6 (58.4) | 22.0 | 13.2 (117) | 1.65 | 2098-DSD-HV050 |
| MPM-B1302M | 4500 | 6000 | 12.57 | 6.6 (58.4) | 32.4 | 13.3 (118) | 1.65 | 2098-DSD-HV100 |
| MPM-B1302T | 6000 | 7000 | 16.83 | 6.7 (59.3) | 43.4 | 13.3 (118) | 1.65 | 2098-DSD-HV100 |
| MPM-B1304C | 1500 | 2750 | 7.00 | 10.3 (91.1) | 14.0 | 18.7 (165) | 2.00 | 2098-DSD-HV030 |
| | | | | | 22.0 | 26.8 (237) | | 2098-DSD-HV050 |
| MPM-B1304E | 2250 | 4000 | 10.75 | 10.2 (90.3) | 22.0 | 19.1 (169) | 2.20 | 2098-DSD-HV050 |
| | | | | | 34.2 | 27.1 (240) | | 2098-DSD-HV100 |
| MPM-B1304M | 4500 | 6000 | 19.02 | 10.4 (92.0) | 46.0 | 21.9 (194) | 2.20 | 2098-DSD-HV100 |
| | | | | | 60.6 | 27.1 (240) | | 2098-DSD-HV150 |
| MPM-B1651C | 1500 | 3500 | 10.21 | 11.4 (101) | 22.0 | 19.5 (172) | 2.50 | 2098-DSD-HV050 |
| | | | | | 29.2 | 23.2 (205) | | 2098-DSD-HV100 |
| MPM-B1651F | 3000 | 5000 | 17.75 | 11.4 (101) | 46.0 | 21.8 (193) | 2.50 | 2098-DSD-HV100 |
| | | | | | 50.9 | 23.2 (205) | | 2098-DSD-HV150 |
| MPM-B1651M | 4500 | 5000 | 22.46 | 11.3 (100) | 46.0 | 18.5 (164) | 2.50 | 2098-DSD-HV100 |
| | | | | | 56.8 | 21.4 (189) | | 2098-DSD-HV150 |
| MPM-B1652C | 1500 | 2500 | 11.51 | 16.4 (145) | 22.0 | 30.0 (265) | 3.80 | 2098-DSD-HV050 |
| | | | | | 33.6 | 40.2 (356) | | 2098-DSD-HV100 |
| MPM-B1652E | 2250 | 3500 | 20.94 | 21.1 (187) | 46.0 | 39.1 (346) | 4.30 | 2098-DSD-HV100 |
| | | | | | 60.5 | 48.0 (425) | | 2098-DSD-HV150 |
| MPM-B1652F | 3000 | 4500 | 28.74 | 21.1 (187) | 68.0 | 39.1 (346) | 4.30 | 2098-DSD-HV150 |
| | | | | | 84.1 | 45.0 (398) | | 2098-DSD-HV220 |
| MPM-B1653C | 1500 | 2500 | 20.05 | 26.7 (236) | 46.0 | 56.1 (496) | 4.60 | 2098-DSD-HV100 |
| | | | | | 59.2 | 67.7 (599) | | 2098-DSD-HV150 |

Bulletin MPM Motor Performance Specifications with Ultra3000 (400V class) Drives (continued)

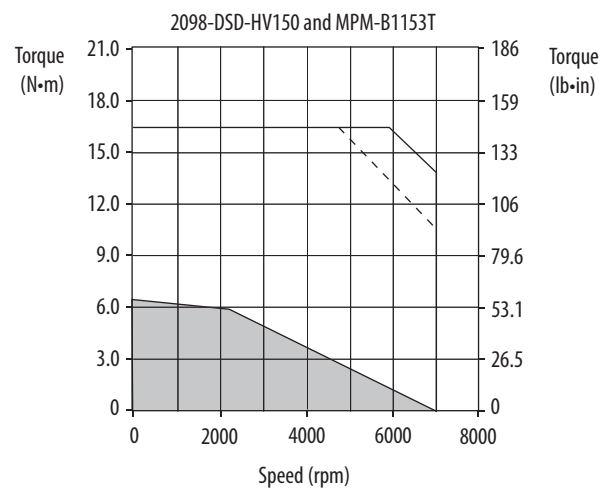
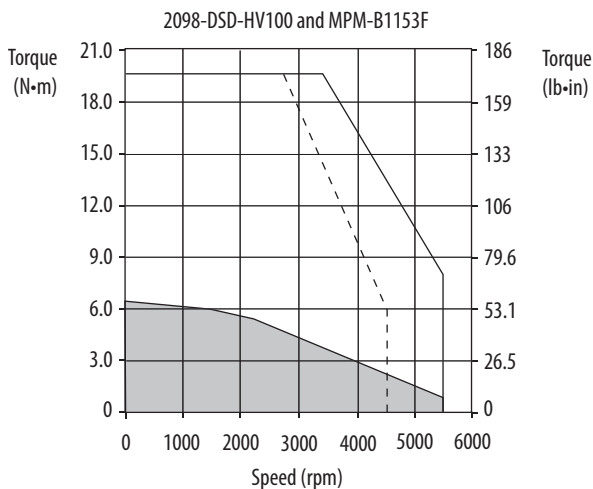
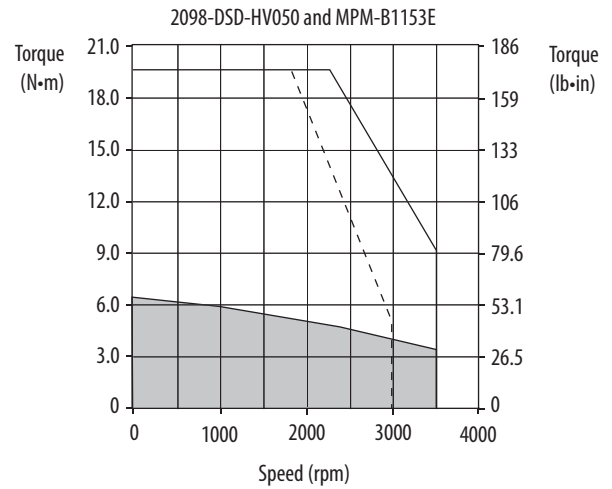
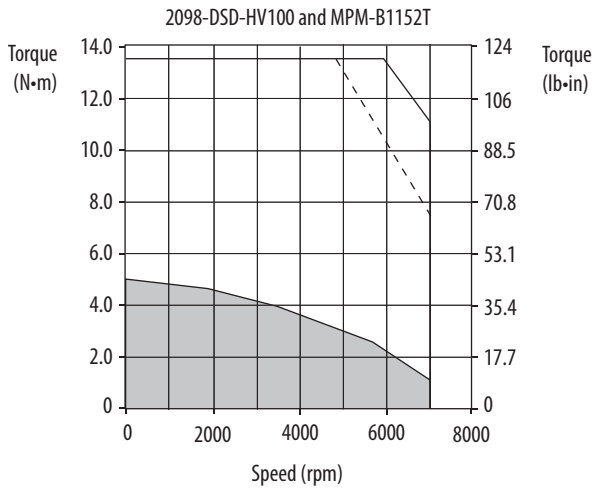
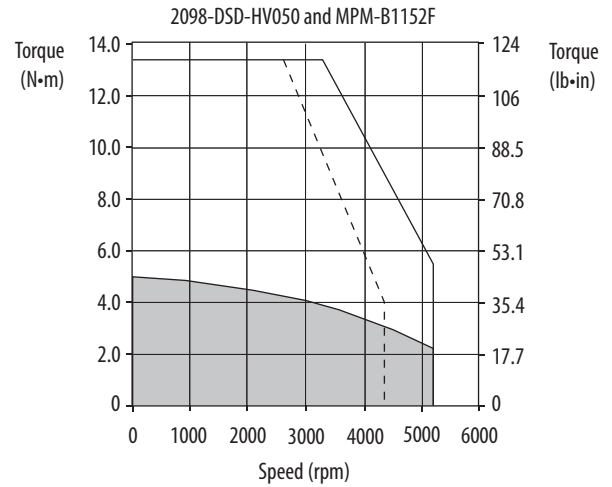
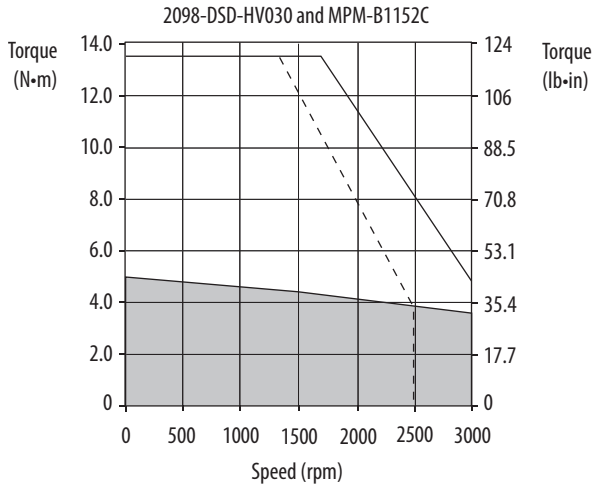
| Rotary Motor | Speed, base rpm | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A 0-pk | System Peak Stall Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 400V-class Drives |
|--------------|-----------------|----------------|----------------------------------------|--------------------------------------------|----------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPM-B1653E | 2250 | 3500 | 27.00 | 26.8 (237) | 68.0 | 58.8 (520) | 5.10 | 2098-DSD-HV150 |
| | | | | | 72.9 | 62.0 (549) | | 2098-DSD-HV220 |
| MPM-B1653F | 3000 | 4000 | 34.94 | 31.0 (274) | 94.0 | 56.1 (496) | 5.10 | 2098-DSD-HV220 |
| MPM-B2152C | 1500 | 2500 | 27.40 | 36.7 (325) | 55.4 | 72.2 (639) | 5.60 | 2098-DSD-HV150 |
| MPM-B2152F | 3000 | 4500 | 43.54 | 33.9 (300) | 94.0 | 69.8 (618) | 5.90 | 2098-DSD-HV220 |
| MPM-B2152M | 4500 | 5000 | 44.58 | 34.1 (302) | 94.0 | 52.9 (468) | 5.90 | 2098-DSD-HV220 |
| MPM-B2153B | 1250 | 2000 | 24.06 | 47.1 (417) | 46.0 | 81.5 (721) | 6.80 | 2098-DSD-HV100 |
| | | | | 48.0 (425) | 60.0 | 101.2 (895) | | 2098-DSD-HV150 |
| MPM-B2153E | 2250 | 3000 | 39.63 | 47.9 (424) | 94.0 | 97.1 (859) | 7.20 | 2098-DSD-HV220 |
| MPM-B2153F | 3000 | 3800 | 43.86 | 45.6 (403) | 94.0 | 94.8 (839) | 7.20 | 2098-DSD-HV220 |
| MPM-B2154B | 1250 | 2000 | 35.46 | 62.7 (555) | 94.0 | 149 (1319) | 6.90 | 2098-DSD-HV220 |
| MPM-B2154E | 2250 | 3000 | 43.68 | 55.9 (495) | 94.0 | 108 (956) | 7.50 | 2098-DSD-HV220 |
| MPM-B2154F | 3000 | 3300 | 44.40 | 56.2 (497) | 83.6 | 87.9 (778) | 7.50 | 2098-DSD-HV220 |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (400V class) Drives/MP-Series Medium Inertia Motor Curves

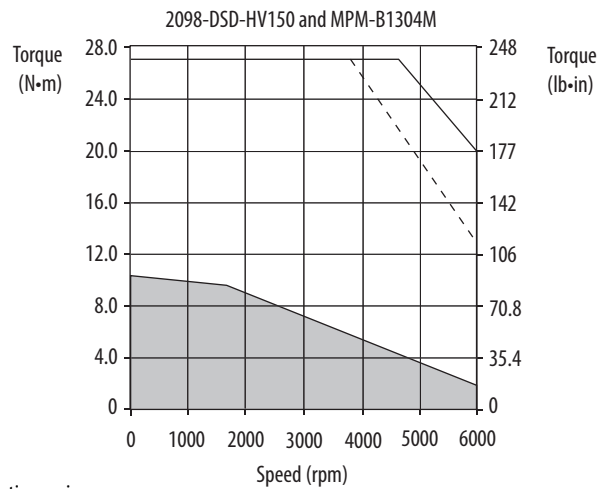
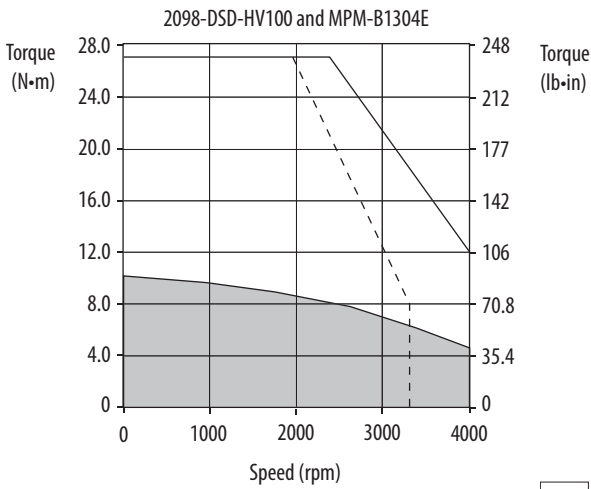
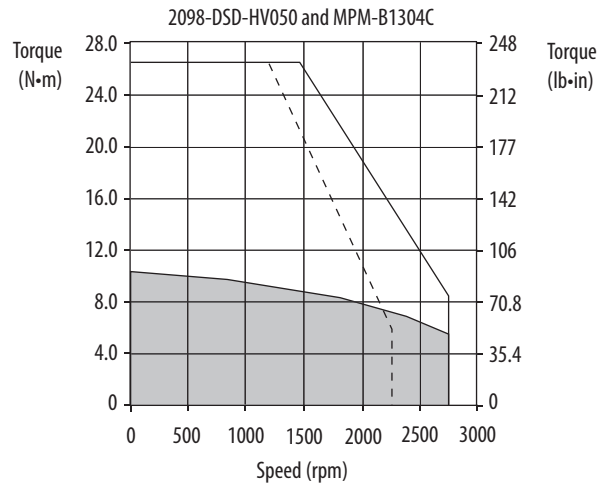
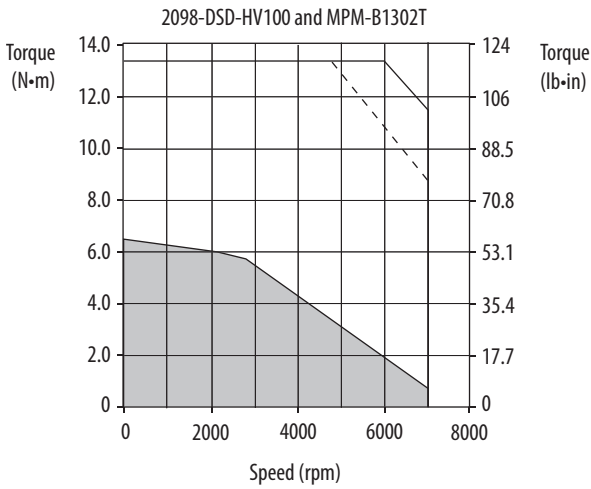
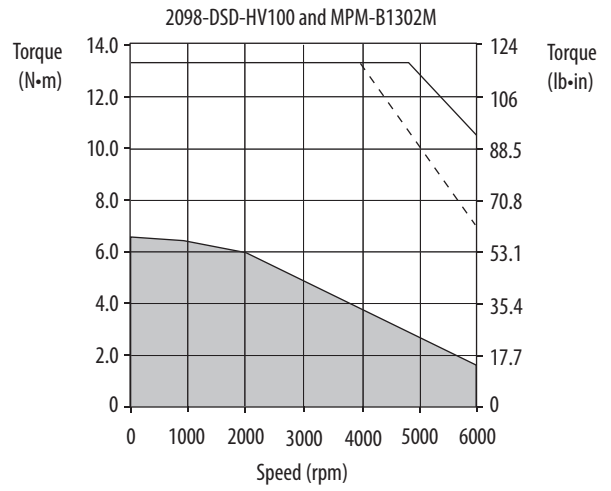
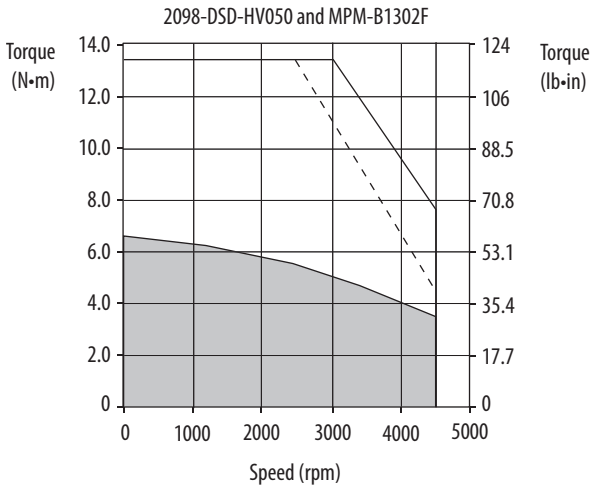


Ultra3000 (400V class) Drives/MP-Series Medium Inertia Motor Curves (continued)



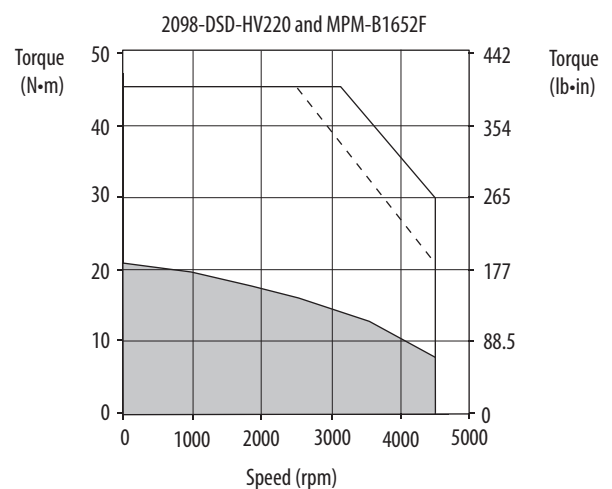
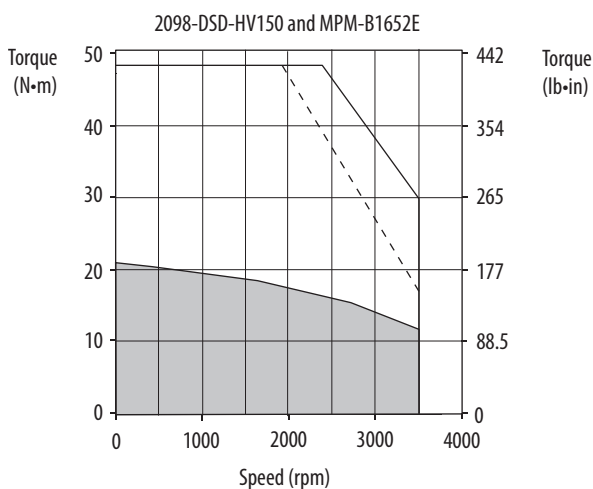
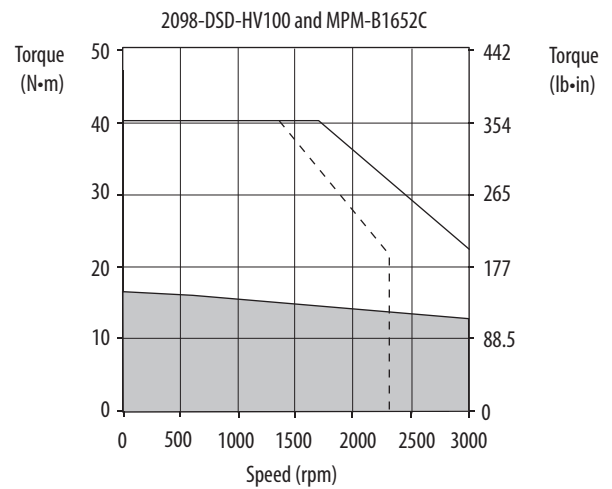
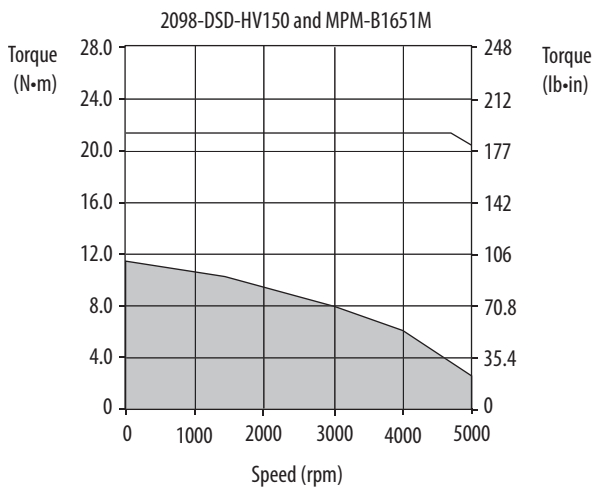
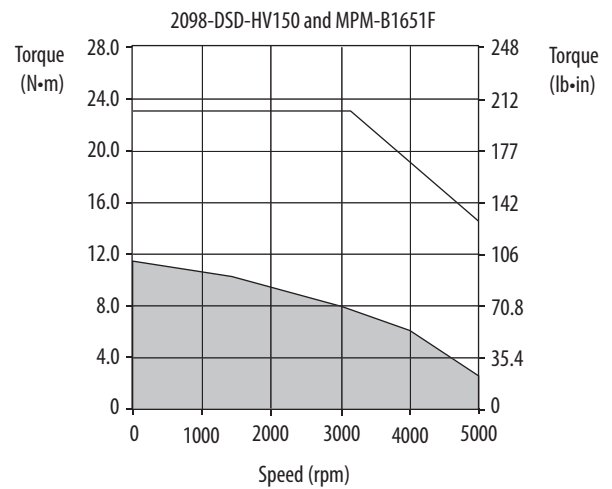
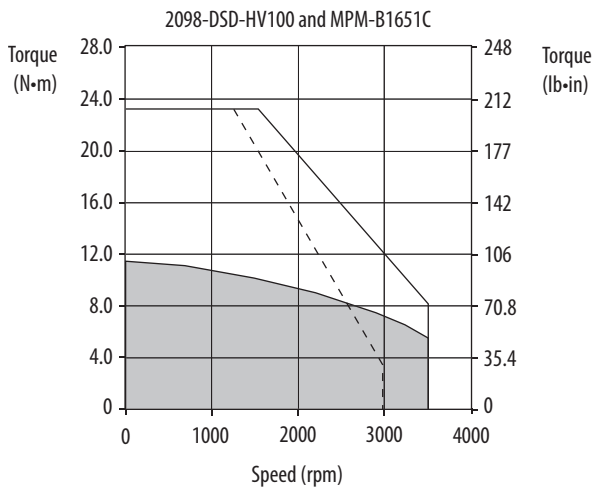
- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Medium Inertia Motor Curves (continued)



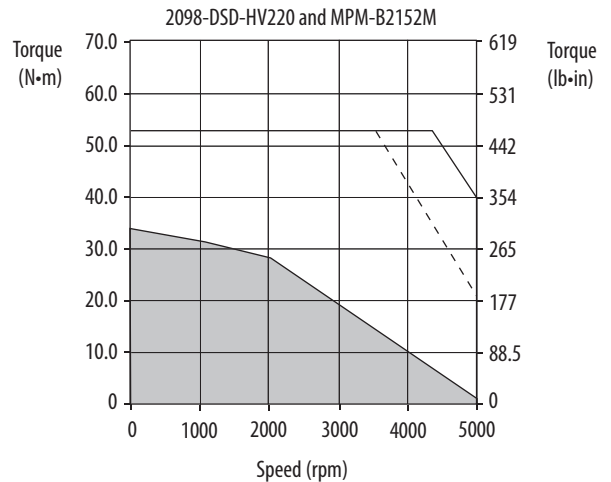
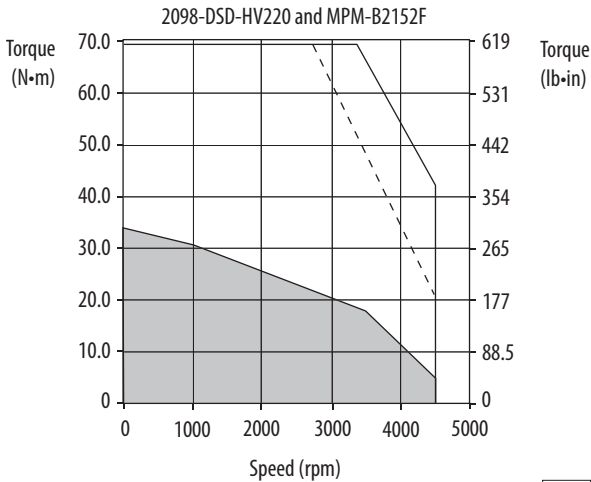
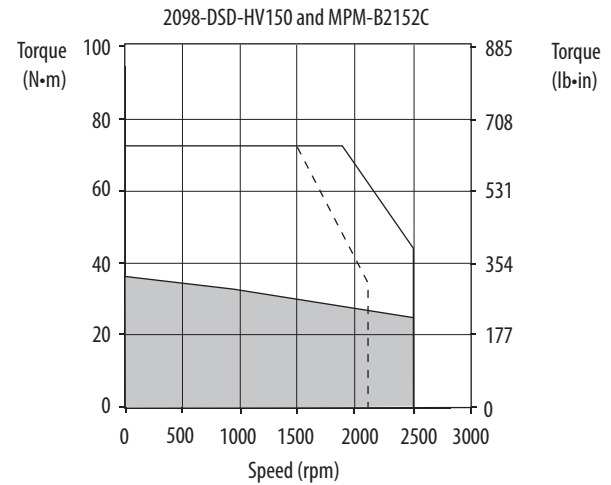
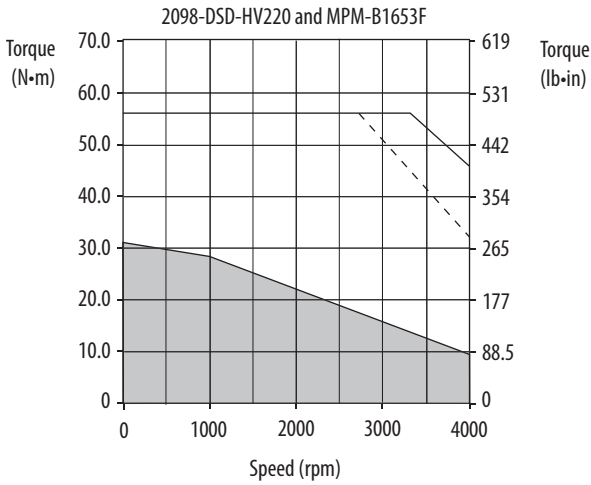
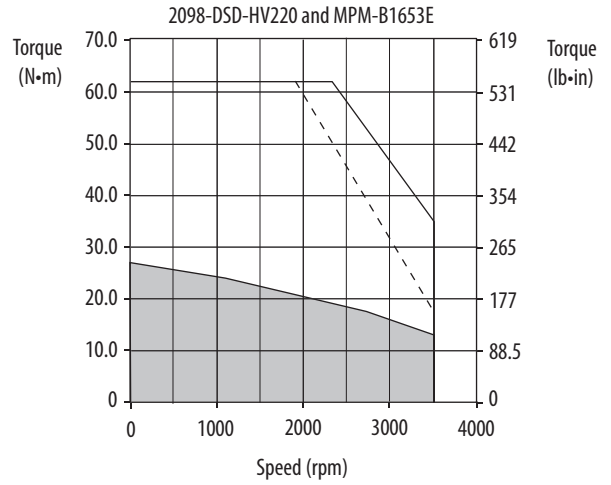
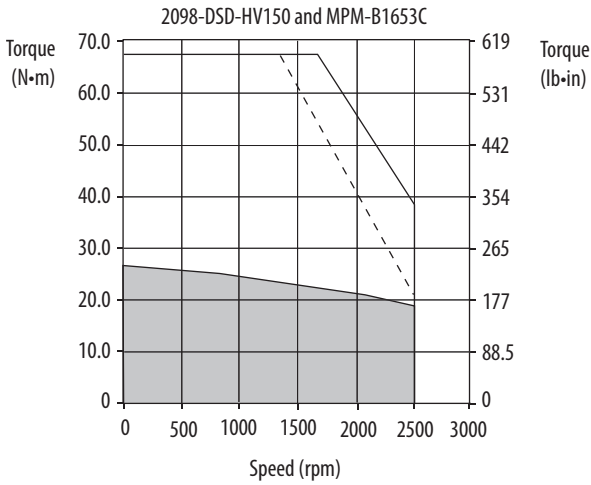
- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Medium Inertia Motor Curves (continued)



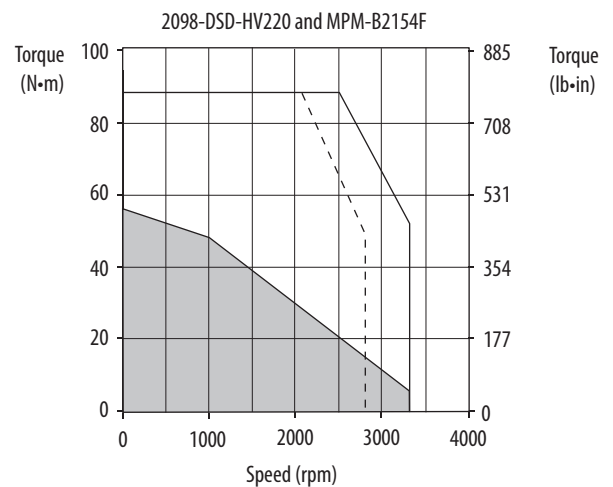
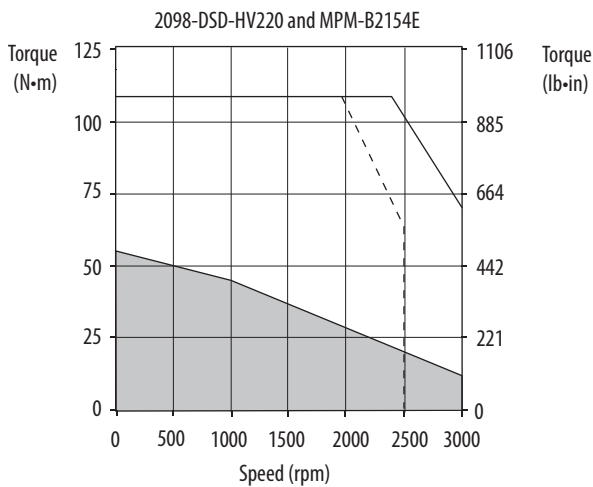
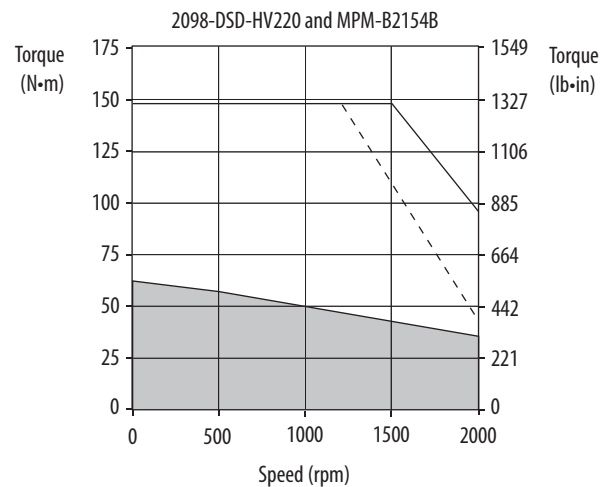
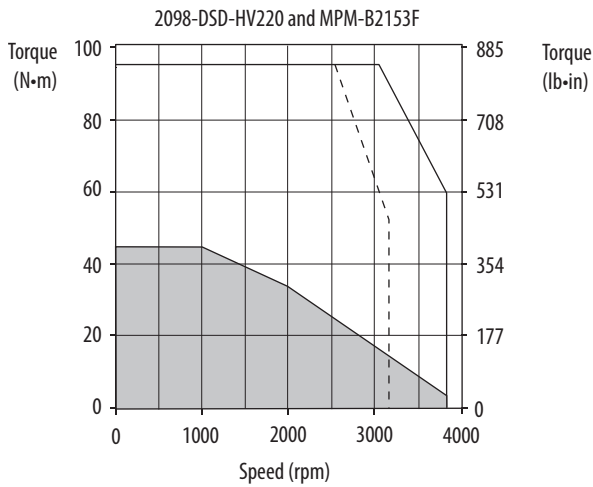
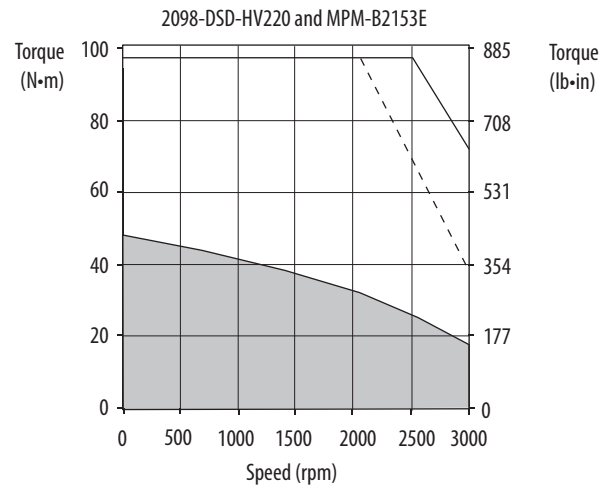
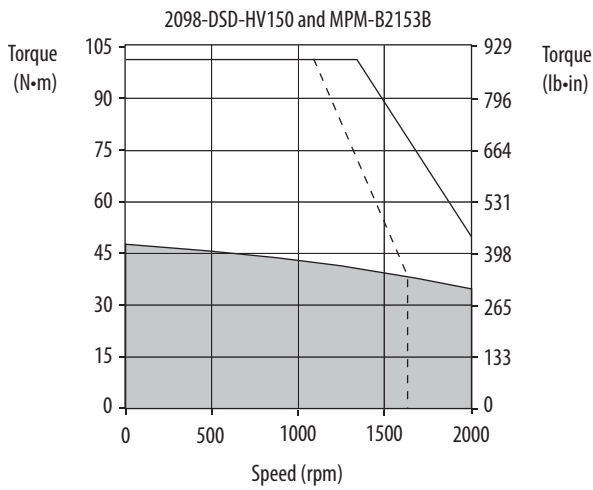
- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Medium Inertia Motor Curves (continued)



- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Medium Inertia Motor Curves (continued)



- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (200V class) Drives with MP-Series Food Grade Motors

This section provides system combination information for the Ultra3000 (200V class) drives when matched with MP-Series food-grade motors. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

Bulletin MPF Motor Cable Combinations

| Motor Cat. No. (200V class) | Motor Power Cable | Motor Feedback Cable ⁽¹⁾ |
|--------------------------------------------|-----------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MPF-A310P, MPF-A320H, MPF-A320P, MPF-A330P | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-CFBM7DF-CEAAxx or 2090-CFBM7DD-CEAAxx (standard, non-flex) 2090-CFBM7DF-CEAFxx or 2090-CFBM7DD-CEAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPF-A430H | | |
| MPF-A430P | 2090-CPxM7DF-14AAxx (standard, non-flex) 2090-CPxM7DF-14AFxx (continuous-flex) | |
| MPF-A4530K, MPF-A4540F | | |
| MPF-A540K | 2090-CPxM7DF-08AAxx (standard, non-flex) 2090-CPxM7DF-08AFxx (continuous-flex) | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) with flying-lead cables on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

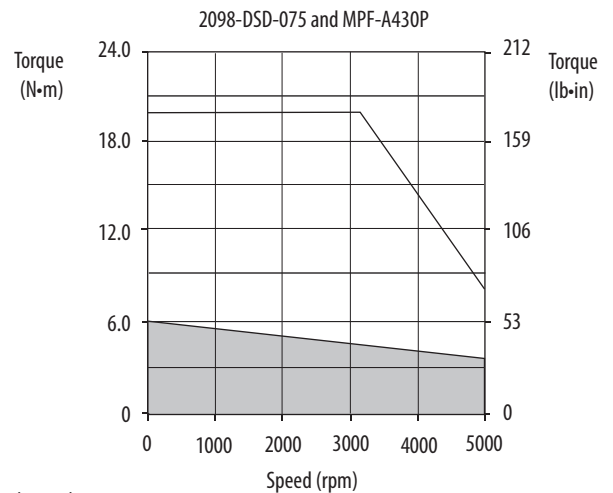
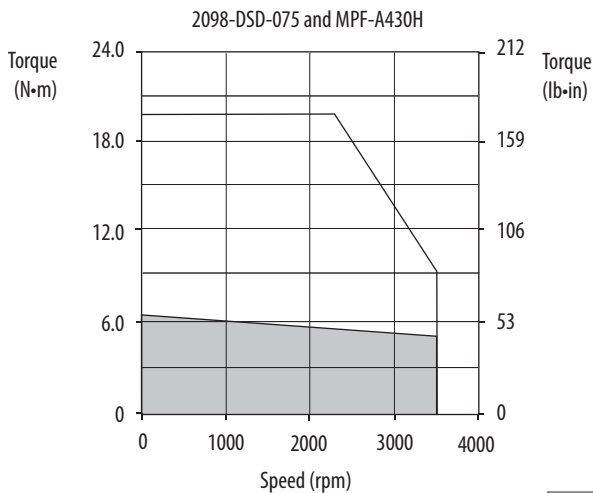
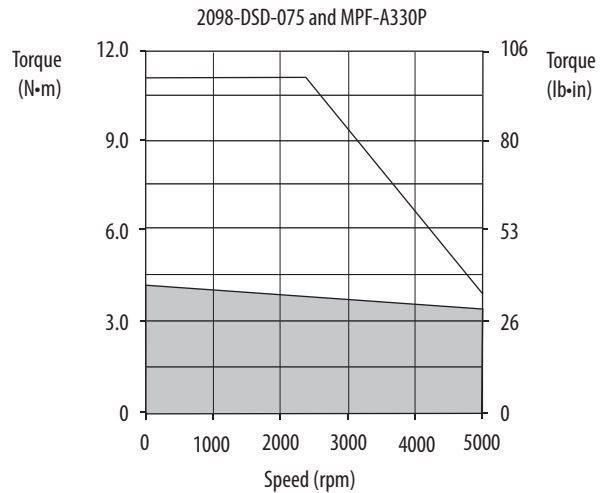
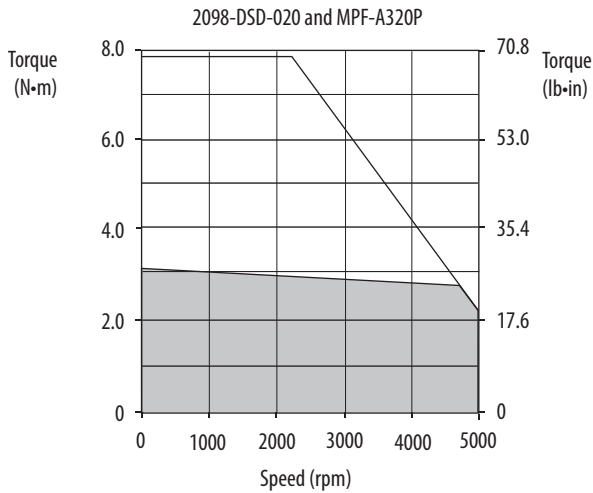
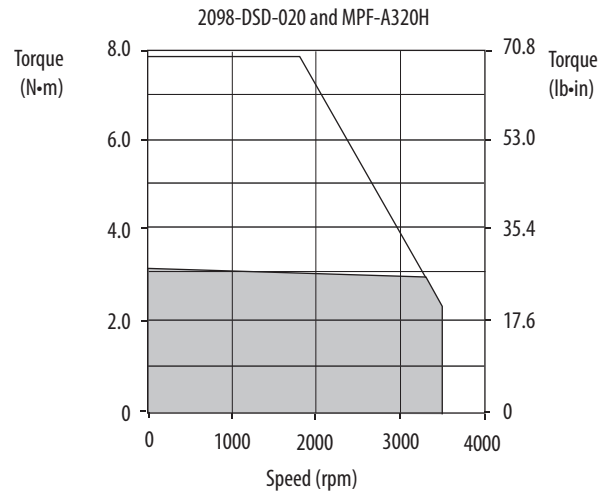
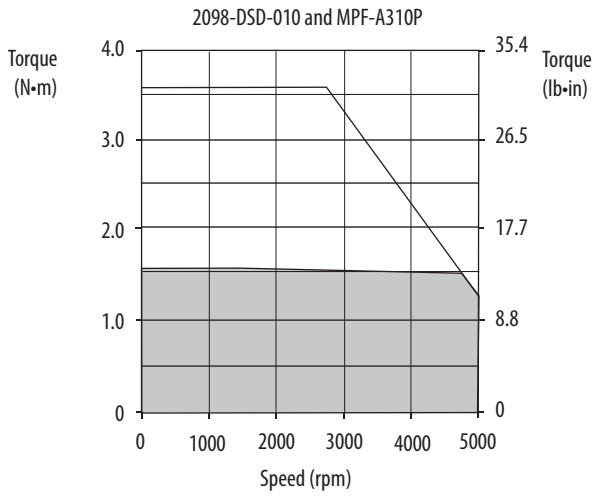
Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin MPF Motor Performance Specifications with Ultra3000 (200V class) Drives

| Rotary Motor | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A 0-pk | System Peak Stall Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 200V-class Drives |
|--------------|----------------|----------------------------------------|--------------------------------------------|----------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPF-A310P | 5000 | 2.50 | 0.79 (7) | 7.5 | 1.92 (17) | 0.73 | 2098-DSD-005 |
| | | 4.85 | 1.58 (14) | 14 | 3.61 (32) | | 2098-DSD-010 |
| MPF-A320H | 3500 | 5.0 | 2.48 (22) | 15 | 6.44 (57) | 1.0 | 2098-DSD-010 |
| | | 6.1 | 3.05 (27) | 19.3 | 7.91 (70) | | 2098-DSD-020 |
| MPF-A320P | 5000 | 5.0 | 1.69 (15) | 15 | 3.95 (35) | 1.3 | 2098-DSD-010 |
| | | 9.0 | 3.05 (27) | 29.5 | 7.91 (70) | | 2098-DSD-020 |
| MPF-A330P | 5000 | 12.0 | 4.18 (37) | 30 | 9.60 (85) | 1.6 | 2098-DSD-030 |
| | | | | 38 | 11.1 (98) | | 2098-DSD-075 |
| MPF-A430H | 3500 | 12.2 | 6.21 (55) | 30 | 14.7 (130) | 1.8 | 2098-DSD-030 |
| | | | | 45 | 19.8 (175) | | 2098-DSD-075 |
| MPF-A430P | 5000 | 15.0 | 5.42 (48) | 30 | 10.2 (90) | 1.9 | 2098-DSD-030 |
| | | 16.8 | 5.99 (53) | 67 | 19.8 (175) | | 2098-DSD-075 |
| MPF-A4530K | 4000 | 15.0 | 6.21 (55) | 30 | 11.3 (100) | 2.3 | 2098-DSD-030 |
| | | 19.5 | 8.13 (72) | 62 | 20.3 (180) | | 2098-DSD-075 |
| MPF-A4540F | 3000 | 15.0 | 8.25 (73) | 30 | 15.8 (140) | 2.5 | 2098-DSD-030 |
| | | 18.4 | 10.2 (90) | 58 | 27.1 (240) | | 2098-DSD-075 |
| MPF-A540K | 4000 | 41.5 | 19.4 (172) | 120 | 48.6 (430) | 4.1 | 2098-DSD-150 |

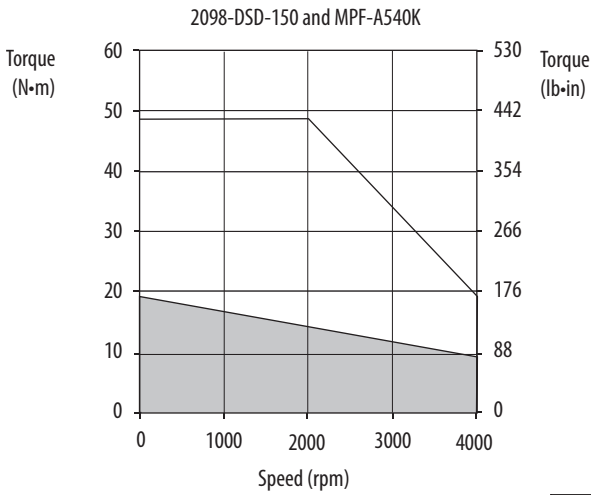
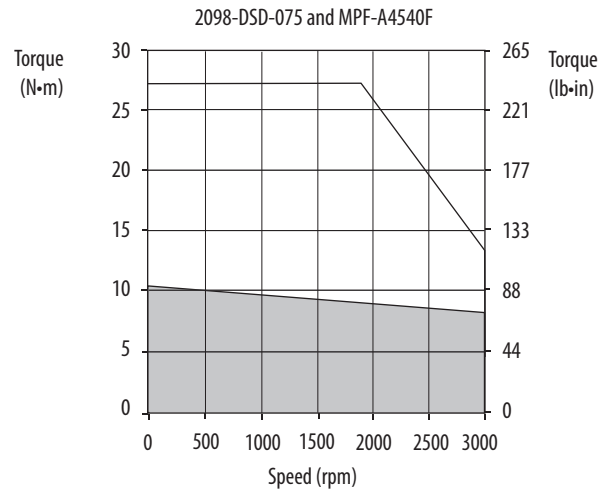
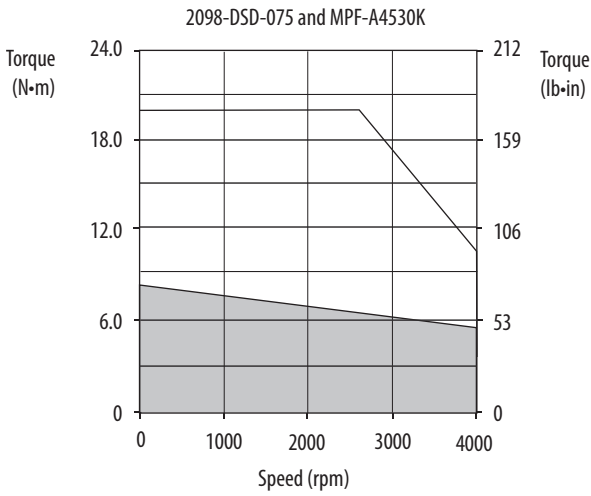
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (200V class) Drives/MP-Series Food Grade Motor Curves



= Intermittent operating region
 = Continuous operating region

Ultra3000 (200V class) Drives/MP-Series Food Grade Motor Curves (continued)



= Intermittent operating region
 = Continuous operating region

Ultra3000 (400V class) Drives with MP-Series Food Grade Motors

This section provides system combination information for the Ultra3000 (400V class) drives when matched with MP-Series food-grade motors. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

Bulletin MPF Motor Cable Combinations

| Motor Cat. No. (400V class) | Motor Power Cable | Motor Feedback Cable ⁽¹⁾ |
|---------------------------------|-----------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MPF-B310P, MPF-B320P, MPF-B330P | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-CFBM7DF-CEAAxx or 2090-CFBM7DD-CEAAxx (standard, non-flex) 2090-CFBM7DF-CEAFxx or 2090-CFBM7DD-CEAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPF-B430P | | |
| MPF-B4530K, MPF-B4540F | | |
| MPF-B540K | 2090-CPxM7DF-10AAxx (standard, non-flex) 2090-CPxM7DF-10AFxx (continuous-flex) | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) with flying-lead cables on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

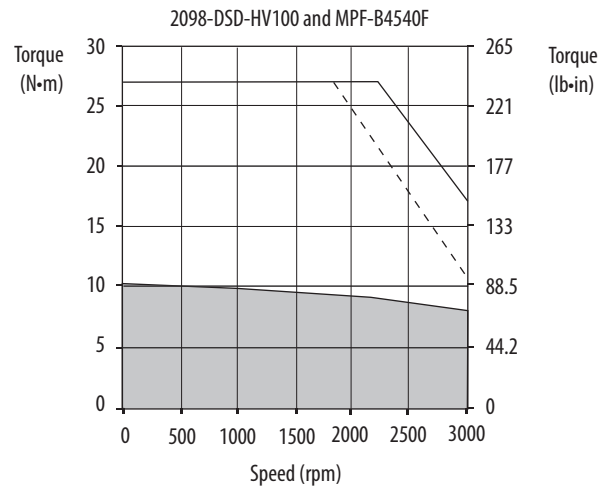
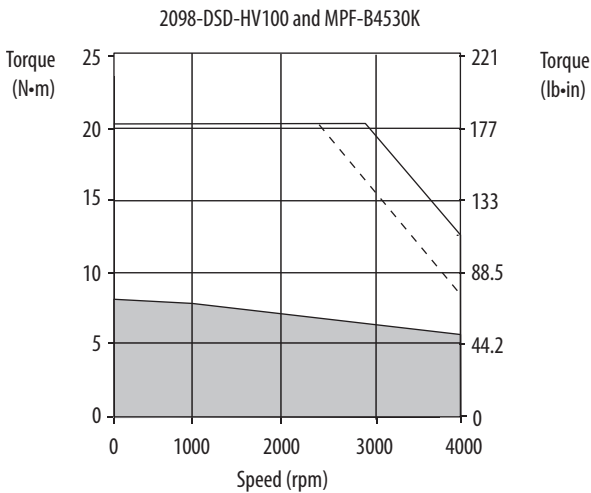
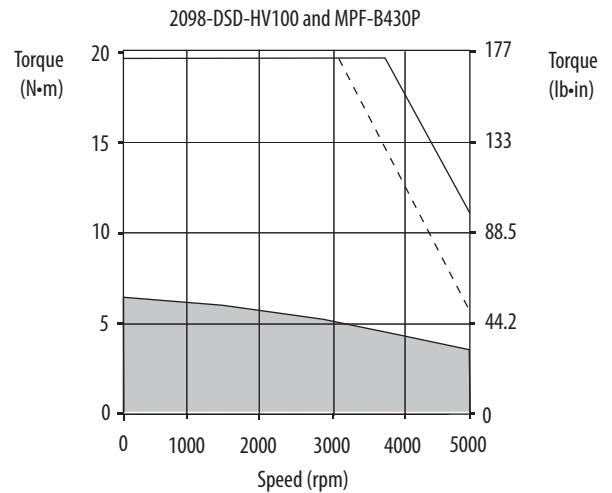
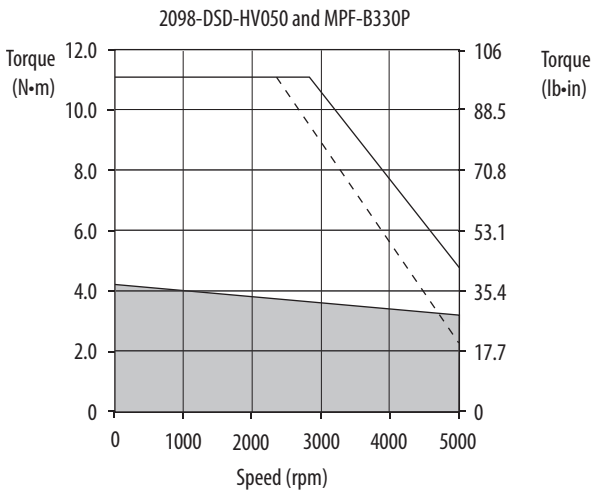
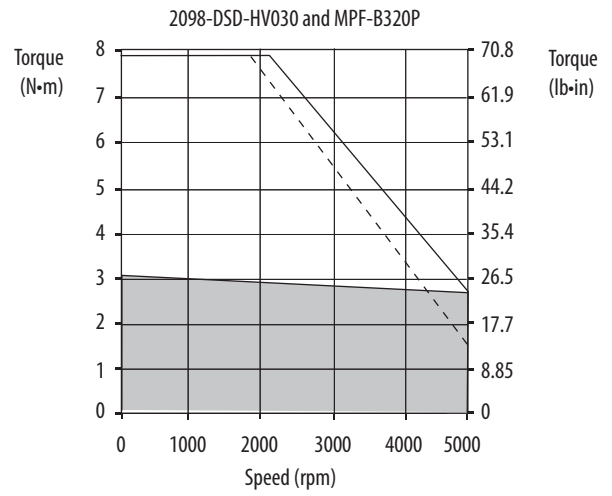
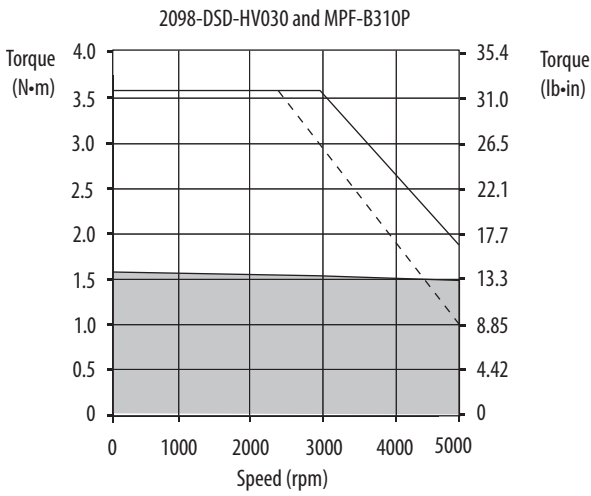
Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin MPF Motor Performance Specifications with Ultra3000 (400V class) Drives

| Rotary Motor | Speed, max rpm | System Continuous Stall Current A (0-pk) | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A (0-pk) | System Peak Stall Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 400V-class Drives |
|--------------|----------------|------------------------------------------|--------------------------------------------|------------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPF-B310P | 5000 | 2.30 | 1.58 (14) | 7.1 | 3.61 (32) | 0.77 | 2098-DSD-HV030 |
| MPF-B320P | 5000 | 4.24 | 3.05 (27) | 14.0 | 7.34 (65) | 1.5 | 2098-DSD-HV030 |
| MPF-B330P | 5000 | 5.70 | 4.18 (37) | 14.0 | 8.59 (76) | 1.6 | 2098-DSD-HV030 |
| | | | | 19.0 | 11.1 (98) | | 2098-DSD-HV050 |
| MPF-B430P | 5000 | 9.20 | 6.55 (58) | 22.0 | 12.9 (114) | 2.0 | 2098-DSD-HV050 |
| | | | | 32.0 | 19.8 (175) | | 2098-DSD-HV100 |
| MPF-B4530K | 4000 | 9.90 | 8.25 (73) | 22.0 | 14.5 (128) | 2.4 | 2098-DSD-HV050 |
| | | | | 31.0 | 20.3 (180) | | 2098-DSD-HV100 |
| MPF-B4540F | 3000 | 9.10 | 10.2 (90) | 22.0 | 22.0 (195) | 2.5 | 2098-DSD-HV050 |
| | | | | 29.0 | 27.1 (240) | | 2098-DSD-HV100 |
| MPF-B540K | 4000 | 20.5 | 19.4 (172) | 46.0 | 33.9 (300) | 4.1 | 2098-DSD-HV100 |
| | | | | 60.0 | 45.2 (400) | | 2098-DSD-HV150 |

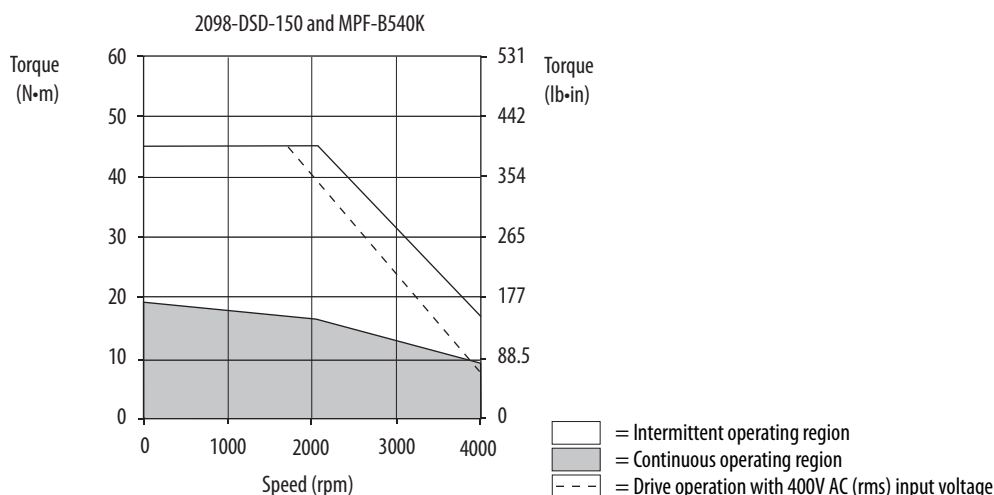
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (400V class) Drives/MP-Series Food Grade Motor Curves



- = Intermittent operating region
- = Continuous operating region
- = Drive operation with 400V AC (rms) input voltage

Ultra3000 (400V class) Drives/MP-Series Food Grade Motor Curves (continued)



Ultra3000 (200V class) Drives with MP-Series Stainless Steel Motors

This section provides system combination information for the Ultra3000 (200V class) drives when matched with MP-Series stainless-steel motors. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

Bulletin MPS Motor Cable Combinations

| Motor Cat. No. (200V class) | Motor Power Cable | Motor Feedback Cable ⁽¹⁾ |
|-----------------------------|----------------------------------------|----------------------------------------------------------------------------|
| MPS-A330P | 2090-XXNPMF-16Sxx (standard, non-flex) | 2090-XXNFMF-Sxx (standard, non-flex) |
| MPS-A4540F | 2090-CPxM4DF-16AFxx (continuous-flex) | 2090-CFBM4DF-CDAFxx (continuous-flex) Absolute High-resolution Feedback |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

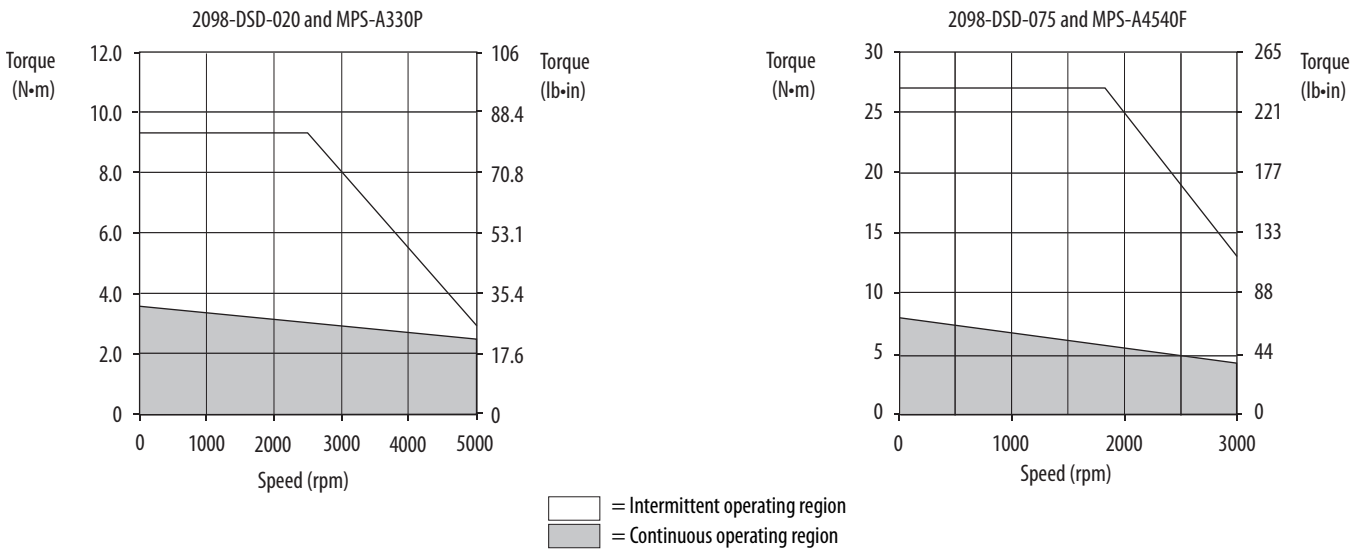
Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin MPS Motor Performance Specifications with Ultra3000 (200V class) Drives

| Rotary Motor | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A 0-pk | System Peak Stall Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 200V-class Drives |
|--------------|----------------|----------------------------------------|--------------------------------------------|----------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPS-A330P | 5000 | 5.0 | 1.80 (16) | 15.0 | 5.20 (46) | 1.3 | 2098-DSD-010 |
| | | 9.80 | 3.60 (32) | 30.0 | 9.30 (82) | | 2098-DSD-020 |
| MPS-A4540F | 3000 | 14.4 | 8.1 (72) | 30.0 | 15.9 (141) | 1.4 | 2098-DSD-030 |
| | | | | 56.0 | 27.1 (240) | | 2098-DSD-075 |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (200V class) Drives/MP-Series Stainless Steel Motor Curves



Ultra3000 (400V class) Drives with MP-Series Stainless Steel Motors

This section provides system combination information for the Ultra3000 (400V class) drives when matched with MP-Series stainless-steel motors. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

Bulletin MPS Motor Cable Combinations

| Motor Cat. No. (400V class) | Motor Power Cable | Motor Feedback Cable ⁽¹⁾ |
|-----------------------------|---------------------------------------------------------------------------------|-------------------------------------------------------------------------------|
| MPS-B330P | 2090-XXNPMF-16Sxx (standard, non-flex) | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM4DF-CDAFxx (continuous-flex) |
| MPS-B4540F | 2090-CPxM4DF-16AFxx (continuous-flex) | |
| MPS-B560F | 2090-XXNPMF-14Sxx (standard, non-flex) 2090-CPxM4DF-14AFxx (continuous-flex) | Absolute High-resolution Feedback |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

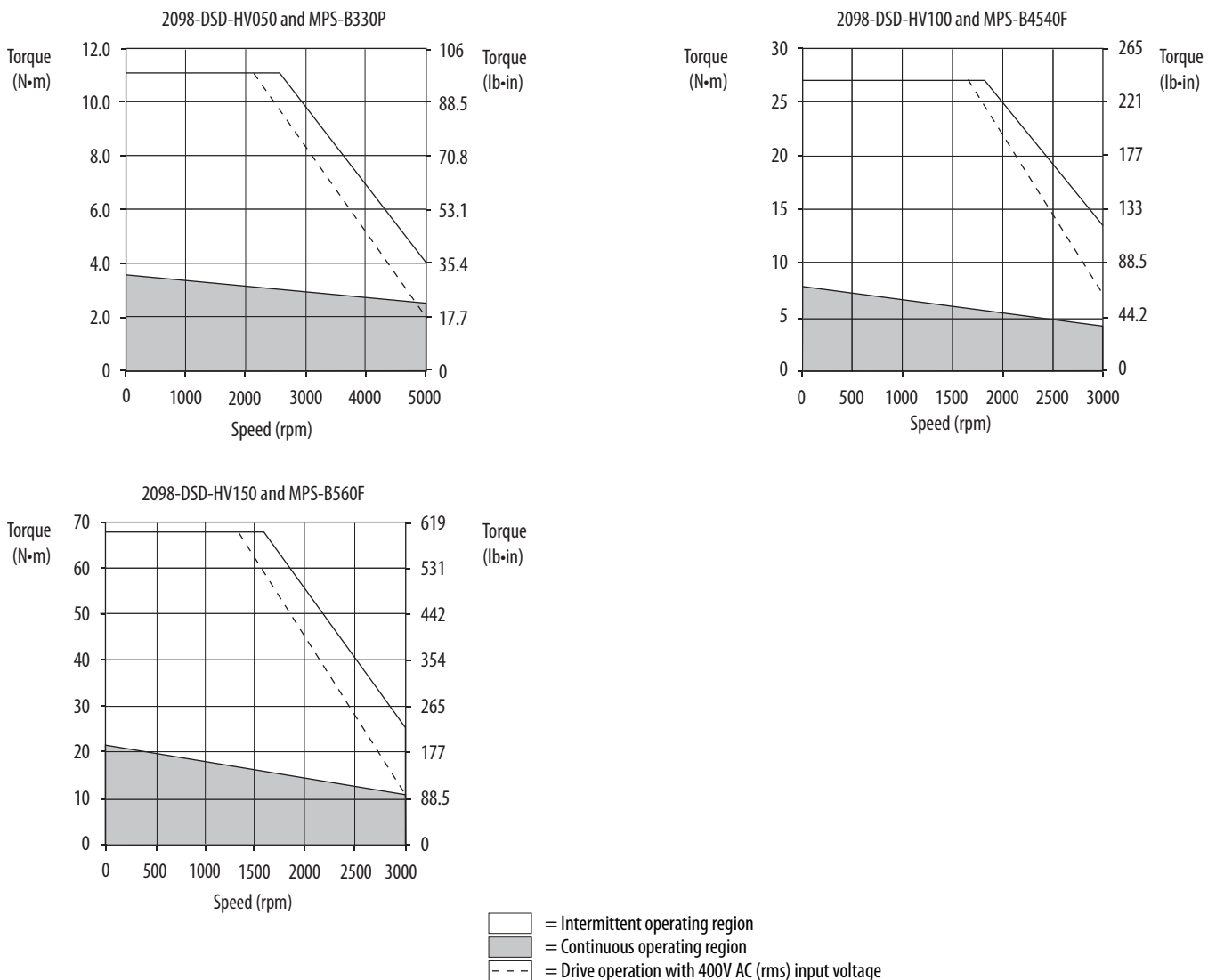
Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin MPS Motor Performance Specifications with Ultra3000 (400V class) Drives

| Rotary Motor | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A 0-pk | System Peak Stall Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 400V-class Drives |
|--------------|----------------|----------------------------------------|--------------------------------------------|----------------------------------|--------------------------------------|-----------------------|-----------------------------|
| MPS-B330P | 5000 | 4.90 | 3.6 (32) | 14.0 | 8.80 (78) | 1.3 | 2098-DSD-HV030 |
| | | | | 19.0 | 11.10 (98) | | 2098-DSD-HV050 |
| MPS-B4540F | 3000 | 7.0 | 8.0 (71) | 14.0 | 15.6 (138) | 1.4 | 2098-DSD-HV030 |
| | | | | 22.0 | 23.5 (208) | | 2098-DSD-HV050 |
| | | | | 26.0 | 27.1 (240) | | 2098-DSD-HV100 |
| MPS-B560F | 3000 | 17.0 | 21.5 (190) | 46.0 | 50.1 (443) | 3.5 | 2098-DSD-HV100 |
| | | | | 68.0 | 67.7 (599) | | 2098-DSD-HV150 |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (400V class) Drives/MP-Series Stainless Steel Motor Curves



Ultra3000 Drives with TL-Series Low Inertia Motors

This section provides system combination information for the Ultra3000 (200V class) drives when matched with TL-Series™ (Bulletin TLY) low-inertia motors. Compatible TL-Series motors are equipped with incremental encoder feedback. Included are motor power/brake and feedback cable catalog numbers, system performance specifications, and the optimum torque/speed curves.

Bulletin TLY Motor Cable Combinations

| Motor Cat. No. (200V class) | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|---------------------------------|-----------------------------------------------------------|--------------------------------------------------------------------------------------------|
| TLY-A110T, TLY-A120T, TLY-A130T | 2090-CPWM6DF-16AAxx (standard, non-flex) without brake | 2090-CFBM6DF-CBAAxx or 2090-CFBM6DD-CCAAxx (standard, non-flex) Incremental Feedback |
| TLY-A220T, TLY-A230T | | |
| TLY-A2530P, TLY-A2540P | 2090-CPBM6DF-16AAxx (standard, non-flex) with brake | |
| TLY-A310M | | |

(1) For TLY-Axxxx-H motors with incremental encoder feedback, use 2090-CFBM6DF-CBAAxx flying-lead cables and 2090-UXBB-DM15 connector kit or use 2090-CFBM6DD-CCAAxx (15-pin connector) cable on the drive end. Refer to Required Drive Accessories on [page 4](#).

TL-Series (Bulletin TLY-Axxx) motors are characterized as having 1000 mm (39.4 in.) cable extensions with circular plastic connectors.

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Bulletin TLY (non-brake) Performance Specifications with Ultra3000 (200V class) Drives

| Rotary Motor | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb·in) | System Peak Stall Current A 0-pk | System Peak Torque N·m (lb·in) | Motor Rated Output kW | Ultra3000 200V-class Drives | |
|--------------|----------------|----------------------------------------|--------------------------------------------|----------------------------------|--------------------------------|-----------------------|-----------------------------|--------------|
| TLY-A110T | 6000 | 0.55 | 0.096 (0.85) | 1.50 | 0.20 (1.75) | 0.041 | 2098-DSD-005 | |
| TLY-A120T | | 1.03 | 0.181 (1.60) | 2.50 | 0.36 (3.20) | 0.086 | 2098-DSD-005 | |
| TLY-A130T | | 1.85 | 0.325 (2.88) | 4.90 | 0.76 (6.70) | 0.14 | 2098-DSD-005 | |
| TLY-A220T | | 2.50 | 0.576 (5.10) | 7.50 | 1.40 (12.4) | 0.35 | 2098-DSD-005 | |
| | | 3.50 | 0.836 (7.40) | 7.90 | 1.48 (13.1) | | 2098-DSD-010 | |
| TLY-A230T | | 5.00 | 1.17 (10.4) | 15.0 | 2.94 (26.0) | 0.44 | 2098-DSD-010 | |
| | | 5.50 | 1.30 (11.5) | 15.5 | 3.05 (27.0) | | 2098-DSD-020 | |
| TLY-A2530P | | 5000 | 5.00 | 1.32 (11.7) | 15.0 | 3.73 (33.0) | 0.69 | 2098-DSD-010 |
| | 10.0 | | 2.60 (23.0) | 21.0 | 5.20 (46.0) | 2098-DSD-020 | | |
| TLY-A2540P | 5.00 | | 1.49 (13.2) | 15.0 | 4.40 (39.0) | 0.86 | 2098-DSD-010 | |
| | 10.0 | | 2.94 (26.0) | 24.8 | 7.10 (63.0) | | 2098-DSD-020 | |
| TLY-A310M | 4500 | | 10.0 | 3.61 (31.9) | 30.0 | 9.0 (79.6) | 0.95 | 2098-DSD-020 |

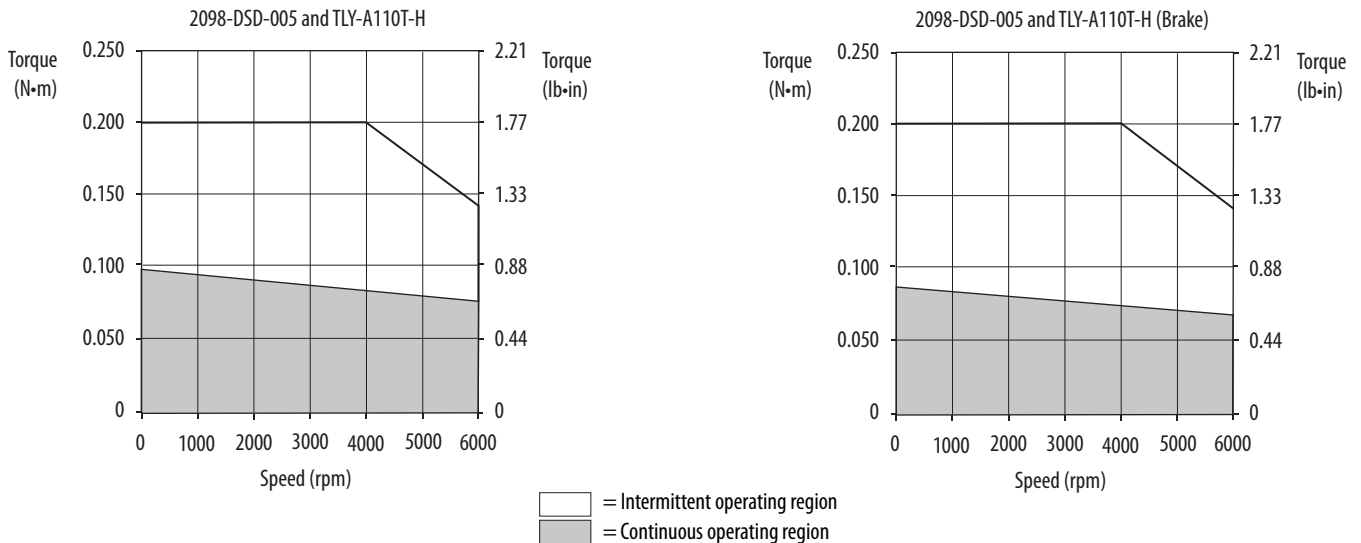
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Bulletin TLY (brake) Performance Specifications with Ultra3000 (200V class) Drives

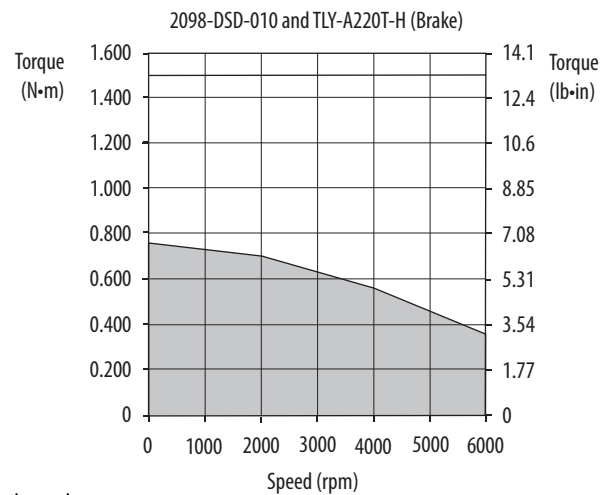
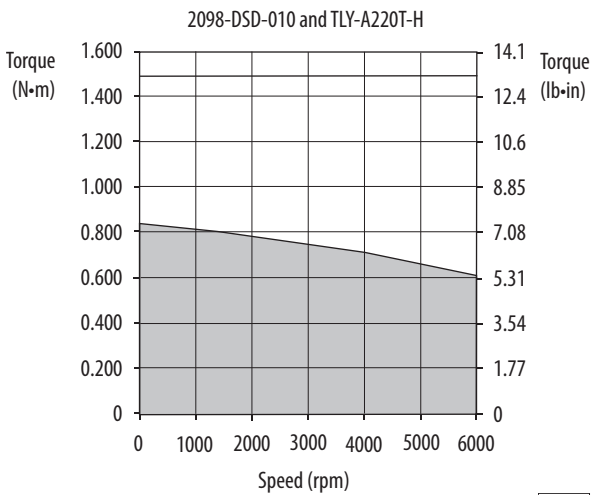
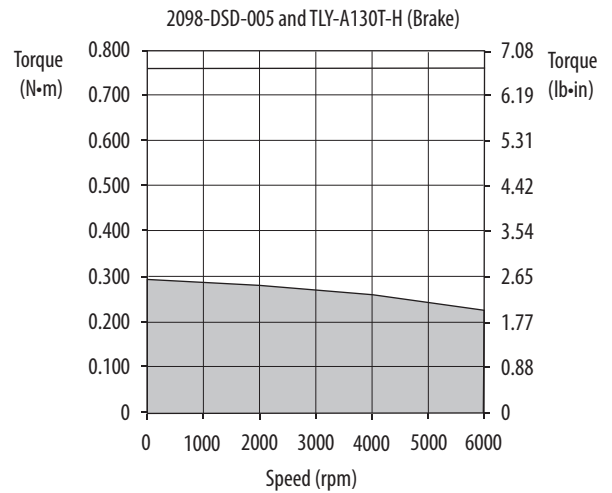
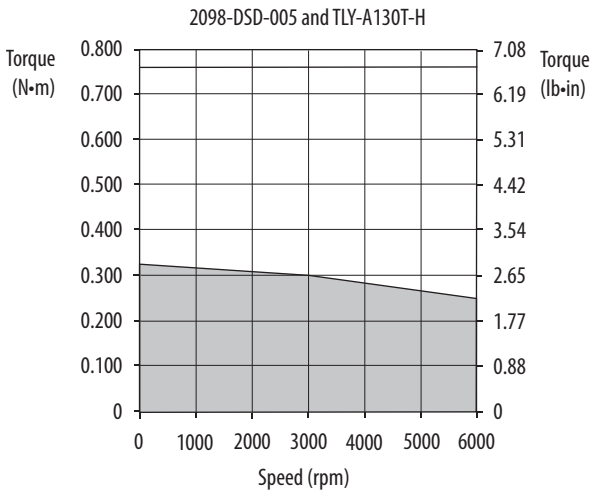
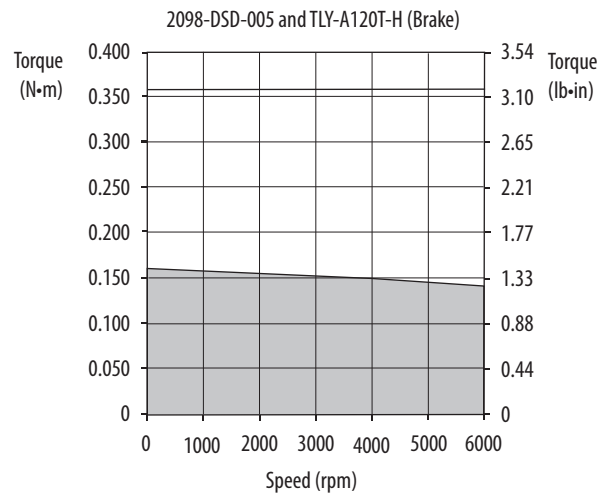
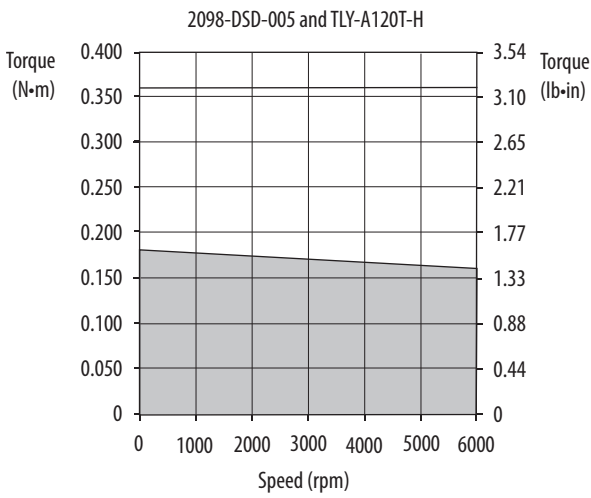
| Rotary Motor | Speed, max rpm | System Continuous Stall Current A 0-pk | System Continuous Stall Torque N·m (lb-in) | System Peak Stall Current A 0-pk | System Peak Torque N·m (lb-in) | Motor Rated Output kW | Ultra3000 200V-class Drives |
|--------------|----------------|-------------------------------------------|-----------------------------------------------|-------------------------------------|-----------------------------------|--------------------------|-----------------------------|
| TLY-A110T | 6000 | 0.50 | 0.086 (0.76) | 1.50 | 0.20 (1.75) | 0.037 | 2098-DSD-005 |
| TLY-A120T | | 0.93 | 0.163 (1.44) | 2.50 | 0.36 (3.20) | 0.077 | 2098-DSD-005 |
| TLY-A130T | | 1.67 | 0.293 (2.59) | 4.90 | 0.76 (6.70) | 0.13 | 2098-DSD-005 |
| TLY-A220T | | 2.50 | 0.576 (5.10) | 7.50 | 1.40 (12.4) | 0.24 | 2098-DSD-005 |
| | | 3.15 | 0.757 (6.70) | 7.90 | 1.48 (13.1) | | 2098-DSD-010 |
| TLY-A230T | | 4.95 | 1.16 (10.3) | 15.0 | 2.94 (26.0) | 0.32 | 2098-DSD-010 |
| | 15.5 | | | 3.05 (27.0) | 2098-DSD-020 | | |
| TLY-A2530P | 5000 | 5.00 | 1.32 (11.7) | 15.0 | 3.73 (33.0) | 0.55 | 2098-DSD-010 |
| | | 10.0 | 2.60 (23.0) | 21.0 | 5.20 (46.0) | | 2098-DSD-020 |
| TLY-A2540P | | 5.0 | 1.49 (13.2) | 15.0 | 4.40 (39.0) | 0.66 | 2098-DSD-010 |
| | | 10.0 | 2.94 (26.0) | 24.8 | 7.10 (63.0) | | 2098-DSD-020 |
| TLY-A310M | 4500 | 10.0 | 3.61 (31.9) | 30.0 | 9.0 (79.6) | 0.90 | 2098-DSD-020 |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (200V class) Drives/TLY-Axxxx-H (incremental) Motor Curves

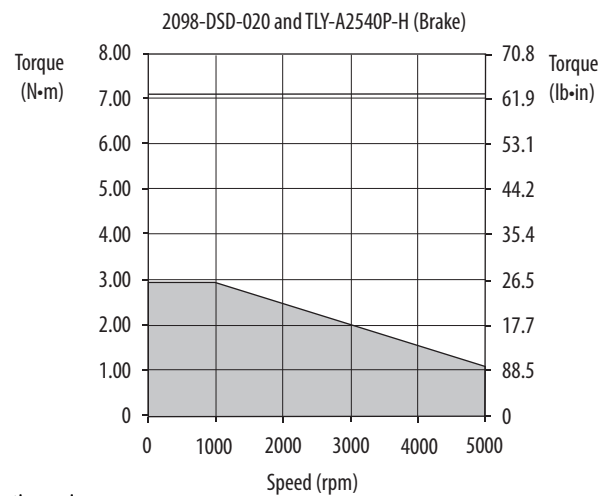
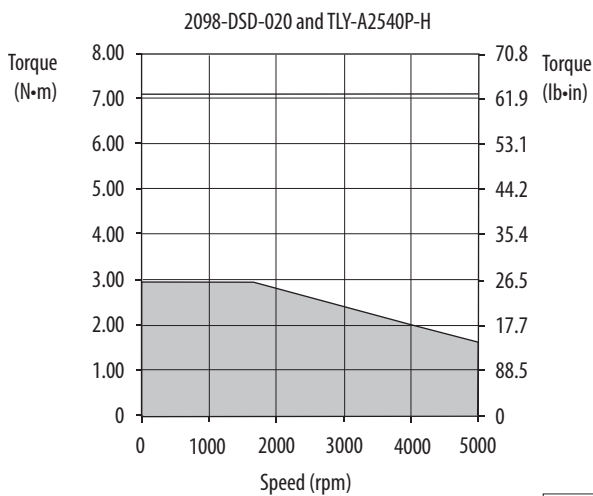
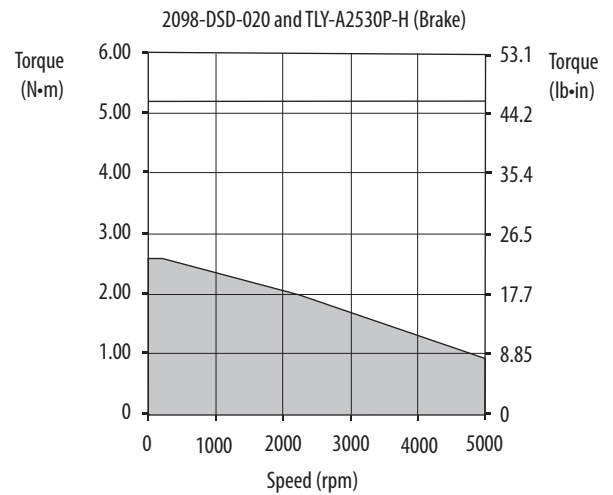
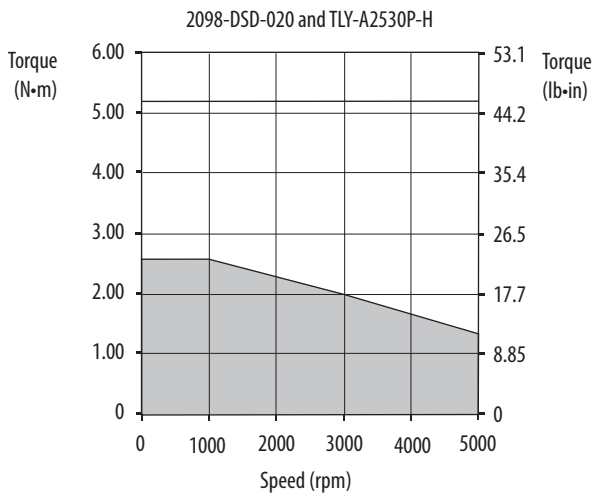
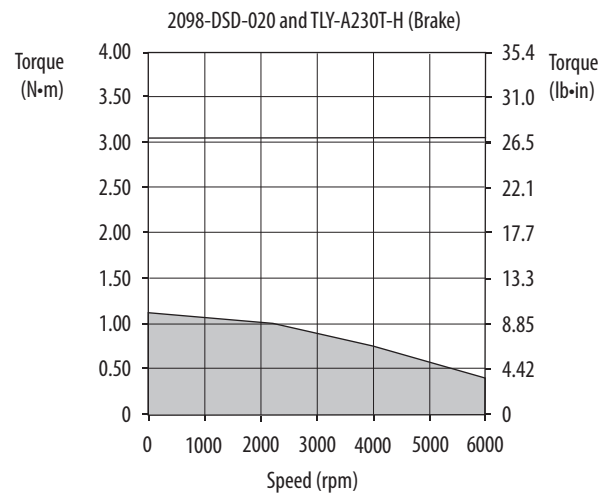
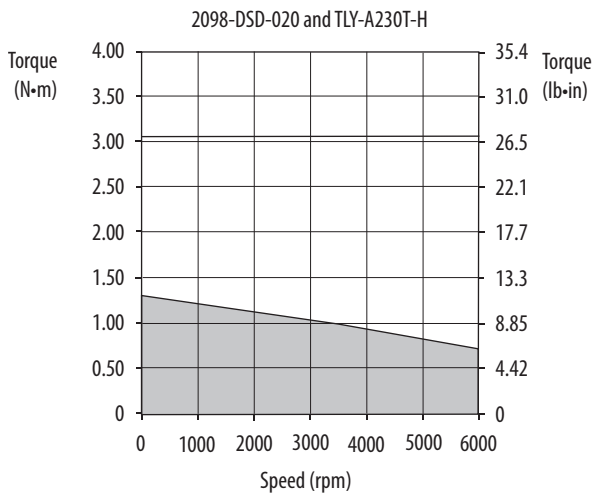




Ultra3000 (200V class) Drives/TLY-Axxxx-H (incremental) Motor Curves (continued)



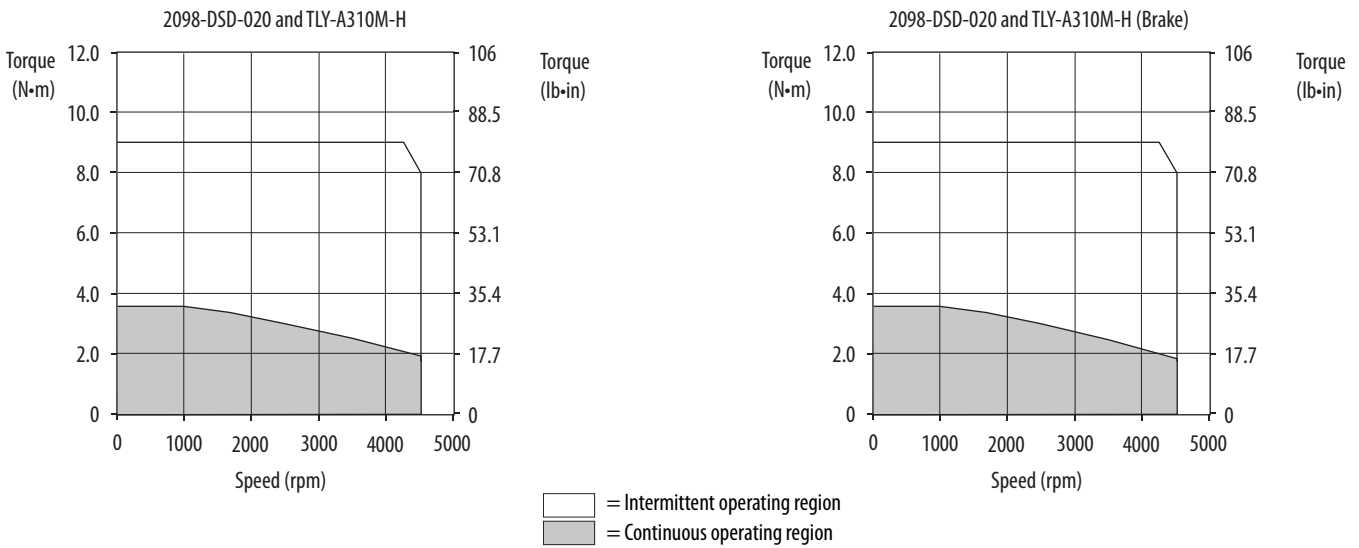
= Intermittent operating region
 = Continuous operating region

Ultra3000 (200V class) Drives/TLY-Axxxx-H (incremental) Motor Curves (continued)



 = Intermittent operating region
 = Continuous operating region

Ultra3000 (200V class) Drives/TLY-Axxxx-H (incremental) Motor Curves (continued)



Ultra3000 (200V class) Drives with MP-Series Integrated Linear Stages

This section provides system combination information for the Ultra3000 (200V class) drives when matched with MP-Series (200V class) integrated direct-drive or ballscrew linear stages. Included are power/brake and feedback cable catalog numbers, system performance specifications, and the optimum force/velocity curves.

Linear Stage Cable Combinations

| Linear Stage | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|------------------------------------------------------------------|---------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------|
| MPAS-Axxxx1-V05SxA, MPAS-Axxxx2-V20SxA | 2090-XXNPMF-16Sxx (standard, non-flex) 2090-CPxM4DF-16AFxx (continuous-flex) | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM4DF-CDAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPAS-A6xxxB-ALMx2C, MPAS-A8xxxE-ALMx2C, MPAS-A9xxxK-ALMx2C | | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM4DF-CDAFxx (continuous-flex) Incremental Feedback |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Linear Stage Performance Specifications with Ultra3000 (200V class) Drives

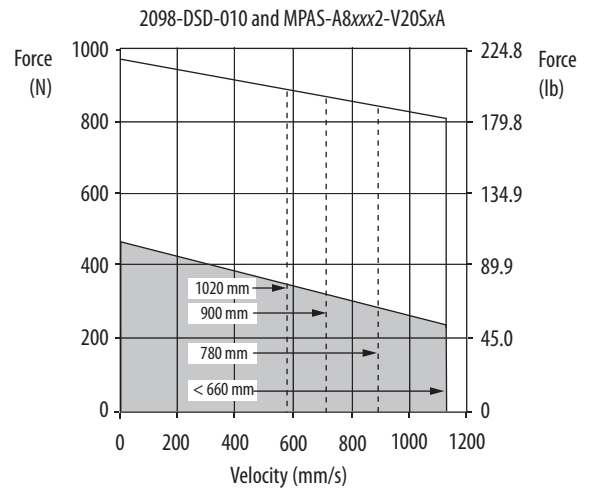
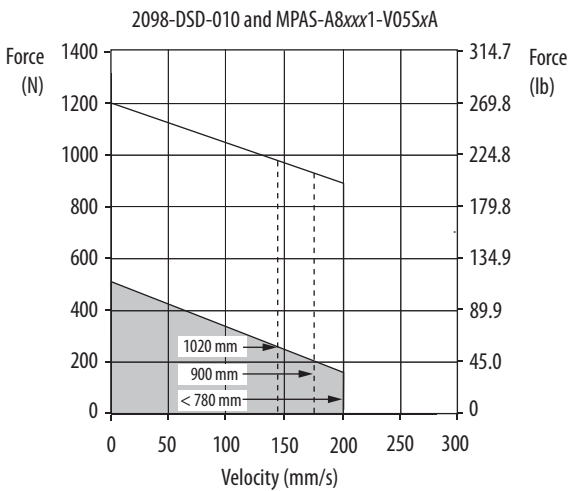
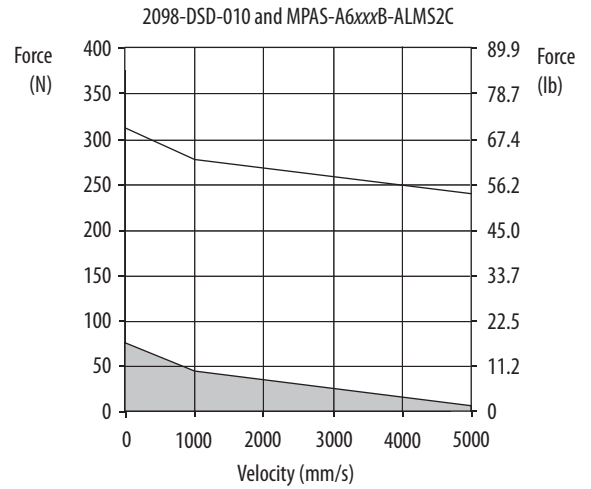
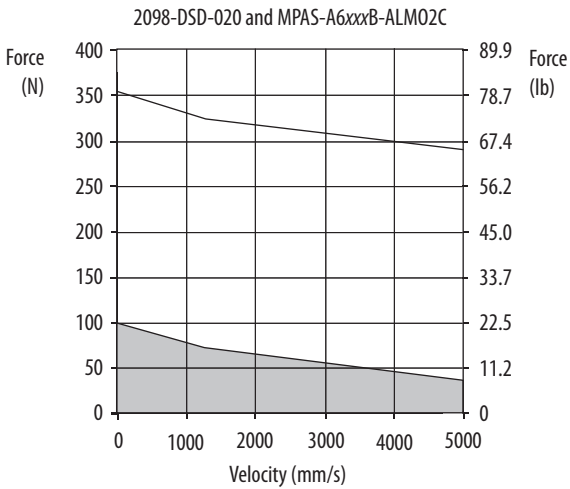
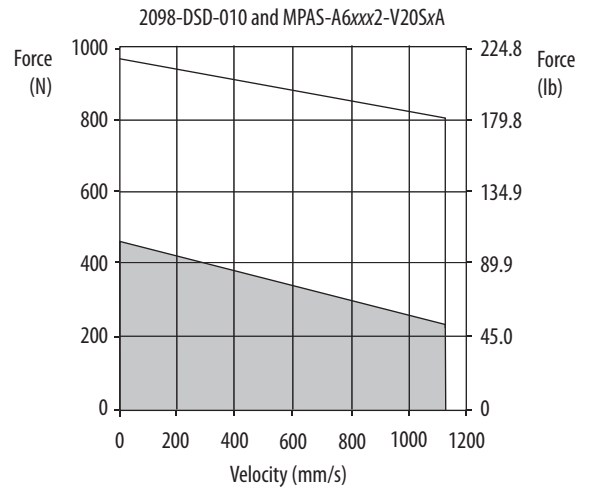
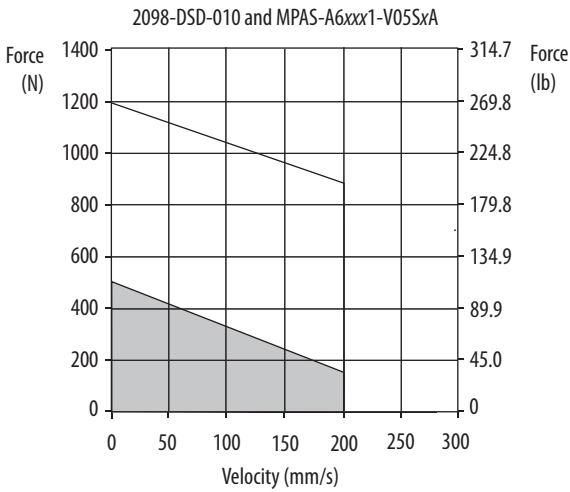
| Linear Stage | Speed, max mm/s (in/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Linear Stage Rated Output kW | Ultra3000 200V-class Drives |
|--------------------|----------------------------|-------------------------------------------------|--------------------------------------------|-------------------------------------------|--------------------------------------|------------------------------------|--------------------------------|
| MPAS-Axxxx1-V05SxA | 200 (7.9) ⁽¹⁾ | 2.50 | 422 (94.9) | 6.10 | 1212 (272) | 0.37 | 2098-DSD-005 |
| | | 3.09 | 521 (117) | | | | 2098-DSD-010 |
| MPAS-Axxxx2-V20SxA | 1124 (44.3) ⁽²⁾ | 2.50 | 254 (57.1) | 7.50 | 798 (179) | 0.62 | 2098-DSD-005 |
| | | 4.54 | 462 (104) | 9.10 | 968 (218) | | 2098-DSD-010 |
| MPAS-A6xxxB-ALM02C | 5000 (200) | 5.0 | 97.8 (22.0) | 15.0 | 340 (76.4) | 0.32 | 2098-DSD-010 |
| | | 5.3 | 105 (23.6) | 15.8 | 359 (80.7) | | 2098-DSD-020 |
| MPAS-A6xxxB-ALMS2C | | 2.5 | 29.6 (6.65) | 7.5 | 150 (33.7) | 0.29 | 2098-DSD-005 |
| | | 4.7 | 83.0 (18.7) | 14.2 | 312 (70.1) | | 2098-DSD-010 |
| MPAS-A8xxxE-ALM02C | | 5.0 | 129 (29.0) | 15.0 | 366 (82.3) | 0.53 | 2098-DSD-010 |
| | | 7.0 | 189 (42.5) | 18.5 | 456 (103) | | 2098-DSD-020 |
| MPAS-A8xxxE-ALMS2C | | 5.0 | 120 (27.0) | 15.0 | 356 (80.0) | 0.48 | 2098-DSD-010 |
| | | 6.3 | 159 (35.7) | 16.7 | 399 (89.7) | | 2098-DSD-020 |
| MPAS-A9xxxK-ALM02C | | 5.0 | 207 (46.5) | 15.0 | 553 (124) | 0.77 | 2098-DSD-010 |
| | | 6.7 | 285 (64.1) | 18.3 | 680 (153) | | 2098-DSD-020 |
| MPAS-A9xxxK-ALMS2C | | 5.0 | 195 (43.8) | 15.0 | 545 (123) | 0.69 | 2098-DSD-010 |
| | | 6.1 | 245 (55.1) | 16.5 | 601 (135) | | 2098-DSD-020 |

(1) For 900 mm stroke length, maximum speed is 176 mm/s (6.9 in/s). For 1020 mm stroke length, maximum speed is 143 mm/s (5.6 in/s).

(2) For 780 mm stroke length, maximum speed is 889 mm/s (35.0 in/s). For 900 mm stroke length, maximum speed is 715 mm/s (28.2 in/s). For 1020 mm stroke length, maximum speed is 582 mm/s (22.9 in/s).

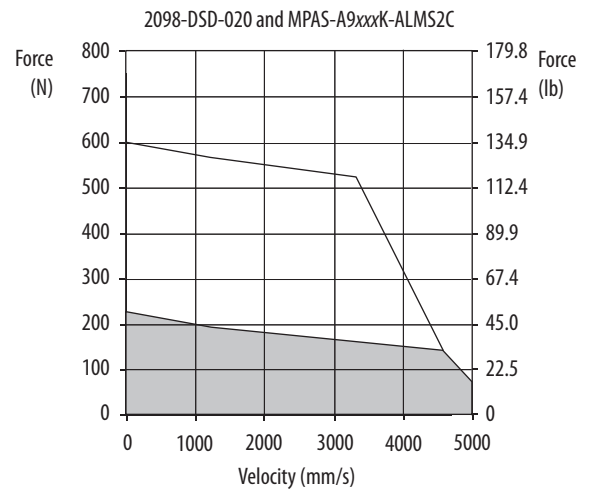
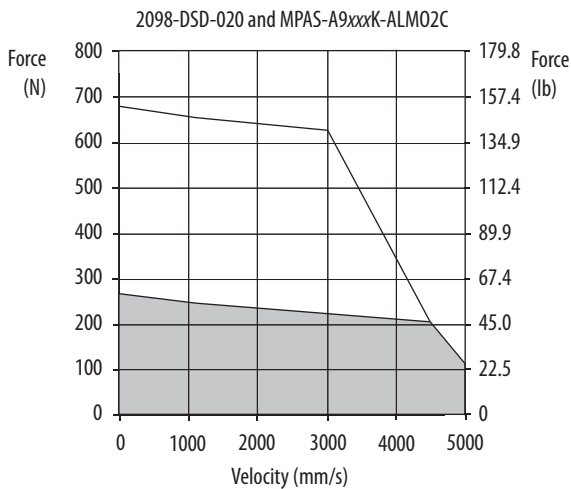
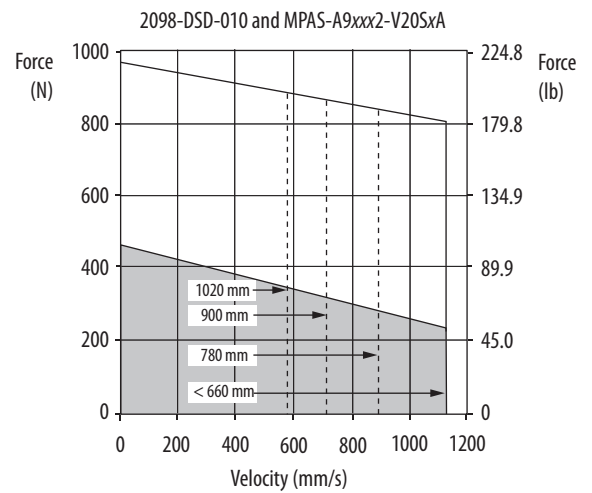
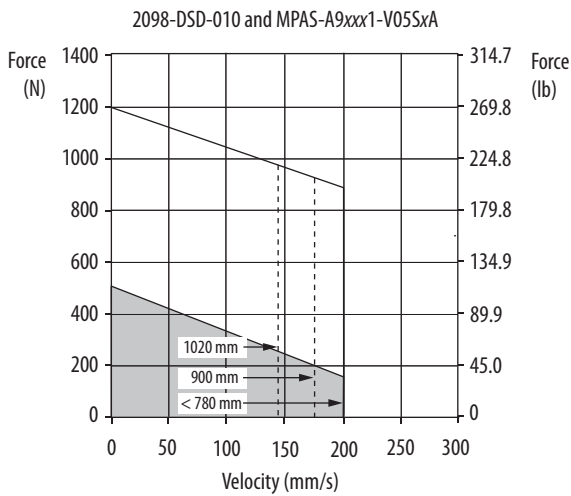
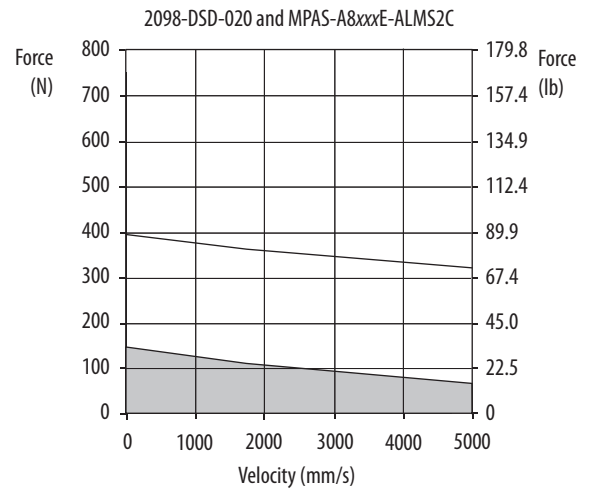
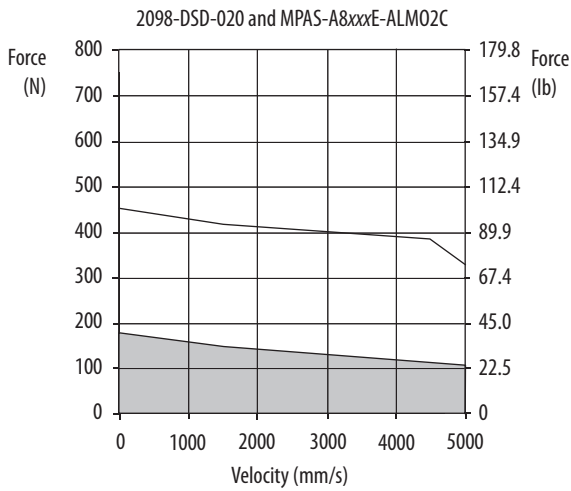
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (200V class) Drives/MP-Series Integrated Linear Stage Curves



- = Intermittent operating region
- = Continuous operating region
- = System operation for specified stroke length

Ultra3000 (200V class) Drives/MP-Series Integrated Linear Stage Curves (continued)



- = Intermittent operating region
- = Continuous operating region
- = System operation for specified stroke length

Ultra3000 (400V class) Drives with MP-Series Integrated Linear Stages

This section provides system combination information for the Ultra3000 (400V class) drives when matched with MP-Series (400V class) integrated direct-drive or ballscrew linear stages. Included are motor power and feedback cable catalog numbers, system performance specifications, and the optimum force/velocity curves.

Linear Stage Cable Combinations

| Linear Stage | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|-------------------------------------------|---------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------|
| MPAS-Bxxxx1-V05SxA, MPAS-Bxxxx2-V20SxA | 2090-XXNPMF-16Sxx (standard, non-flex) 2090-CPxM4DF-16AFxx (continuous-flex) | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM4DF-CDAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPAS-B8xxxF-ALMx2C, MPAS-B9xxxL-ALMx2C | | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM4DF-CDAFxx (continuous-flex) Incremental Feedback |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Linear Stage Performance Specifications with Ultra3000 (400V class) Drives

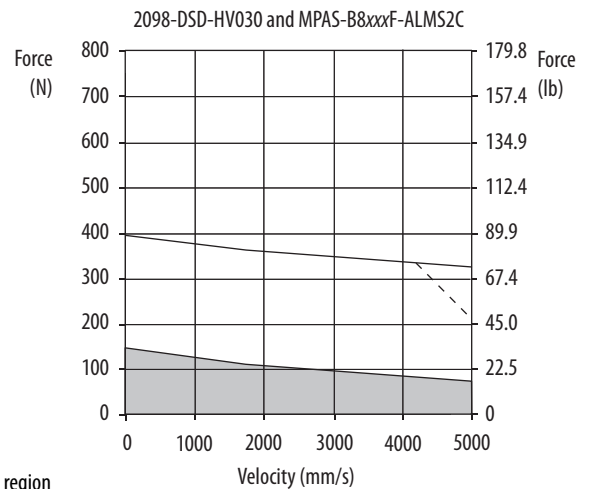
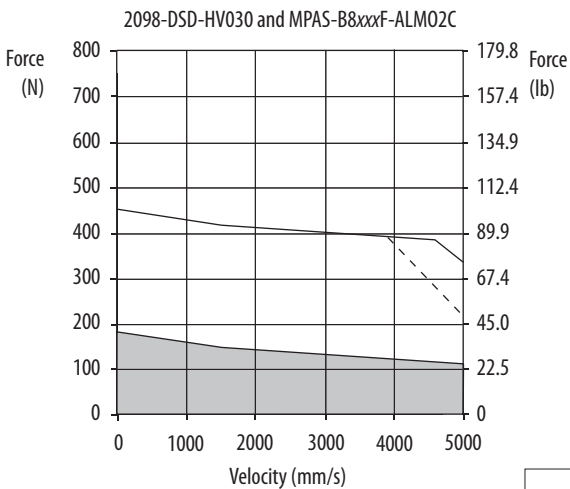
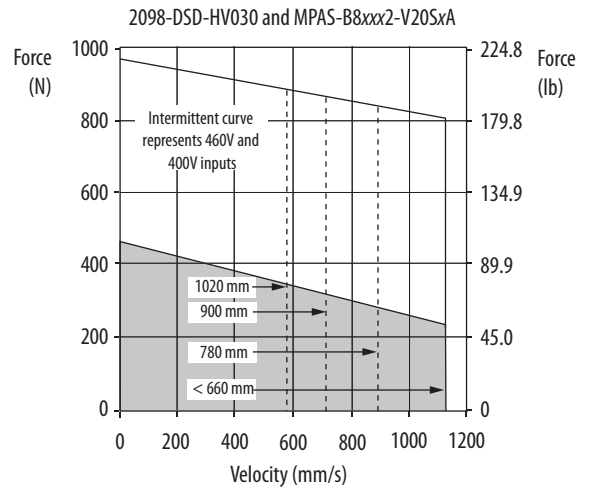
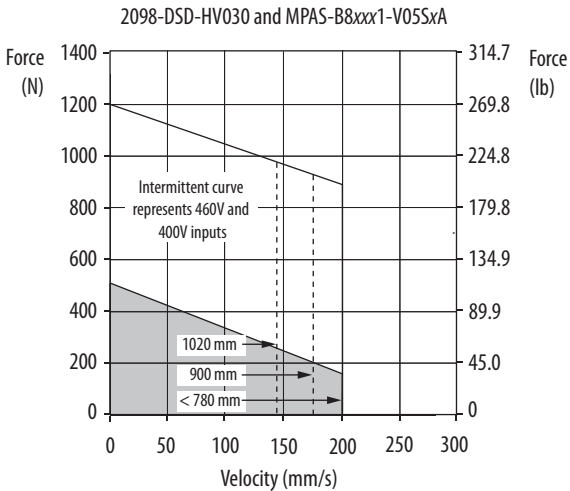
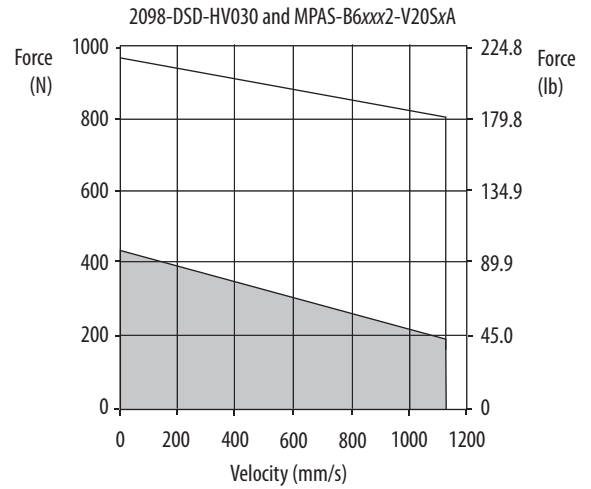
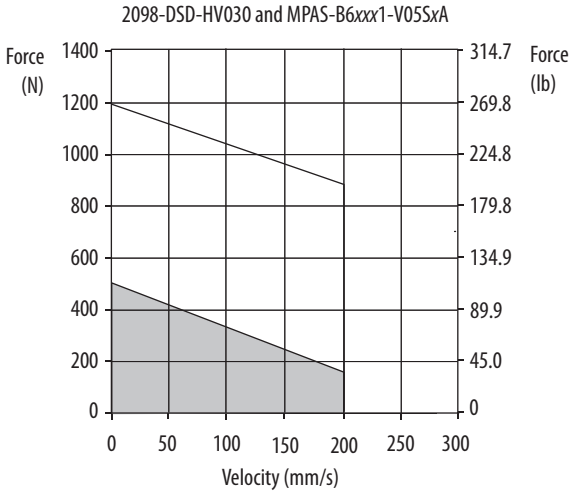
| Linear Stage | Speed, max mm/s (in/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Linear Stage Rated Output kW | Ultra3000 400V-class Drives |
|--------------------|----------------------------|-------------------------------------------------|--------------------------------------------|-------------------------------------------|--------------------------------------|------------------------------------|--------------------------------|
| MPAS-Bxxxx1-V05SxA | 200 (7.9) ⁽¹⁾ | 1.75 | 521 (117) | 3.50 | 1212 (272) | 0.138 | 2098-DSD-HV030 |
| MPAS-Bxxxx2-V20SxA | 1124 (44.3) ⁽²⁾ | 3.30 | 462 (104) | 6.60 | 968 (218) | 0.52 | 2098-DSD-HV030 |
| MPAS-B8xxxF-ALM02C | 5000 (200) | 3.50 | 189 (42.5) | 9.30 | 456 (103) | 0.527 | 2098-DSD-HV030 |
| MPAS-B8xxxF-ALMS2C | 5000 (200) | 3.15 | 159 (35.7) | 8.37 | 399 (89.7) | 0.475 | 2098-DSD-HV030 |
| MPAS-B9xxxL-ALM02C | 5000 (200) | 3.40 | 285 (64.1) | 9.10 | 680 (153) | 0.768 | 2098-DSD-HV030 |
| MPAS-B9xxxL-ALMS2C | 5000 (200) | 3.03 | 245 (55.1) | 8.19 | 601 (135) | 0.69 | 2098-DSD-HV030 |

(1) For 900 mm stroke length, maximum speed is 176 mm/s (6.9 in/s). For 1020 mm stroke length, maximum speed is 143 mm/s (5.6 in/s).

(2) For 780 mm stroke length, maximum speed is 889 mm/s (35.0 in/s). For 900 mm stroke length, maximum speed is 715 mm/s (28.2 in/s). For 1020 mm stroke length, maximum speed is 582 mm/s (22.9 in/s).

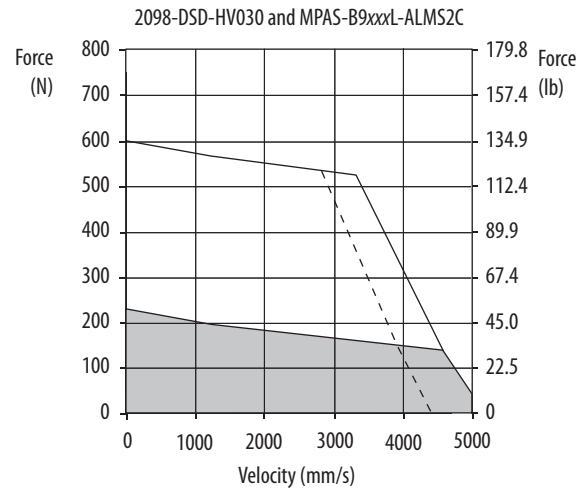
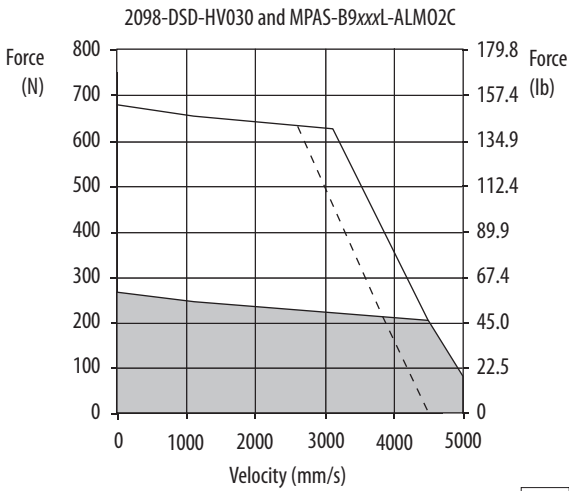
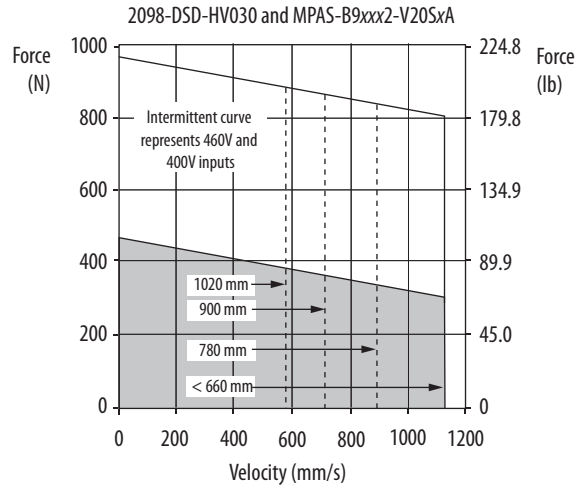
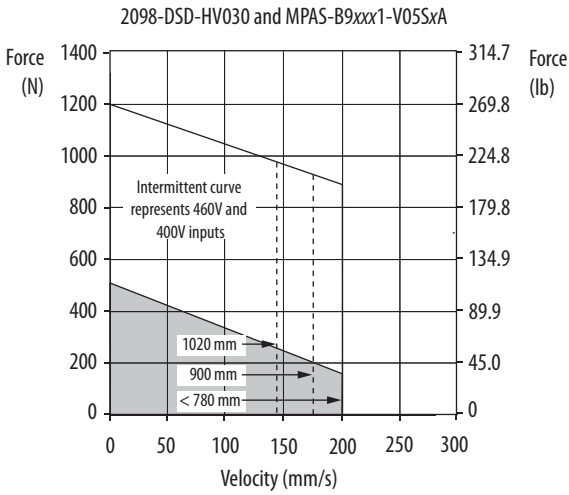
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (400V class) Drives/MP-Series Integrated Linear Stage Curves



- = Intermittent operating region
- = Continuous operating region
- = System operation with 400V AC (rms) input voltage
- = System operation for specified stroke length

Ultra3000 (400V class) Drives/MP-Series Integrated Linear Stage Curves (continued)



- = Intermittent operating region
- = Continuous operating region
- = System operation with 400V AC (rms) input voltage
- = System operation for specified stroke length

Ultra3000 Drives with MP-Series Electric Cylinders

This section provides system combination information for the Ultra3000 drives when matched with MP-Series electric cylinders. Included are power/brake and feedback cable catalog numbers, system performance specifications, and the optimum force/velocity curves.

Electric Cylinder Cable Combinations

| Electric Cylinders | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|------------------------------------------------------------------|-----------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MPAR-A/B1xxxB MPAR-A/B1xxxE MPAR-A/B2xxxC MPAR-A/B2xxxF | 2090-XXNPMF-16Sxx (standard, non-flex) 2090-CPxM4DF-16AFxx (continuous-flex) | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM4DF-CDAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPAR-A/B3xxxE MPAR-A/B3xxxH | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-CFBM7DF-CEAAxx or 2090-CFBM7DD-CEAAxx (standard, non-flex) 2090-CFBM7DF-CEAFxx or 2090-CFBM7DD-CEAFxx (continuous-flex) Absolute High-resolution Feedback |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) with flying-lead cables on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Electric Cylinder Performance Specifications with Ultra3000 Drives

Performance Specifications with Ultra3000 (200V class) Drives

| Electric Cylinder | Speed, max mm/s (in/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Rated Output kW | Ultra3000 200V-class Drives |
|-------------------|---------------------------|-------------------------------------------------|--------------------------------------------|-------------------------------------------|--------------------------------------|--------------------|--------------------------------|
| MPAR-A1xxxB | 150 | 1.15 | 240 (53.9) | 1.35 | 300 (67.4) | 0.036 | 2098-DSD-005 |
| MPAR-A1xxxE | 500 | 2.16 | 280 (62.9) | 2.48 | 350 (78.7) | 0.140 | |
| MPAR-A2xxxC | 250 | 2.42 | 420 (94.4) | 2.72 | 525 (118) | 0.105 | 2098-DSD-010 |
| MPAR-A2xxxF | 640 | 4.54 | 640 (144) | 5.41 | 800 (180) | 0.410 | |
| MPAR-A3xxxE | 500 | 10.33 | 2000 (450) | 12.34 | 2500 (562) | 1.00 | 2098-DSD-030 ⁽¹⁾ |
| MPAR-A3xxxH | 1000 | 12.20 | 1300 (292) | 16.40 | 1625 (365) | 1.30 | 2098-DSD-030 |

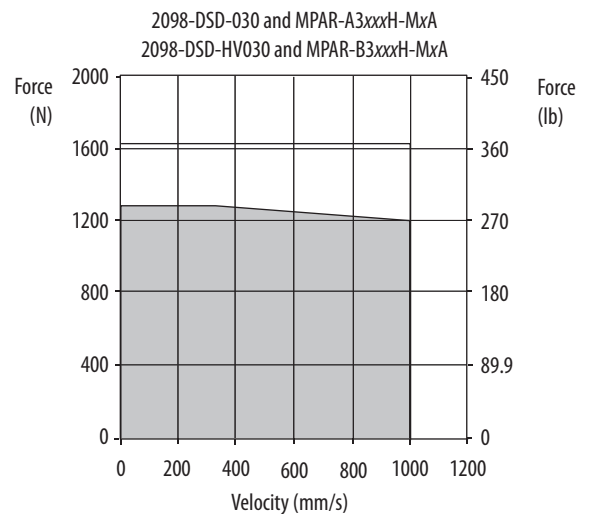
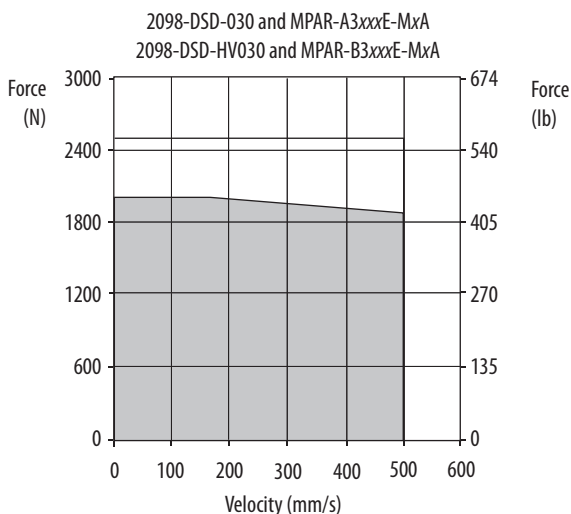
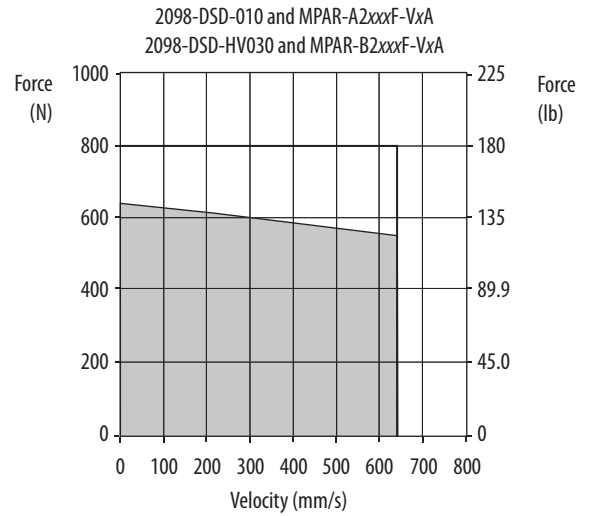
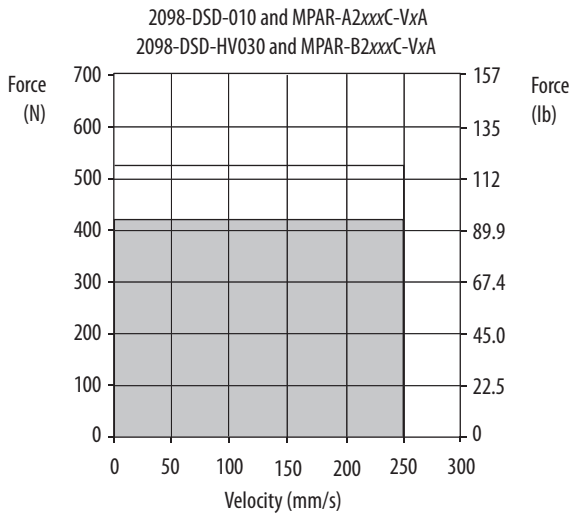
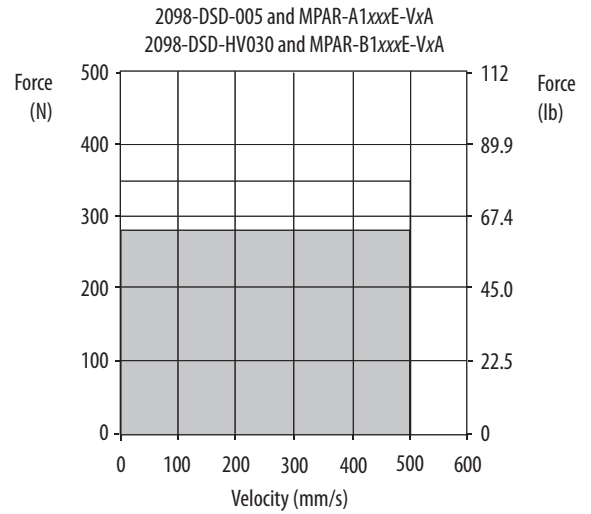
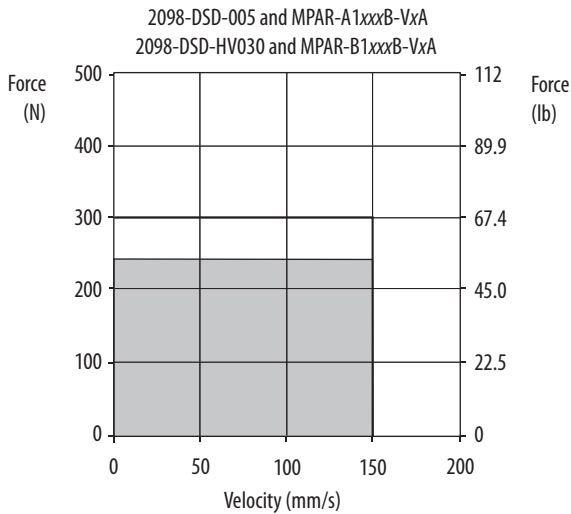
(1) Use of catalog number 2098-DSD020x-xx is acceptable for applications with actuators and continuous force derated by 5%.

Performance Specifications with Ultra3000 (400V class) Drives

| Electric Cylinder | Speed, max mm/s (in/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Rated Output kW | Ultra3000 400V-class Drives |
|-------------------|---------------------------|-------------------------------------------------|--------------------------------------------|-------------------------------------------|--------------------------------------|--------------------|--------------------------------|
| MPAR-B1xxxB | 150 | 1.15 | 240 (53.9) | 1.35 | 300 (67.4) | 0.036 | 2098-DSD-HV030 |
| MPAR-B1xxxE | 500 | 1.49 | 280 (62.9) | 1.71 | 350 (78.7) | 0.140 | |
| MPAR-B2xxxC | 250 | 1.67 | 420 (94.4) | 1.90 | 525 (118) | 0.105 | |
| MPAR-B2xxxF | 640 | 3.29 | 640 (144) | 3.93 | 800 (180) | 0.410 | |
| MPAR-B3xxxE | 500 | 5.16 | 2000 (450) | 6.17 | 2500 (562) | 1.00 | |
| MPAR-B3xxxH | 1000 | 6.13 | 1300 (292) | 6.79 | 1625 (365) | 1.30 | |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 Drives/MP-Series Electric Cylinder Curves



= Intermittent operating region
 = Continuous operating region

Ultra3000 Drives with MP-Series Heavy Duty Electric Cylinders

This section provides system combination information for the Ultra3000 drives when matched with MP-Series heavy-duty electric cylinders. Included are power/brake and feedback cable catalog numbers, system performance specifications, and the optimum force/velocity curves.

Electric Cylinder Cable Combinations

| Electric Cylinder | Motor Power/Brake Cable | Motor Feedback Cable ⁽¹⁾ |
|--------------------------------------------------------------|-----------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MPAI-A/B3xxxC, MPAI-A/B3xxxE MPAI-A/B3xxxR, MPAI-A/B3xxxS | 2090-CPWM7DF-16AAxx (standard, non-flex) 2090-CPWM7DF-16AFxx (continuous-flex) | 2090-CFBM7DF-CEAAxx or 2090-CFBM7DD-CEAAxx (standard, non-flex) 2090-CFBM7DF-CEAFxx or 2090-CFBM7DD-CEAFxx (continuous-flex) Absolute High-resolution Feedback |
| MPAI-A/B4xxxC, MPAI-A/B4xxxE MPAI-A/B4xxxR, MPAI-A/B4xxxS | | |
| MPAI-B5xxxC, MPAI-B5xxxE | | |
| MPAI-A5xxxC, MPAI-A5xxxE | 2090-CPWM7DF-14AAxx (standard, non-flex) 2090-CPWM7DF-14AFxx (continuous-flex) | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) with flying-lead cables on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

Electric Cylinder Performance Specifications with Ultra3000 (200V class) Drives

Performance Specifications with Ball Screw Electric Cylinders

| Electric Cylinder | Speed, max mm/s (in/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Rated Output kW | Ultra3000 200V-class Drives |
|-------------------|---------------------------|-------------------------------------------------|-----------------------------------------|----------------|-------------------------------------------|--------------------------------------|--------------------|--------------------------------|
| | | | 25 °C (77 °F) | 40 °C (104 °F) | | | | |
| MPAI-A3076CM1 | 305 (12) | 2.68 | 1624 (365) | 1290 (290) | 8.90 | 4448 (1000) | 0.27 | 2098-DSD-010 |
| MPAI-A3076EM1 | 610 (24) | | 814 (183) | 645 (145) | | 2570 (578) | | |
| MPAI-A3150CM3 | 279 (11) | 5.61 | 4003 (900) | 3176 (714) | 8.40 | 4448 (1000) | 0.39 | 2098-DSD-020 |
| MPAI-A3300CM3 | | | | | | | | |
| MPAI-A3450CM3 | 188 (7.3) | | | | | | | |
| MPAI-A3150EM3 | 559 (22) | | 2002 (450) | 1588 (357) | 14.14 | 4003 (900) | | |
| MPAI-A3300EM3 | | | | | | | | |
| MPAI-A3450EM3 | 376 (15) | | | | | | | |
| MPAI-A4150CM3 | 279 (11) | 10.89 | 7784 (1750) | 6179 (1389) | 17.07 | 8896 (2000) | 0.43 | 2098-DSD-030 |
| MPAI-A4300CM3 | | | | | | | | |
| MPAI-A4450CM3 | 245 (9.5) | | | | | | | |
| MPAI-A4150EM3 | 559 (22) | | 3892 (875) | 3092 (695) | 27.44 | 7784 (1750) | | |
| MPAI-A4300EM3 | | | | | | | | |
| MPAI-A4450EM3 | 491 (19) | | | | | | | |
| MPAI-A5xxxCM3 | 200 (7.8) | 13.25 | 13,123 (2950) | 10,415 (2341) | 16.70 | 13,345 (3000) | 0.55 | 2098-DSD-075 |
| MPAI-A5xxxEM3 | 400 (15.6) | | 6562 (1475) | 5208 (1171) | 33.40 | 13,122 (2950) | | |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Performance Specifications with Roller Screw Electric Cylinders

| Electric Cylinder | Speed, max mm/s (in/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Rated Output kW | Ultra3000 200V-class Drives |
|-------------------|---------------------------|-------------------------------------------------|-----------------------------------------|----------------|-------------------------------------------|--------------------------------------|--------------------|--------------------------------|
| | | | 25 °C (77 °F) | 40 °C (104 °F) | | | | |
| MPAI-A3076RM1 | 305 (12) | 2.87 | 1557 (350) | 1237 (278) | 8.90 | 4862 (1093) | 0.27 | 2098-DSD-010 |
| MPAI-A3076SM1 | 610 (24) | | 778 (175) | 618 (139) | | 2431 (547) | | |
| MPAI-A3150RM3 | 279 (11) | 5.61 | 3781 (850) | 3003 (675) | 14.14 | 7562 (1700) | 0.39 | 2098-DSD-020 |
| MPAI-A3300RM3 | | | | | | | | |
| MPAI-A3450RM3 | 176 (6.9) | | | | | | | |
| MPAI-A3150SM3 | 559 (22) | | 1891 (425) | 1499 (337) | | 3781 (850) | | |
| MPAI-A3300SM3 | | | | | | | | |
| MPAI-A3450SM3 | 353 (14) | | | | | | | |
| MPAI-A4150RM3 | 279 (11) | 10.89 | 7340 (1650) | 5827 (1310) | 27.44 | 14,679 (3300) | 0.43 | 2098-DSD-030 |
| MPAI-A4300RM3 | | | | | | | | |
| MPAI-A4450RM3 | 196 (7.6) | | | | | | | |
| MPAI-A4150SM3 | 559 (22) | | 3670 (825) | 2914 (655) | | 7340 (1650) | | |
| MPAI-A4300SM3 | | | | | | | | |
| MPAI-A4450SM3 | 393 (15) | | | | | | | |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Electric Cylinder Performance Specifications with Ultra3000 (400V class) Drives

Performance Specifications with Ball Screw Electric Cylinders

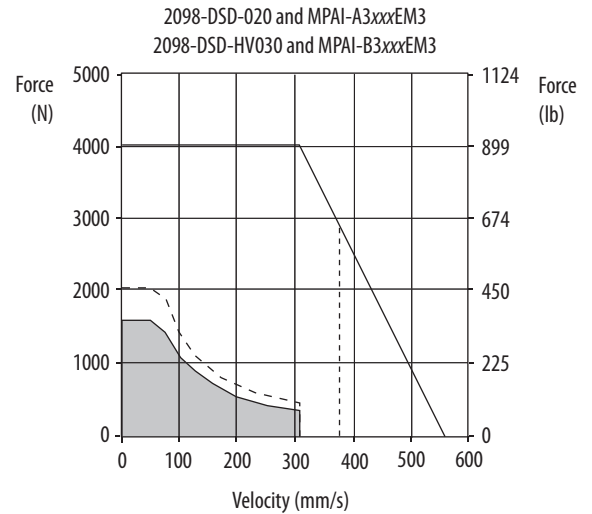
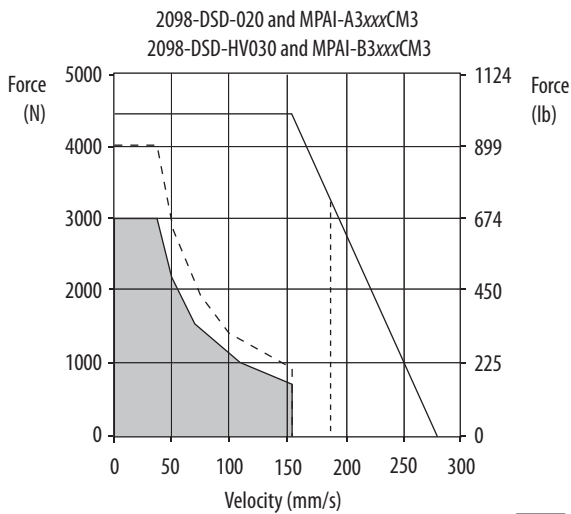
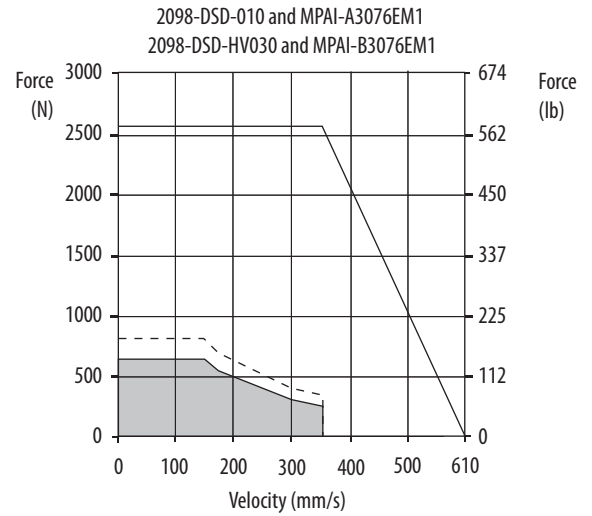
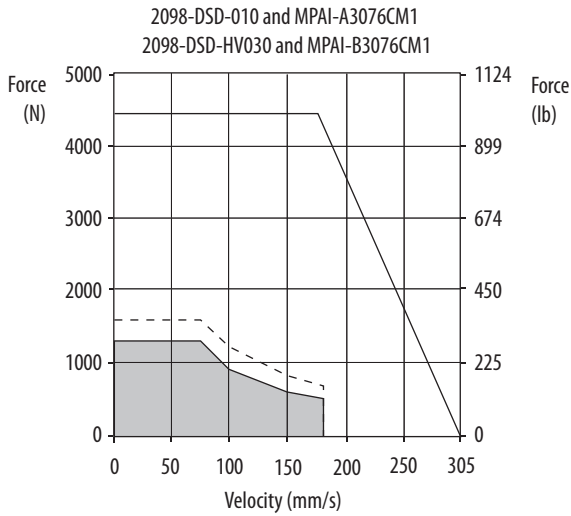
| Electric Cylinder | Speed, max mm/s (in/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Rated Output kW | Ultra3000 400V-class Drives |
|-------------------|---------------------------|-------------------------------------------------|-----------------------------------------|----------------|-------------------------------------------|--------------------------------------|--------------------|--------------------------------|
| | | | 25 °C (77 °F) | 40 °C (104 °F) | | | | |
| MPAI-B3076CM1 | 305 (12) | 1.35 | 1624 (365) | 1290 (290) | 4.57 | 4448 (1000) | 0.27 | 2098-DSD-HV030 |
| MPAI-B3076EM1 | 610 (24) | | 814 (183) | 645 (145) | | 2570 (578) | | |
| MPAI-B3150CM3 | 279 (11) | 2.81 | 4003 (900) | 3176 (714) | 4.30 | 4448 (1000) | 0.39 | 2098-DSD-HV030 |
| MPAI-B3300CM3 | | | | | | | | |
| MPAI-B3450CM3 | 188 (7.3) | | | | | | | |
| MPAI-B3150EM3 | 559 (22) | | 2002 (450) | 1588 (357) | 7.07 | 4003 (900) | | |
| MPAI-B3300EM3 | | | | | | | | |
| MPAI-B3450EM3 | | | 376 (15) | | | | | |
| MPAI-B4150CM3 | 279 (11) | 5.61 | 7784 (1750) | 6179 (1389) | 8.68 | 8896 (2000) | 0.43 | 2098-DSD-HV030 |
| MPAI-B4300CM3 | | | | | | | | |
| MPAI-B4450CM3 | 245 (9.5) | | | | | | | |
| MPAI-B4150EM3 | 559 (22) | | 3892 (875) | 3092 (695) | 14.14 | 7784 (1750) | | |
| MPAI-B4300EM3 | | | | | | | | |
| MPAI-B4450EM3 | | | 491 (19) | | | | | |
| MPAI-B5xxxCM3 | 200 (7.8) | 6.62 | 13,123 (2950) | 10,415 (2341) | 8.48 | 13,345 (3000) | 0.55 | 2098-DSD-HV050 |
| MPAI-B5xxxEM3 | 400 (15.6) | | 6562 (1475) | 5208 (1171) | 16.70 | 13,122 (2950) | | |

Performance Specifications with Roller Screw Electric Cylinders

| Electric Cylinder | Speed, max mm/s (in/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Rated Output kW | Ultra3000 400V-class Drives |
|-------------------|---------------------------|-------------------------------------------------|-----------------------------------------|----------------|-------------------------------------------|--------------------------------------|--------------------|--------------------------------|
| | | | 25 °C (77 °F) | 40 °C (104 °F) | | | | |
| MPAI-B3076RM1 | 305 (12) | 1.45 | 1557 (350) | 1237 (278) | 4.57 | 4862 (1093) | 0.27 | 2098-DSD-HV030 |
| MPAI-B3076SM1 | 610 (24) | | 778 (175) | 618 (139) | | 2431 (547) | | |
| MPAI-B3150RM3 | 279 (11) | 2.81 | 3781 (850) | 3003 (675) | 7.07 | 7562 (1700) | 0.39 | 2098-DSD-HV030 |
| MPAI-B3300RM3 | | | | | | | | |
| MPAI-B3450RM3 | 176 (6.9) | | | | | | | |
| MPAI-B3150SM3 | 559 (22) | | 1891 (425) | 1499 (337) | 3781 (850) | | | |
| MPAI-B3300SM3 | | | | | | | | |
| MPAI-B3450SM3 | | | 353 (14) | | | | | |
| MPAI-B4150RM3 | 279 (11) | 5.61 | 7340 (1650) | 5827 (1310) | 14.14 | 14,679 (3300) | 0.43 | 2098-DSD-HV030 |
| MPAI-B4300RM3 | | | | | | | | |
| MPAI-B4450RM3 | 196 (7.6) | | | | | | | |
| MPAI-B4150SM3 | 559 (22) | | 3670 (825) | 2914 (655) | 7340 (1650) | | | |
| MPAI-B4300SM3 | | | | | | | | |
| MPAI-B4450SM3 | | | 393 (15) | | | | | |

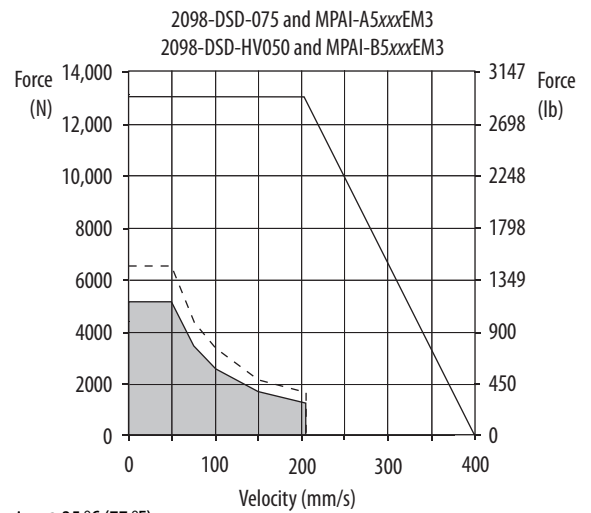
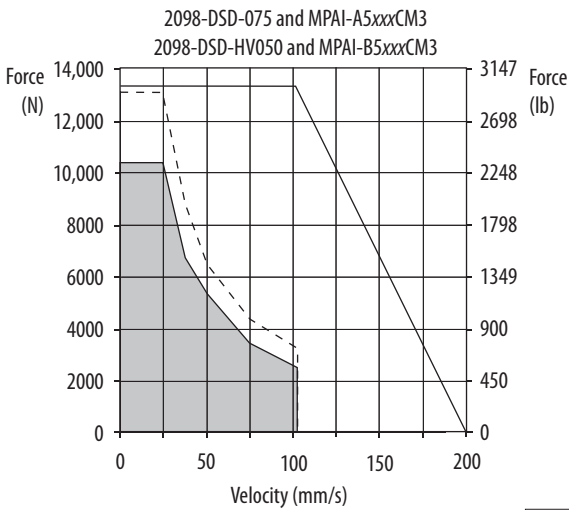
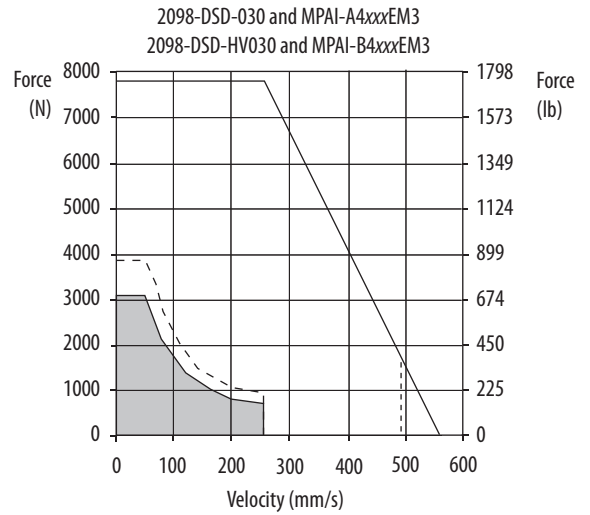
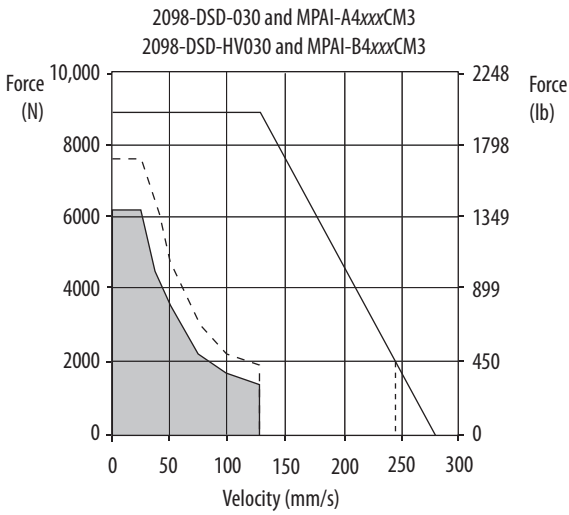
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 Drives/MP-Series Heavy Duty (ball screw) Electric Cylinder Curves



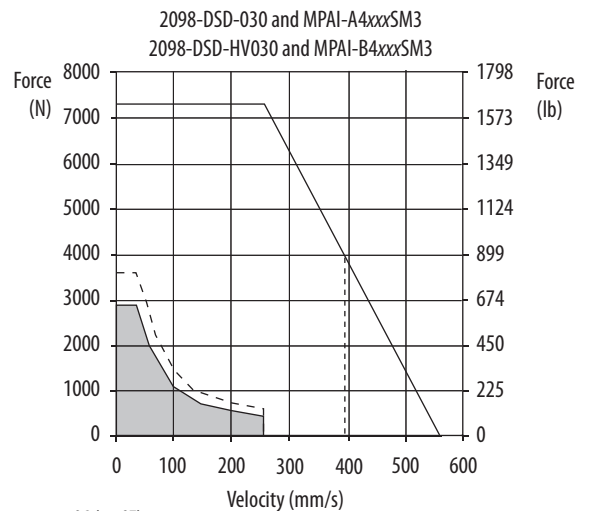
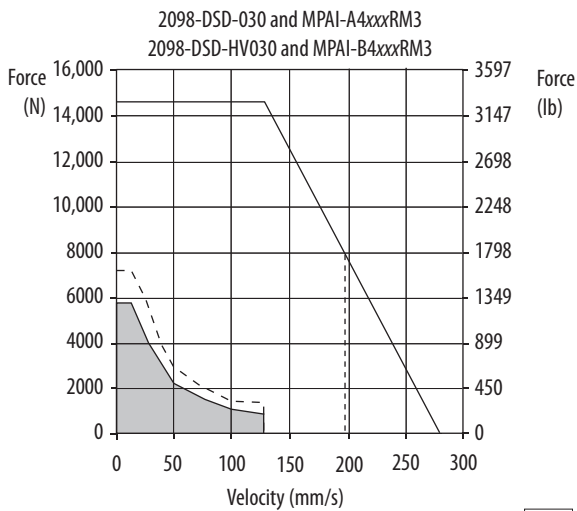
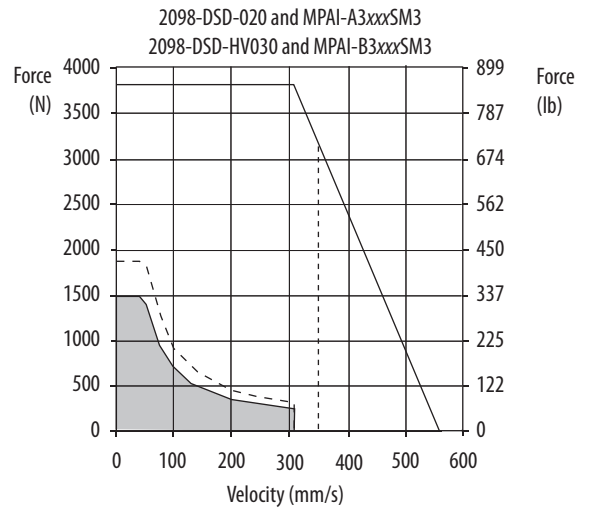
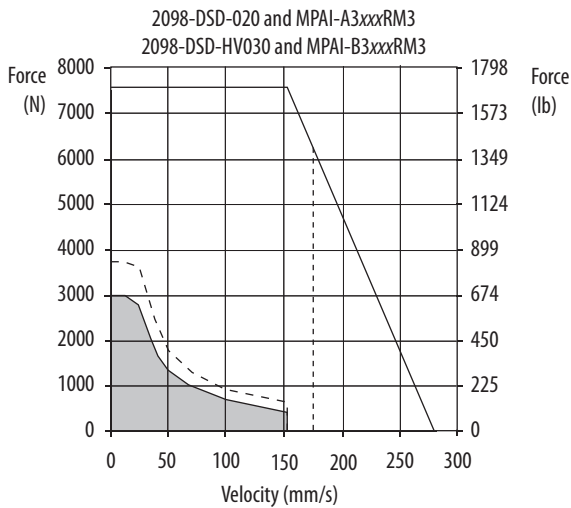
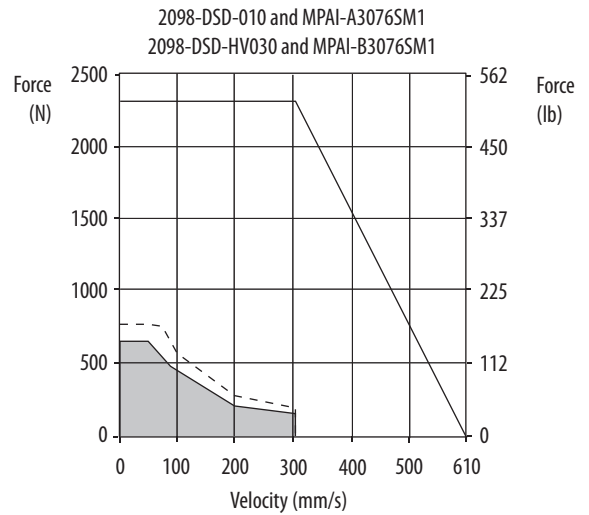
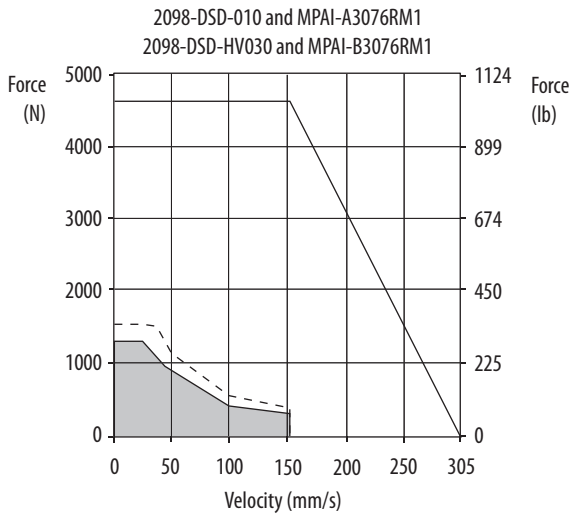
- = Continuous operating region @ 25 °C (77 °F)
- = Continuous operating region @ 40 °C (104 °F)
- = Intermittent operating region, 450 mm (18 in.) stroke length only
- = Intermittent operating region, 076 . . . 300 mm (3 . . . 12 in.) stroke lengths

Ultra3000 Drives/MP-Series Heavy Duty (ball screw) Electric Cylinder Curves (continued)



- = Continuous operating region @ 25 °C (77 °F)
- = Continuous operating region @ 40 °C (104 °F)
- = Intermittent operating region, 450 mm (18 in.) stroke length only
- = Intermittent operating region, 076...300 mm (3...12 in.) stroke lengths

Ultra3000 Drives/MP-Series Heavy Duty (roller screw) Electric Cylinder Curves



- = Continuous operating region @ 25 °C (77 °F)
- █ = Continuous operating region @ 40 °C (104 °F)
- - - = Intermittent operating region, 450 mm (18 in.) stroke length only
- = Intermittent operating region, 076...300 mm (3...12 in.) stroke lengths

Ultra3000 (200V class) Drives with LDC-Series Linear Motors

This section provides system combination information for the Ultra3000 (200V class) drives when matched with LDC-Series™ iron-core linear motors. Included are power and feedback cable catalog numbers, system performance specifications, and the optimum force/velocity curves.

Linear Motor Cable Combinations

| Linear Motor | Motor Power Cable | Motor Feedback Cable ⁽¹⁾ |
|------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------|
| LDC-C030100-DHT, LDC-C030200-DHT, LDC-C030200-EHT | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM7DF-CDAFxx (continuous-flex) Sin/Cos or TTL Encoder Feedback |
| LDC-C050100-DHT, LDC-C050200-DHT, LDC-C050200-EHT, LDC-C050300-DHT, LDC-C050300-EHT | | |
| LDC-C075200-DHT, LDC-C075200-EHT, LDC-C075300-DHT, LDC-C075300-EHT, LDC-C075400-DHT, LDC-C075400-EHT | | |
| LDC-C100300-DHT, LDC-C100300-EHT, LDC-C100400-DHT, LDC-C100400-EHT, LDC-C100600-DHT | | |
| LDC-C150400-DHT, LDC-C150600-DHT | | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

LDC-Series Performance Specifications with Ultra3000 (200V class) Drives

| Linear Motor | Speed, max m/s (ft/s) | System Continuous Stall Current ⁽¹⁾ Amps 0-pk | System Continuous Stall Force ⁽¹⁾ N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Linear Motor Rated Output kW | Ultra3000 200V-class Drives |
|-----------------|--------------------------|----------------------------------------------------------------|-----------------------------------------------------------|-------------------------------------------|--------------------------------------|------------------------------------|--------------------------------|
| LDC-C030100-DHT | 10.0 (32.8) | 4.1...6.1 | 74...111 (17...25) | 12.1 | 188 (42) | 0.37...0.55 | 2098-DSD-010 |
| LDC-C030200-DHT | | 8.1...12.2 | 148...222 (33...50) | 24.3 | 375 (84) | 0.74...1.11 | 2098-DSD-020 |
| LDC-C030200-EHT | | 4.1...6.1 | | 12.1 | | | 2098-DSD-010 |
| LDC-C050100-DHT | 10.0 (32.8) | 3.9...5.9 | 119...179 (27...40) | 11.7 | 302 (68) | 0.59...0.89 | 2098-DSD-010 |
| LDC-C050200-DHT | | 7.9...11.8 | 240...359 (54...81) | 23.3 | 600 (135) | 1.20...1.79 | 2098-DSD-020 |
| LDC-C050200-EHT | | 3.9...5.9 | | 11.6 | | | 2098-DSD-010 |
| LDC-C050300-DHT | | 11.8...17.7 | 363...544 (82...122) | 35.9 | 941 (212) | 1.81...2.72 | 2098-DSD-075 |
| LDC-C050300-EHT | | 3.9...5.9 | 12.0 | 2098-DSD-010 | | | |

(1) Values represent the range between no cooling (low value) and water cooling (high value).

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

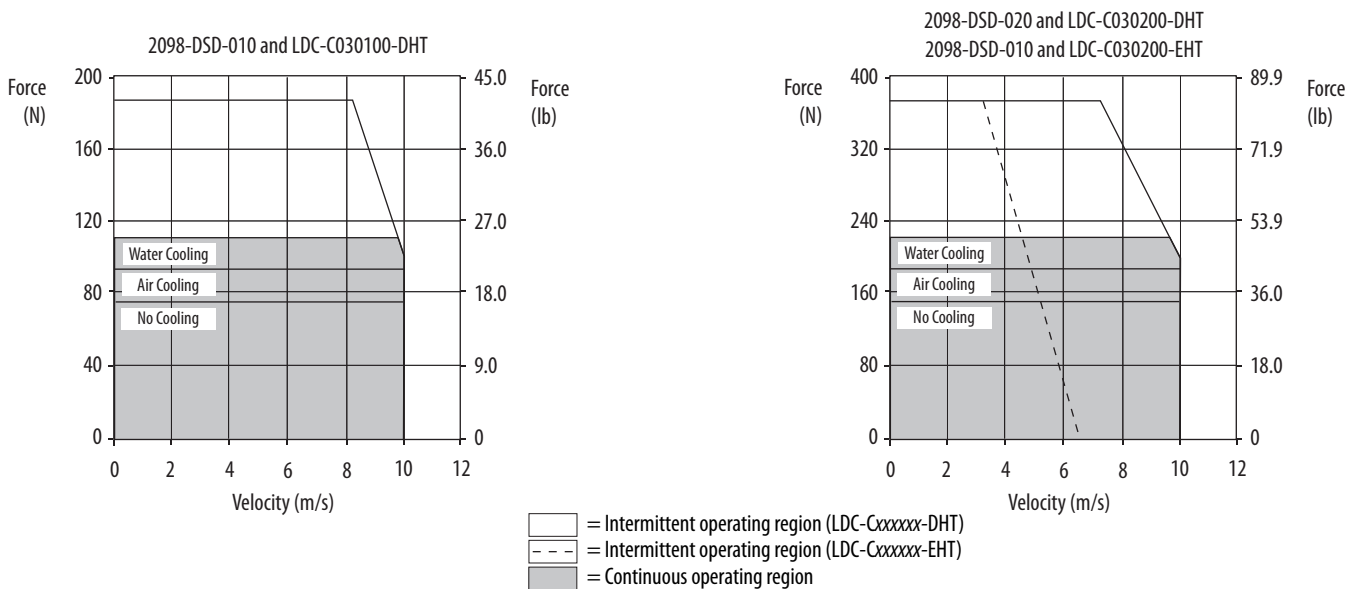
LDC-Series Performance Specifications with Ultra3000 (200V class) Drives (continued)

| Linear Motor | Speed, max m/s (ft/s) | System Continuous Stall Current ⁽¹⁾ Amps 0-pk | System Continuous Stall Force ⁽¹⁾ N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Linear Motor Rated Output kW | Ultra3000 200V-class Drives |
|-----------------|--------------------------|----------------------------------------------------------------|-----------------------------------------------------------|-------------------------------------------|--------------------------------------|------------------------------------|--------------------------------|
| LDC-C075200-DHT | 10.0 (32.8) | 7.7...11.5 | 348...523 | 22.9 | 882 (198) | 1.74...2.61 | 2098-DSD-020 |
| LDC-C075200-EHT | | 3.8...5.7 | (78...117) | 11.5 | | | 2098-DSD-010 |
| LDC-C075300-DHT | | 11.5...17.2 | 523...784 | 35.6 | 1368 (308) | 2.61...3.92 | 2098-DSD-075 |
| LDC-C075300-EHT | | 3.8...5.7 | (117...176) | 11.9 | | | 2098-DSD-010 |
| LDC-C075400-DHT | | 15.3...23.0 | 697...1045 | 47.4 | 1824 (410) | 3.48...5.22 | 2098-DSD-075 |
| LDC-C075400-EHT | | 7.7...11.5 | (157...235) | 23.7 | | | 2098-DSD-020 |
| LDC-C100300-DHT | 10.0 (32.8) | 11.1...16.7 | 674...1012 | 34.3 | 1767 (397) | 3.37...5.06 | 2098-DSD-075 |
| LDC-C100300-EHT | | 3.7...5.6 | (152...227) | 11.4 | | | 2098-DSD-010 |
| LDC-C100400-DHT | | 14.8...22.2 | 899...1349 | 45.7 | 2356 (530) | 4.49...6.74 | 2098-DSD-075 |
| LDC-C100400-EHT | | 7.4...11.1 | (202...303) | 22.8 | | | 2098-DSD-020 |
| LDC-C100600-DHT | | 22.2...33.3 | 1349...2023 | 68.5 | 3534 (794) | 6.74...10.11 | 2098-DSD-075 |
| LDC-C150400-DHT | | 10.0 (32.8) | 14.1...21.1 | 1281...1922 | 45.2 | 3498 (786) | 6.40...9.61 |
| LDC-C150600-DHT | 21.1...31.7 | | 1922...2882 | 67.8 | 5246 (1179) | 9.61...14.41 | 2098-DSD-075 |

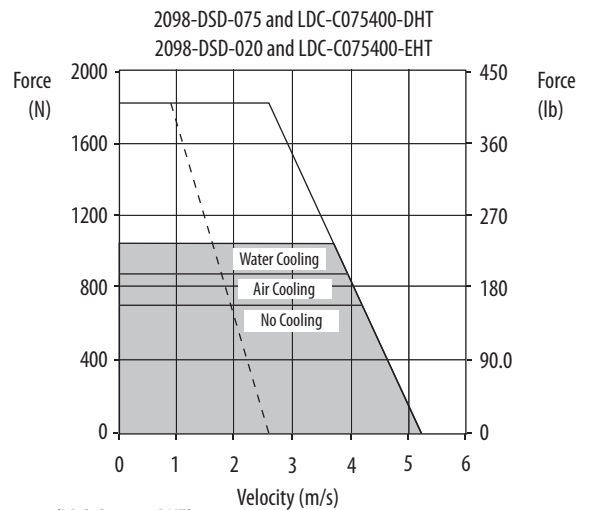
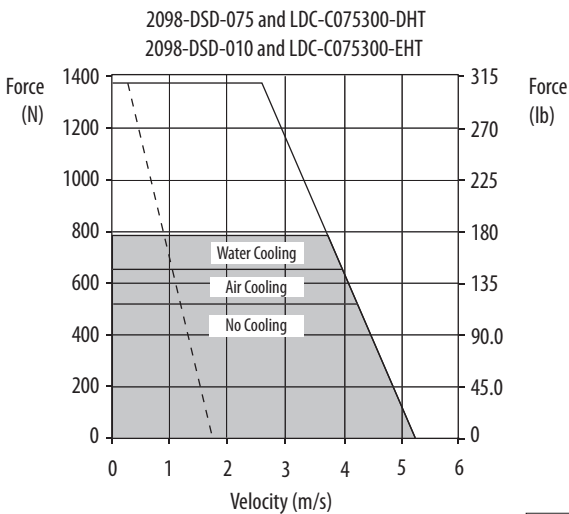
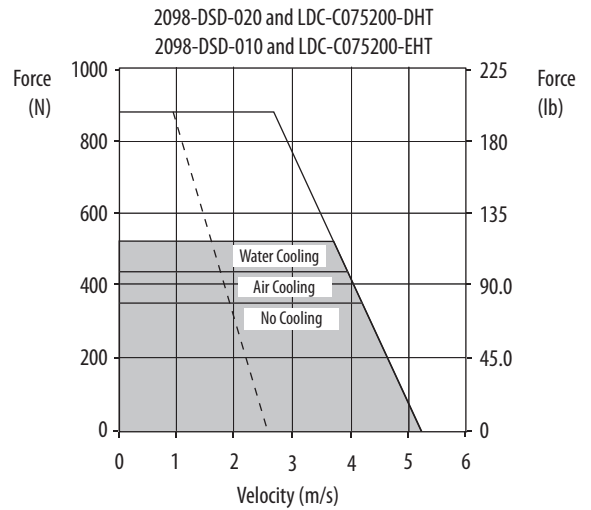
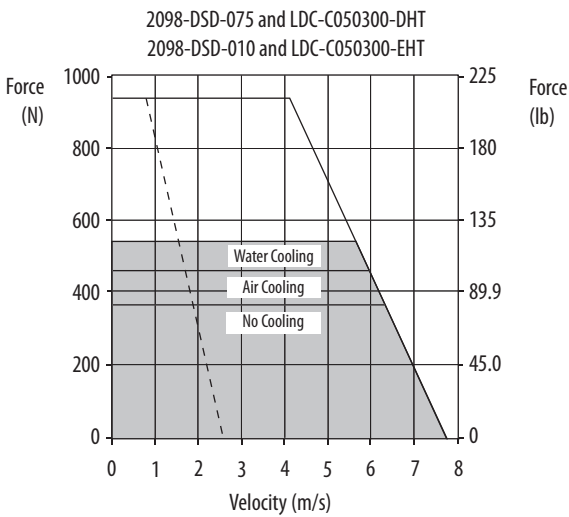
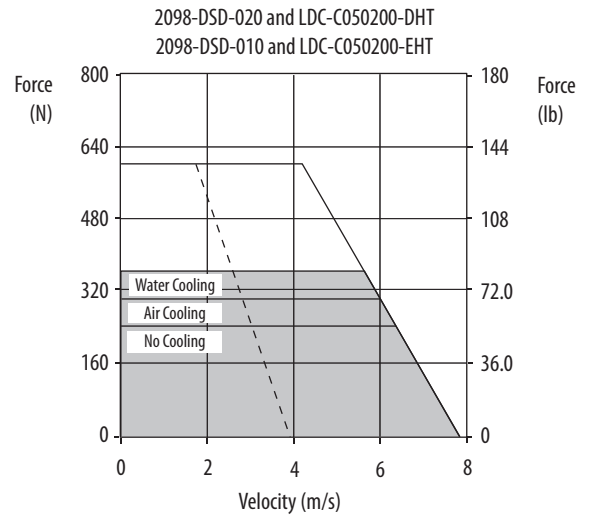
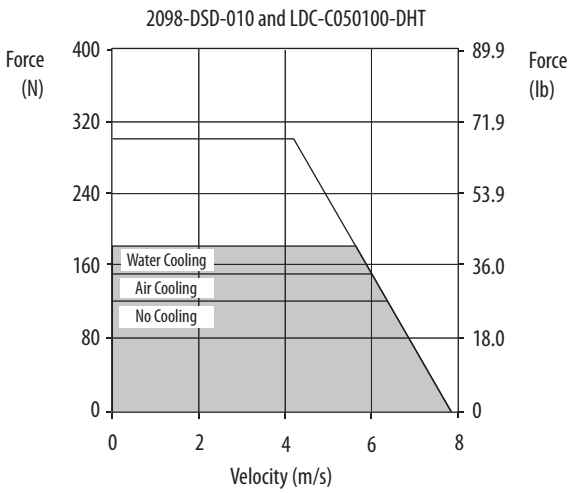
(1) Values represent the range between no cooling (low value) and water cooling (high value).

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (200V class) Drives/LDC-Series Linear Motor Curves

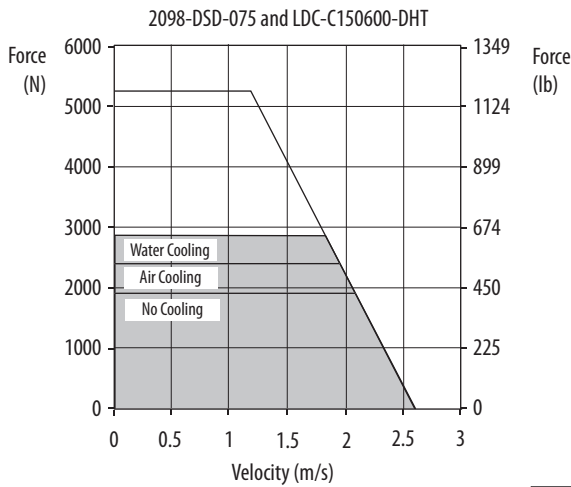
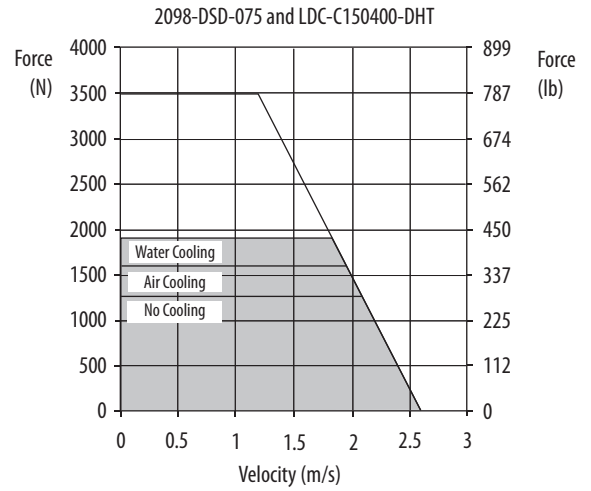
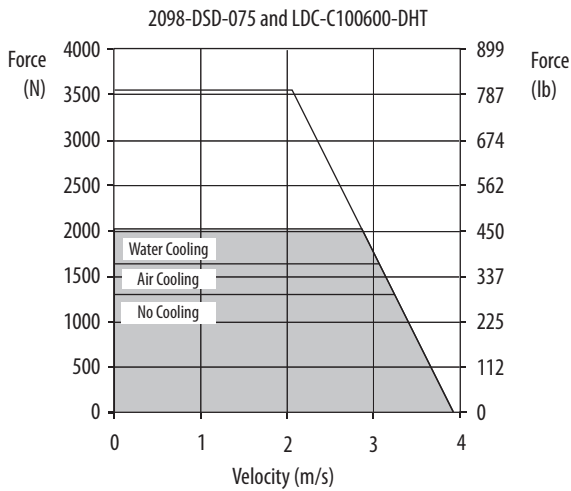
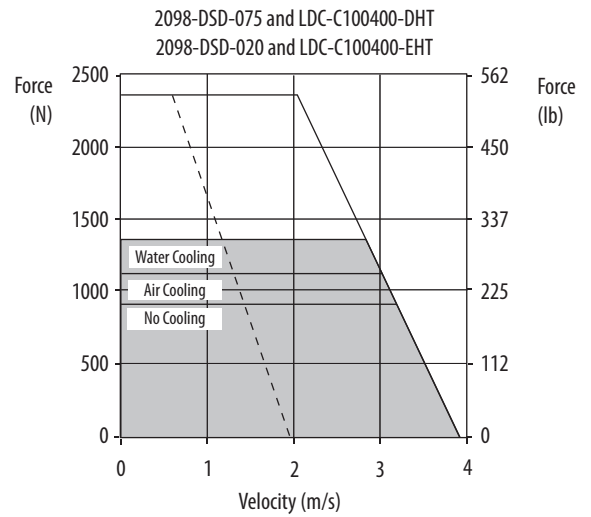
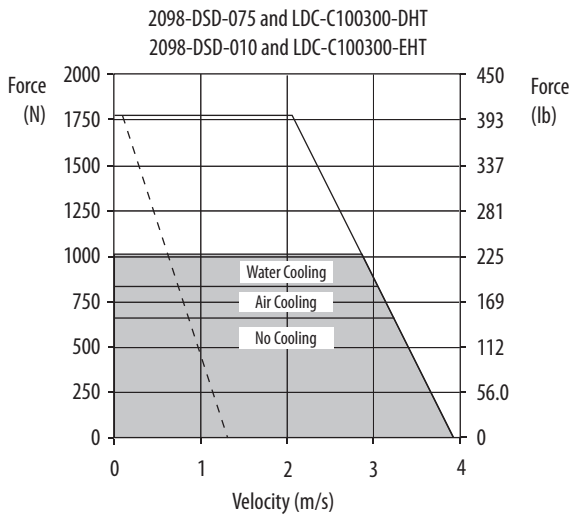


Ultra3000 (200V class) Drives/LDC-Series Linear Motor Curves (continued)



- = Intermittent operating region (LDC-Cxxxxx-DHT)
- = Intermittent operating region (LDC-Cxxxxx-EHT)
- = Continuous operating region

Ultra3000 (200V class) Drives/LDC-Series Linear Motor Curves (continued)



- = Intermittent operating region (LDC-Cxxxxx-DHT)
- = Intermittent operating region (LDC-Cxxxxx-EHT)
- = Continuous operating region

Ultra3000 (400V class) Drives with LDC-Series Linear Motors

This section provides system combination information for the Ultra3000 (400V class) drives when matched with LDC-Series iron-core linear motors. Included are power and feedback cable catalog numbers, system performance specifications, and the optimum force/velocity curves.

Linear Motor Cable Combinations

| Linear Motor | Motor Power Cable | Motor Feedback Cable ⁽¹⁾ |
|------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------|
| LDC-C030100-DHT, LDC-C030200-DHT, LDC-C030200-EHT | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM7DF-CDAFxx (continuous-flex) Sin/Cos or TTL Encoder Feedback |
| LDC-C050100-DHT, LDC-C050200-DHT, LDC-C050200-EHT, LDC-C050300-DHT, LDC-C050300-EHT | | |
| LDC-C075200-DHT, LDC-C075200-EHT, LDC-C075300-DHT, LDC-C075300-EHT, LDC-C075400-DHT, LDC-C075400-EHT | | |
| LDC-C100300-DHT, LDC-C100300-EHT, LDC-C100400-DHT, LDC-C100400-EHT, LDC-C100600-DHT | | |
| LDC-C150400-DHT, LDC-C150600-DHT | | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

LDC-Series Performance Specifications with Ultra3000 (400V class) Drives

| Linear Motor | Speed, max m/s (ft/s) | System Continuous Stall Current ⁽¹⁾ Amps 0-pk | System Continuous Stall Force ⁽¹⁾ N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Linear Motor Rated Output kW | Ultra3000 400V-class Drives |
|-----------------|--------------------------|----------------------------------------------------------------|-----------------------------------------------------------|-------------------------------------------|--------------------------------------|------------------------------------|--------------------------------|
| LDC-C030100-DHT | 10.0 (32.8) | 4.1...6.1 | 74...111 (17...25) | 12.1 | 188 (42) | 0.37...0.55 | 2098-DSD-HV030 |
| LDC-C030200-DHT | | 8.1...12.2 | 148...222 (33...50) | 24.3 | 375 (84) | 0.74...1.11 | 2098-DSD-HV100 |
| LDC-C030200-EHT | | 4.1...6.1 | | 12.1 | | | 2098-DSD-HV030 |
| LDC-C050100-DHT | 10.0 (32.8) | 3.9...5.9 | 119...179 (27...40) | 11.7 | 302 (68) | 0.59...0.89 | 2098-DSD-HV030 |
| LDC-C050200-DHT | | 7.9...11.8 | 240...359 (54...81) | 23.3 | 600 (135) | 1.20...1.79 | 2098-DSD-HV100 |
| LDC-C050200-EHT | | 3.9...5.9 | | 11.6 | | | 2098-DSD-HV030 |
| LDC-C050300-DHT | | 11.8...17.7 | 363...544 (82...122) | 35.9 | 941 (212) | 1.81...2.72 | 2098-DSD-HV100 |
| LDC-C050300-EHT | | 3.9...5.9 | | 12.0 | | | 2098-DSD-HV030 |

(1) Values represent the range between no cooling (low value) and water cooling (high value).

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

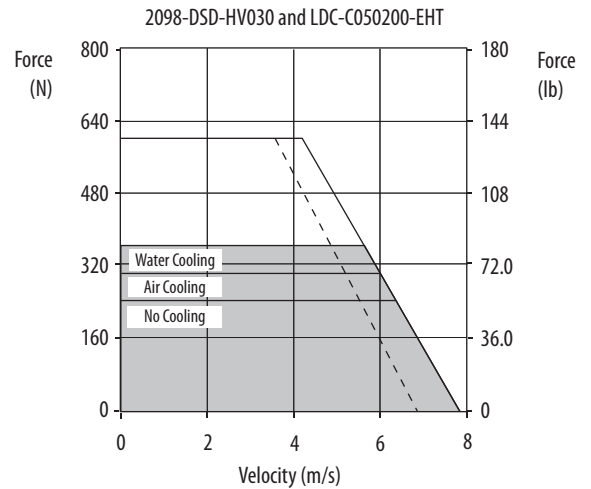
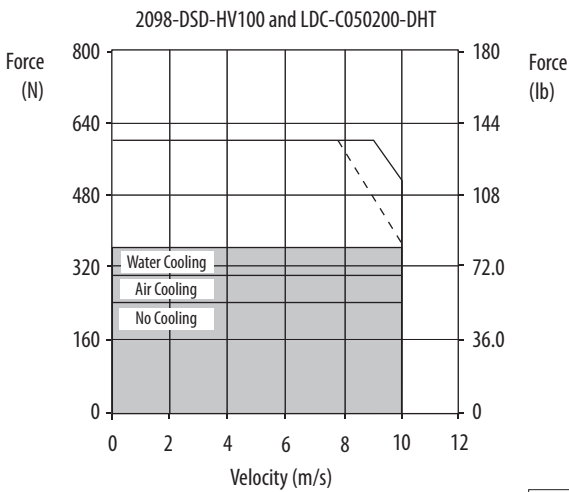
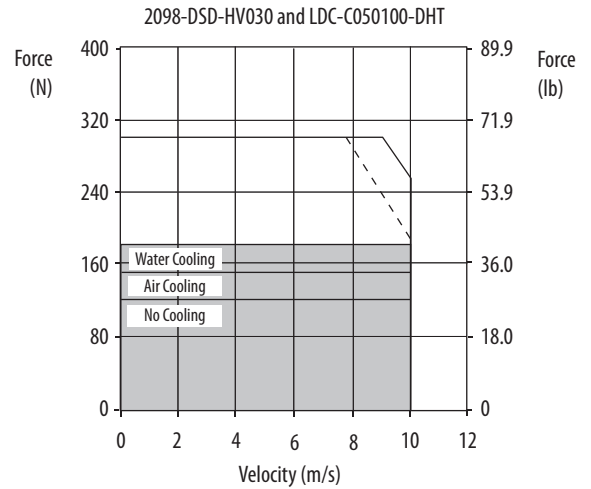
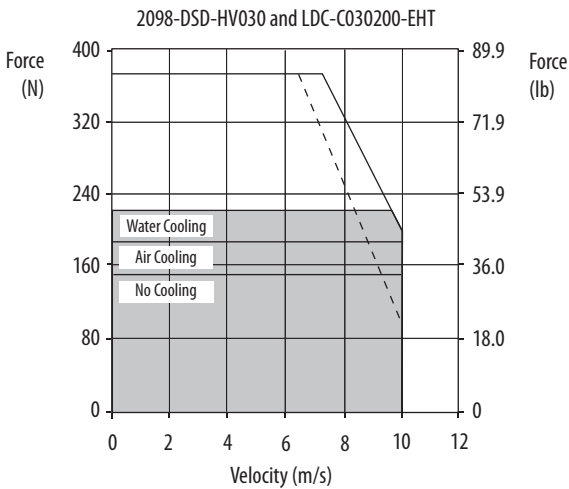
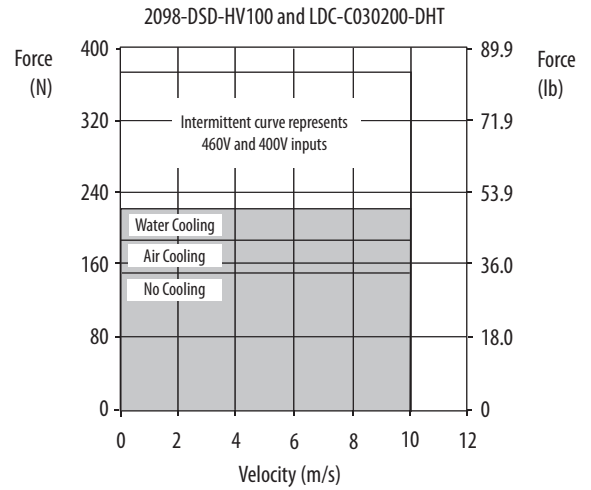
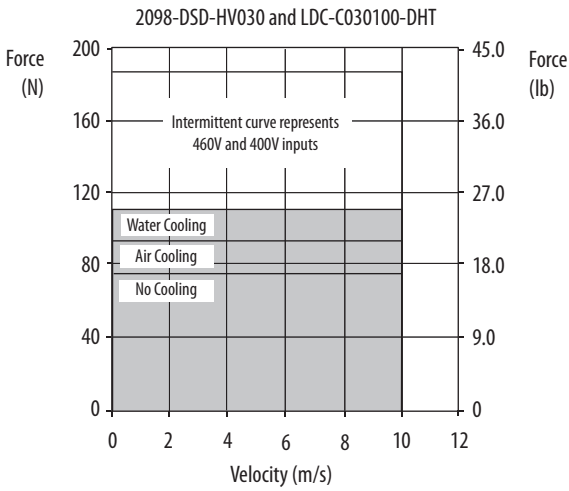
LDC-Series Performance Specifications with Ultra3000 (400V class) Drives (continued)

| Linear Motor | Speed, max m/s (ft/s) | System Continuous Stall Current ⁽¹⁾ Amps 0-pk | System Continuous Stall Force ⁽¹⁾ N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Linear Motor Rated Output kW | Ultra3000 400V-class Drives |
|-----------------|--------------------------|----------------------------------------------------------------|-----------------------------------------------------------|-------------------------------------------|--------------------------------------|------------------------------------|--------------------------------|
| LDC-C075200-DHT | 10.0 (32.8) | 7.7...11.5 | 348...523 (78...117) | 22.9 | 882 (198) | 1.74...2.61 | 2098-DSD-HV100 |
| LDC-C075200-EHT | | 3.8...5.7 | | 11.5 | | | 2098-DSD-HV030 |
| LDC-C075300-DHT | | 11.5...17.2 | 523...784 (117...176) | 35.6 | 1368 (308) | 2.61...3.92 | 2098-DSD-HV100 |
| LDC-C075300-EHT | | 3.8...5.7 | | 11.9 | | | 2098-DSD-HV030 |
| LDC-C075400-DHT | | 15.3...23.0 | 697...1045 (157...235) | 47.4 | 1824 (410) | 3.48...5.22 | 2098-DSD-HV150 |
| LDC-C075400-EHT | | 7.7...11.5 | | 23.7 | | | 2098-DSD-HV100 |
| LDC-C100300-DHT | 10.0 (32.8) | 11.1...16.7 | 674...1012 (152...227) | 34.3 | 1767 (397) | 3.37...5.06 | 2098-DSD-HV100 |
| LDC-C100300-EHT | | 3.7...5.6 | | 11.4 | | | 2098-DSD-HV030 |
| LDC-C100400-DHT | | 14.8...22.2 | 899...1349 (202...303) | 45.7 | 2356 (530) | 4.49...6.74 | 2098-DSD-HV150 |
| LDC-C100400-EHT | | 7.4...11.1 | | 22.8 | | | 2098-DSD-HV100 |
| LDC-C100600-DHT | | 22.2...33.3 | 1349...2023 (303...455) | 68.5 | 3534 (794) | 6.74...10.11 | 2098-DSD-HV220 |
| LDC-C100600-EHT | | 11.1...16.7 | | 34.3 | | | 2098-DSD-HV100 |
| LDC-C150400-DHT | 10.0 (32.8) | 14.1...21.1 | 1281...1922 (288...432) | 45.2 | 3498 (786) | 6.40...9.61 | 2098-DSD-HV150 |
| LDC-C150400-EHT | | 7.0...10.6 | | 22.6 | | | 2098-DSD-HV100 |
| LDC-C150600-DHT | | 21.1...31.7 | 1922...2882 (432...648) | 67.8 | 5246 (1179) | 9.61...14.41 | 2098-DSD-HV220 |
| LDC-C150600-EHT | | 10.6...15.8 | | 33.9 | | | 2098-DSD-HV100 |

(1) Values represent the range between no cooling (low value) and water cooling (high value).

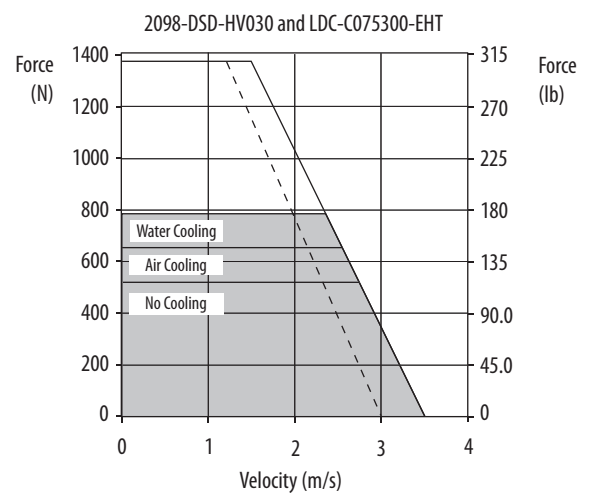
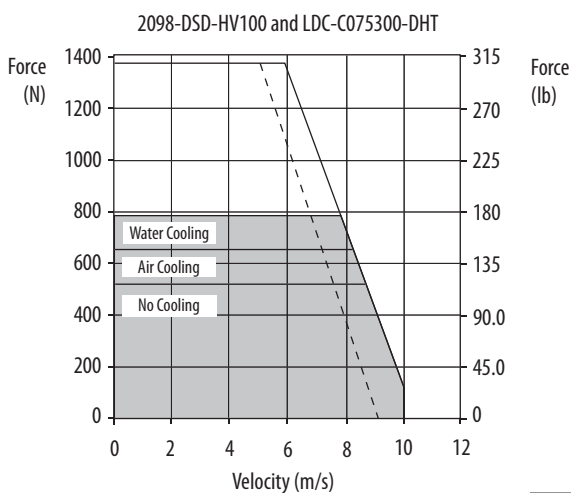
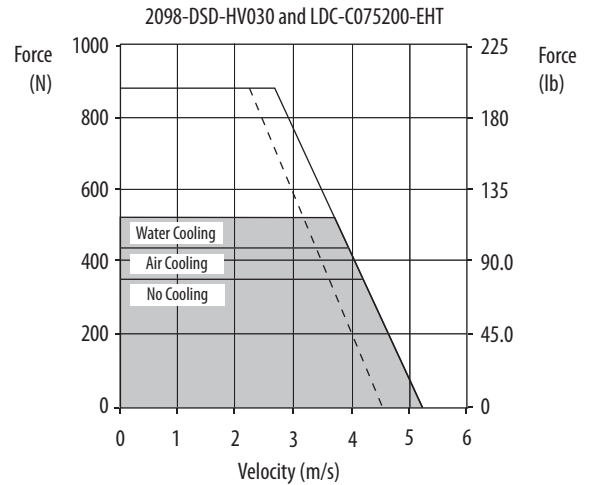
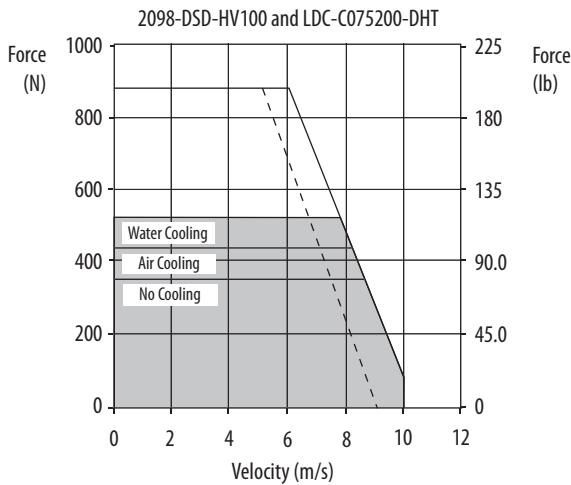
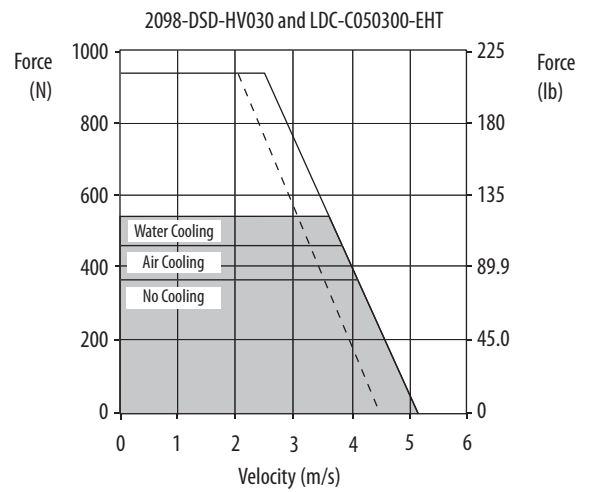
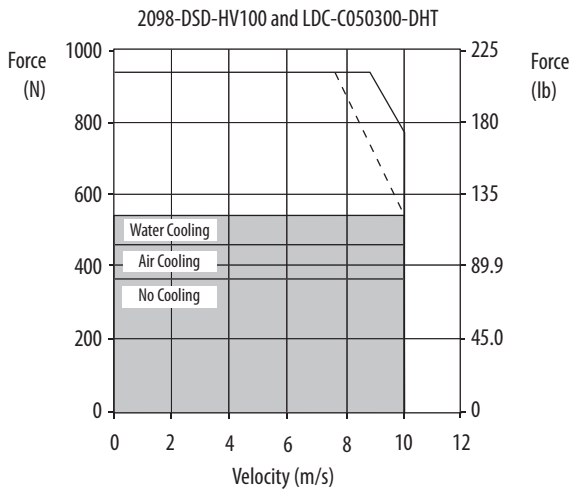
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (400V class) Drives/LDC-Series Linear Motor Curves



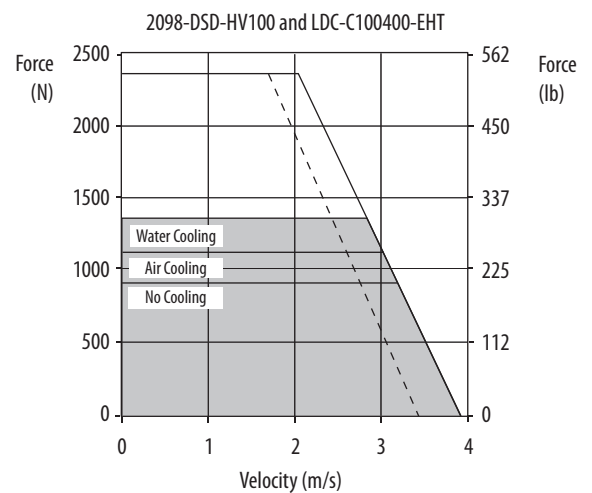
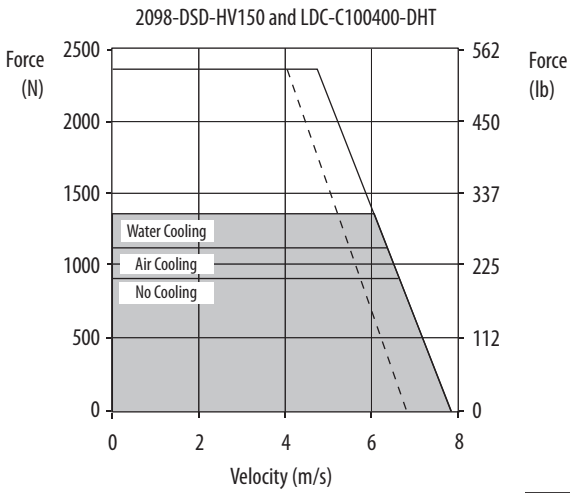
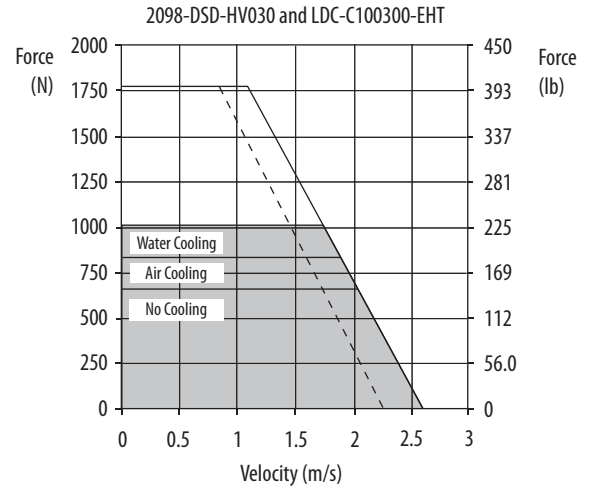
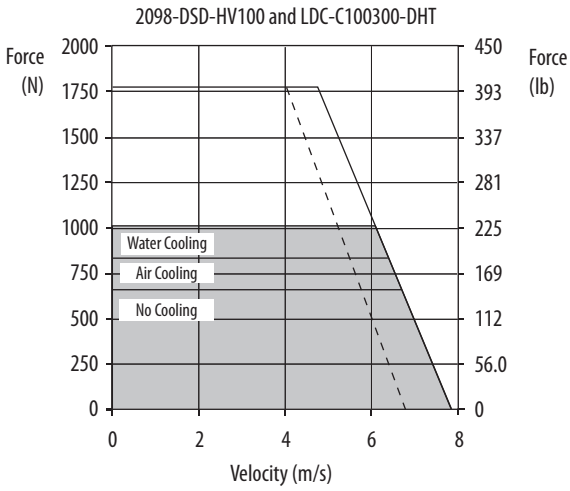
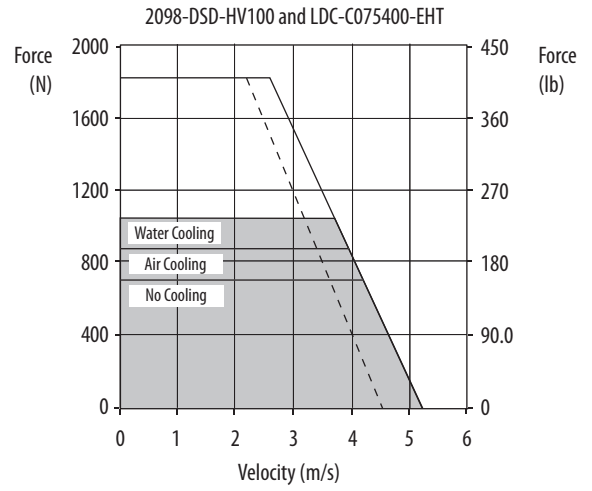
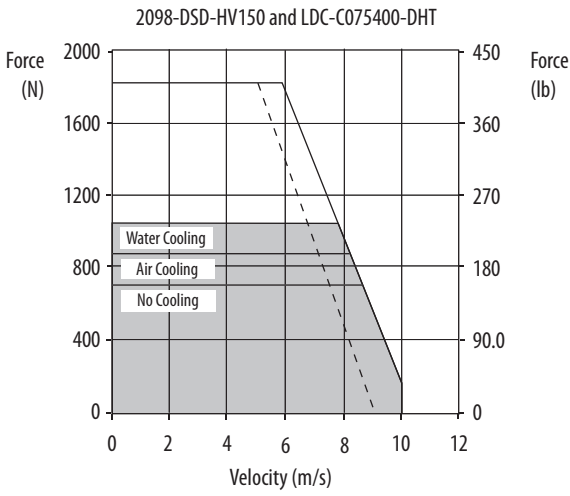
- = Intermittent operating region
- = Intermittent operating region with 400V AC (rms) input voltage
- = Continuous operating region

Ultra3000 (400V class) Drives/LDC-Series Linear Motor Curves (continued)



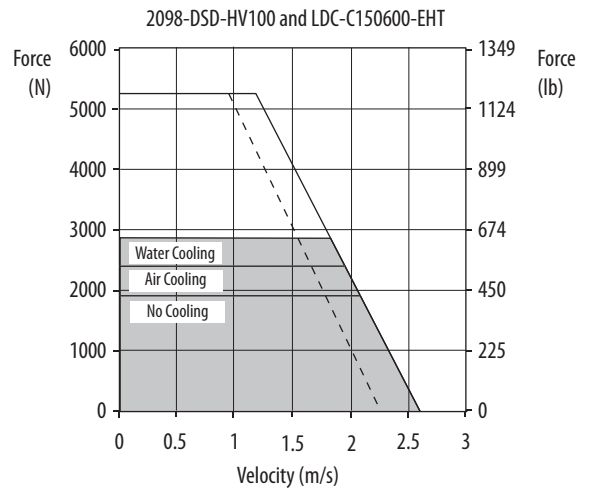
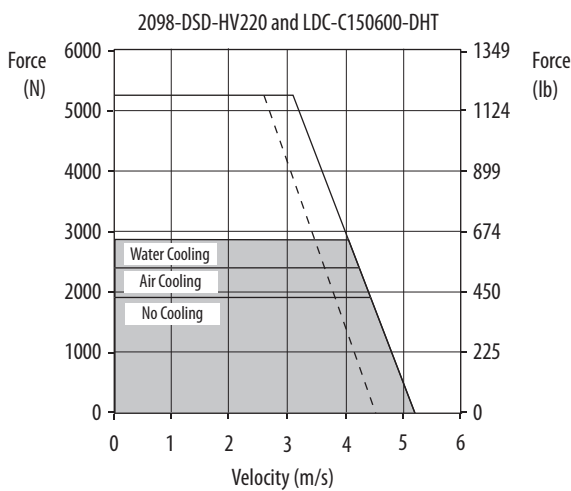
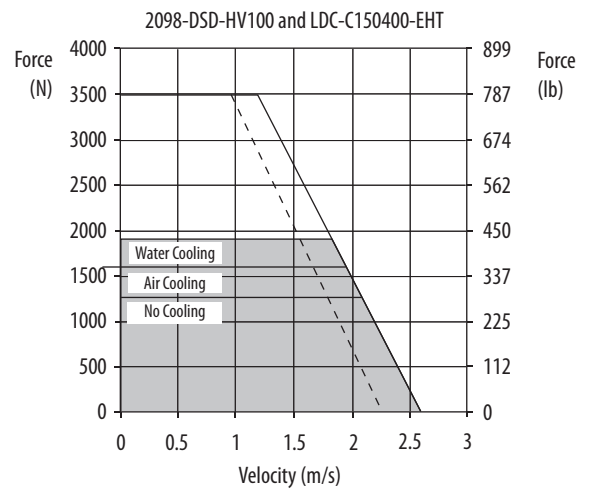
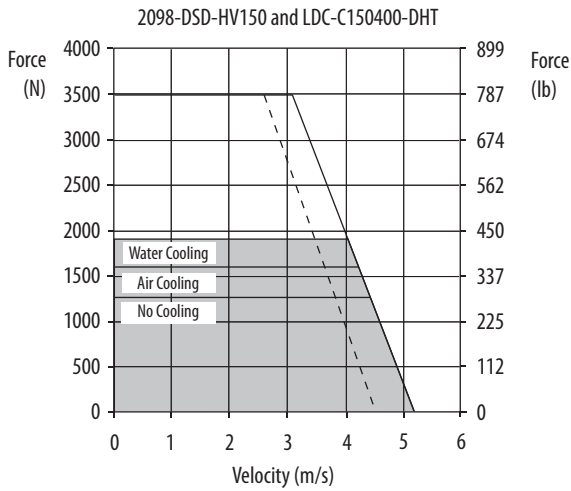
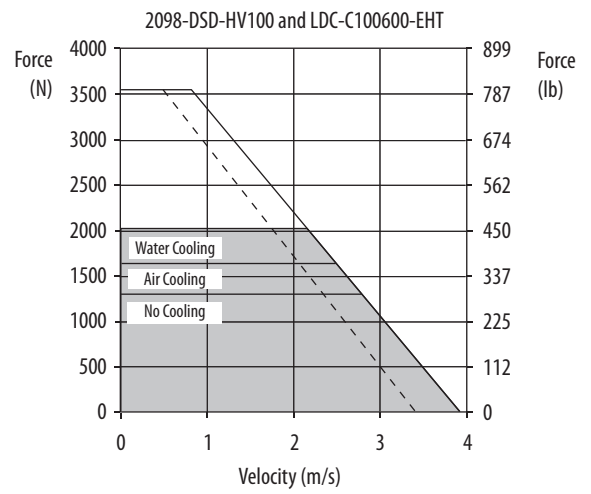
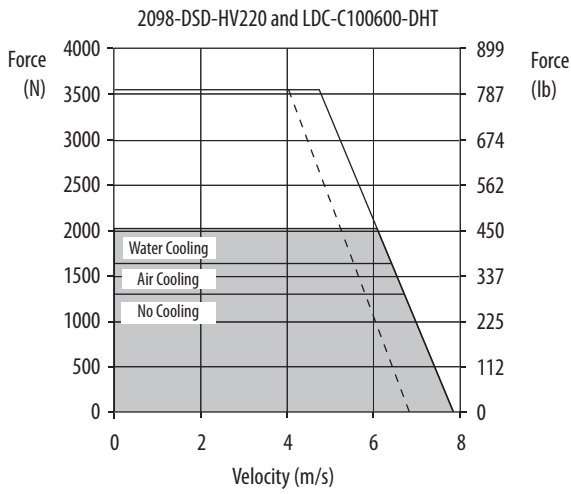
- = Intermittent operating region
- = Intermittent operating region with 400V AC (rms) input voltage
- = Continuous operating region

Ultra3000 (400V class) Drives/LDC-Series Linear Motor Curves (continued)



- = Intermittent operating region
- = Intermittent operating region with 400V AC (rms) input voltage
- = Continuous operating region

Ultra3000 (400V class) Drives/LDC-Series Linear Motor Curves (continued)



- = Intermittent operating region
- = Intermittent operating region with 400V AC (rms) input voltage
- = Continuous operating region

Ultra3000 (200V class) Drives with LDL-Series Linear Motors

This section provides system combination information for the Ultra3000 (200V class) drives when matched with LDL-Series™ ironless linear motors. Included are power and feedback cable catalog numbers, system performance specifications, and the optimum force/velocity curves.

Linear Motor Cable Combinations

| Linear Motors | Motor Power Cable | Motor Feedback Cable ⁽¹⁾ |
|--------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------|
| LDL-N030120-DHT, LDL-N030240-DHT, LDL-N030240-EHT | 2090-CPxM7DF-16AAxx (standard, non-flex) 2090-CPxM7DF-16AFxx (continuous-flex) | 2090-XXNFMF-Sxx (standard, non-flex) 2090-CFBM7DF-CDAFxx (continuous-flex) Sin/Cos or TTL Encoder Feedback |
| LDL-N050120-DHT, LDL-N050240-DHT, LDL-N050240-EHT, LDL-N050360-DHT, LDL-N050360-EHT, LDL-N050480-DHT, LDL-N050480-EHT | | |
| LDL-N075480-DHT, LDL-N075480-EHT | | |
| LDL-T030120-DHT, LDL-T030240-DHT, LDL-T030240-EHT | | |
| LDL-T050120-DHT, LDL-T050240-DHT, LDL-T050240-EHT, LDL-T050360-DHT, LDL-T050480-DHT, LDL-T050480-EHT | | |
| LDL-T075480-EHT, LDL-T075480-EHT | | |

(1) Use drive-mounted breakout board (catalog number 2090-UXBB-DM15) on the drive end. Refer to Required Drive Accessories on [page 4](#).

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on [page 7](#).

Motor-end connector kits, and panel-mounted breakout components (drive end), are available for motor power/brake and feedback cables. Refer to Optional Drive Accessories on [page 6](#).

Cable length xx is in meters. Refer to the Kinetix Motion Accessories Technical Data, publication [GMC-TD004](#), for standard cable lengths.

LDL-Series Performance Specifications with Ultra3000 (200V class) Drives

| Linear Motor | Speed, max m/s (ft/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Linear Motor Rated Output kW | Ultra3000 200V-class Drives |
|-----------------|--------------------------|-------------------------------------------------|--------------------------------------------|-------------------------------------------|--------------------------------------|------------------------------------|--------------------------------|
| LDL-N030120-DHT | 10.0 (32.8) | 3.0 | 63 (14) | 9.9 | 209 (47) | 0.31 | 2098-DSD-010 |
| LDL-N030240-DHT | | 6.0 | 126 (28) | 19.9 | 417 (94) | 0.63 | 2098-DSD-020 |
| LDL-N030240-EHT | | 3.0 | | 9.9 | | | 2098-DSD-010 |
| LDL-T030120-DHT | | 3.0 | 72 (16) | 9.9 | 239 (54) | 0.36 | 2098-DSD-010 |
| LDL-T030240-DHT | | 6.0 | 144 (32) | 19.9 | 479 (108) | 0.72 | 2098-DSD-020 |
| LDL-T030240-EHT | | 3.0 | | 9.9 | | | 2098-DSD-010 |

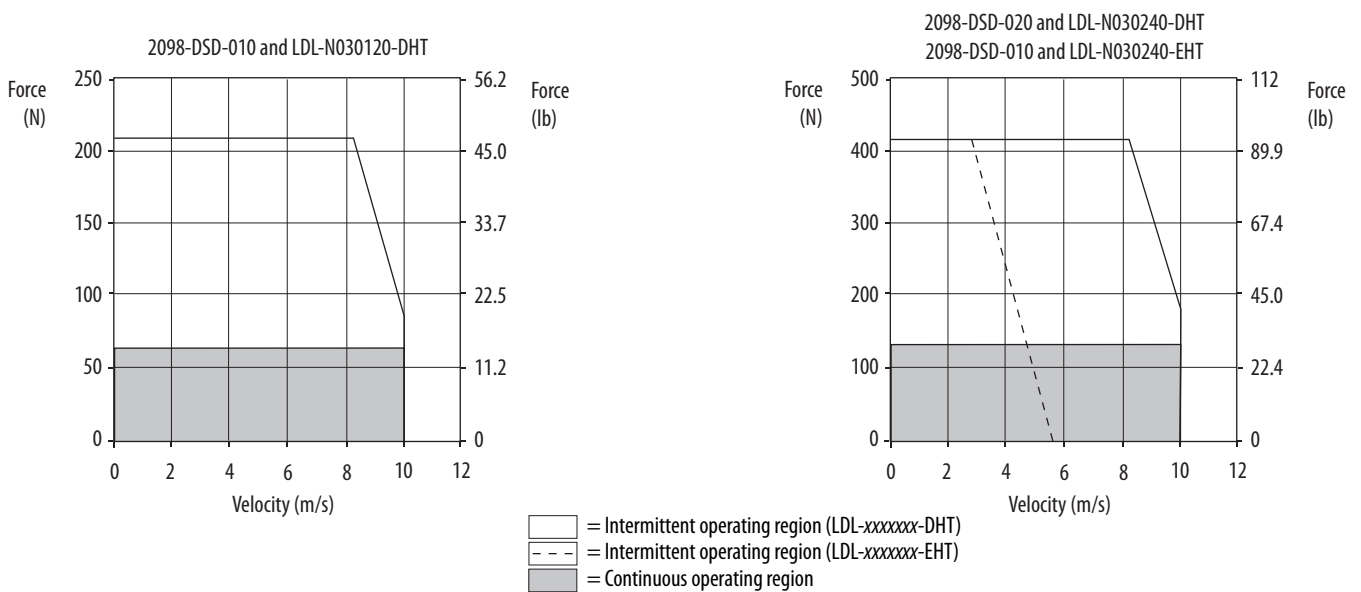
Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

LDL-Series Performance Specifications with Ultra3000 (200V class) Drives (continued)

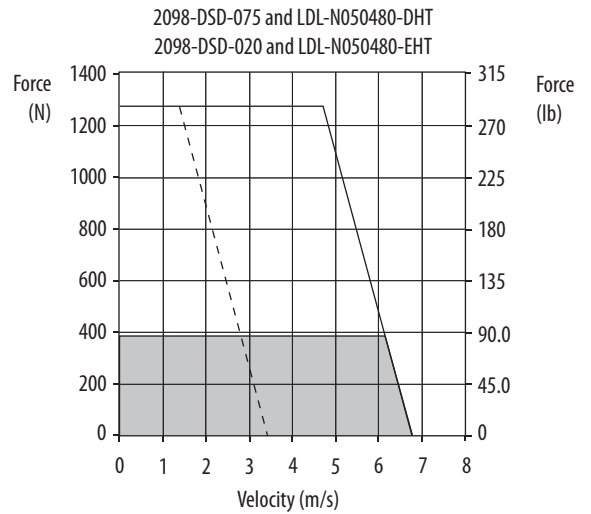
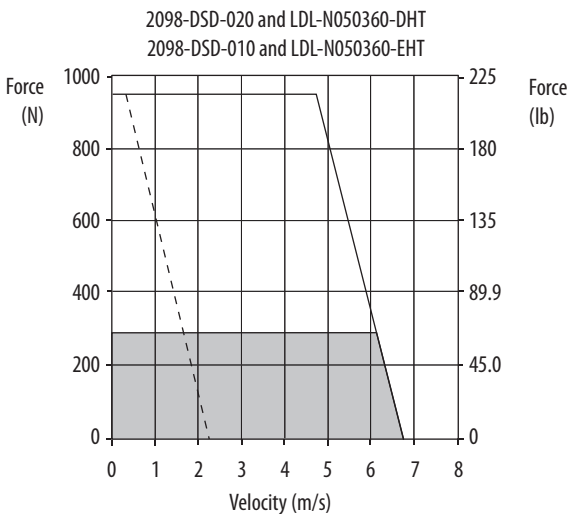
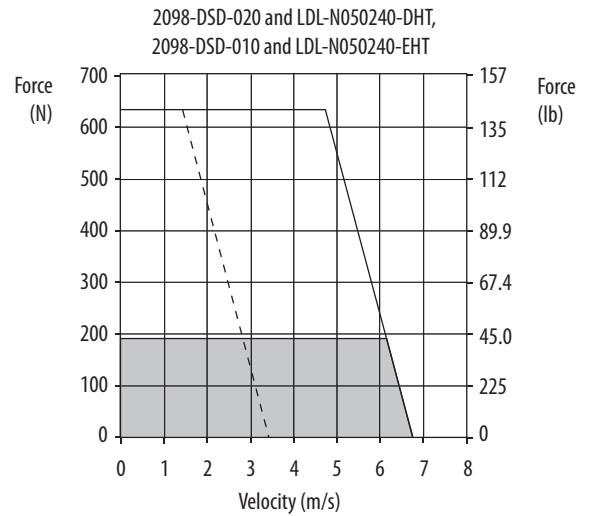
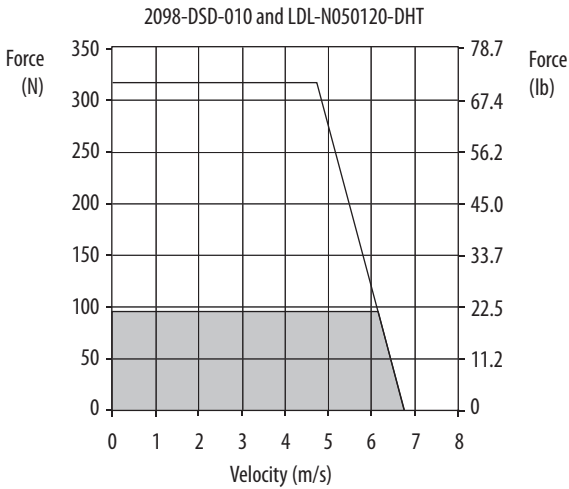
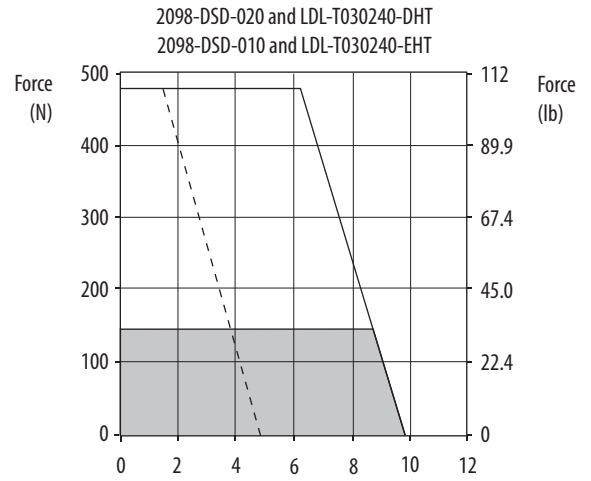
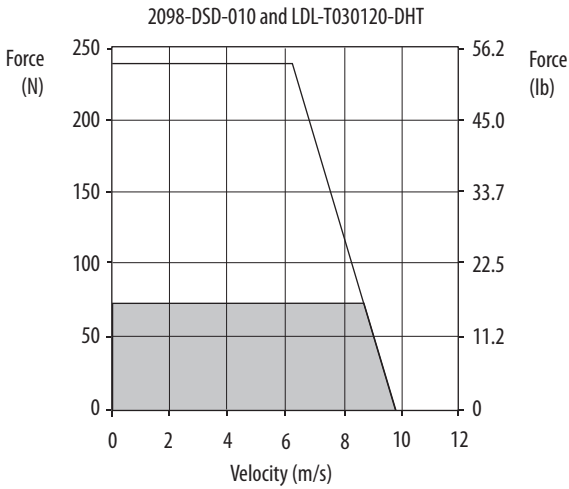
| Linear Motor | Speed, max m/s (ft/s) | System Continuous Stall Current Amps 0-pk | System Continuous Stall Force N (lb) | System Peak Stall Current Amps 0-pk | System Peak Stall Force N (lb) | Linear Motor Rated Output kW | Ultra3000 200V-class Drives | |
|-----------------|--------------------------|-------------------------------------------------|--------------------------------------------|-------------------------------------------|--------------------------------------|------------------------------------|--------------------------------|--------------|
| LDL-N050120-DHT | 10.0 (32.8) | 2.7 | 96 (22) | 9.1 | 317 (71) | 0.48 | 2098-DSD-010 | |
| LDL-N050240-DHT | | 5.5 | 191 (43) | 18.1 | 635 (143) | 0.95 | 2098-DSD-020 | |
| LDL-N050240-EHT | | 2.7 | | 9.1 | | | 2098-DSD-010 | |
| LDL-N050360-DHT | | 8.2 | 287 (65) | 27.2 | 952 (214) | 1.43 | 2098-DSD-020 | |
| LDL-N050360-EHT | | 2.7 | | 9.1 | | | 2098-DSD-010 | |
| LDL-N050480-DHT | | 10.9 | 383 (86) | 36.3 | 1269 (285) | 1.91 | 2098-DSD-075 | |
| LDL-N050480-EHT | | 5.5 | | 18.1 | | | 2098-DSD-020 | |
| LDL-T050120-DHT | | 2.7 | 110 (25) | 9.1 | 364 (82) | 0.55 | 2098-DSD-010 | |
| LDL-T050240-DHT | | 5.5 | 220 (49) | 18.1 | 728 (164) | 1.10 | 2098-DSD-020 | |
| LDL-T050240-EHT | | 2.7 | | 9.1 | | | 2098-DSD-010 | |
| LDL-T050360-DHT | | 8.2 | 329 (74) | 27.2 | 1093 (246) | 1.64 | 2098-DSD-020 | |
| LDL-T050480-DHT | | 10.9 | 439 (99) | 36.3 | 1457 (327) | 2.19 | 2098-DSD-075 | |
| LDL-T050480-EHT | | 5.5 | | 18.1 | | | 2098-DSD-020 | |
| LDL-N075480-DHT | | 10.0 (32.8) | 9.9 | 519 (117) | 32.8 | 1723 (387) | 2.59 | 2098-DSD-075 |
| LDL-N075480-EHT | | | 4.9 | | 16.4 | | | 2098-DSD-020 |
| LDL-T075480-DHT | | | 9.9 | 596 (134) | 32.8 | 1977 (444) | 2.98 | 2098-DSD-075 |
| LDL-T075480-EHT | 4.9 | | 16.4 | | 2098-DSD-020 | | | |

Performance specification data and curves reflect nominal system performance of a typical system with motor at 40 °C (104 °F) and drive at 50 °C (122 °F) ambient and rated line voltage. For additional information on ambient and line conditions, refer to Motion Analyzer software, version 4.7 or later.

Ultra3000 (200V class) Drives/ LDL-Series Linear Motor Curves

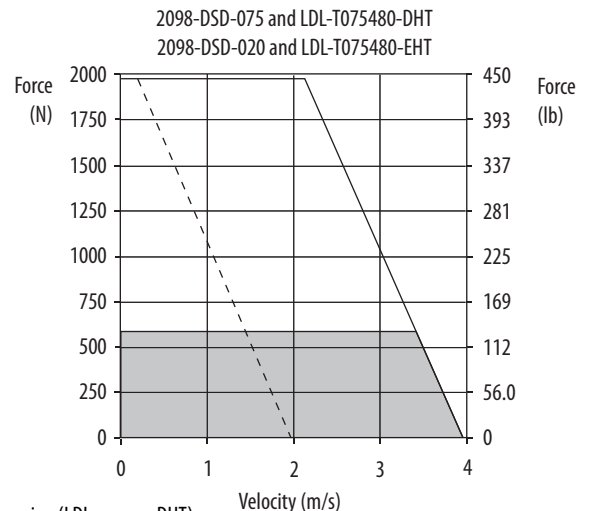
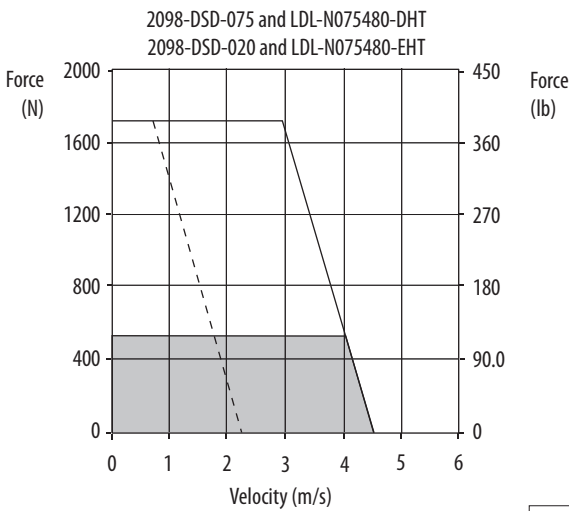
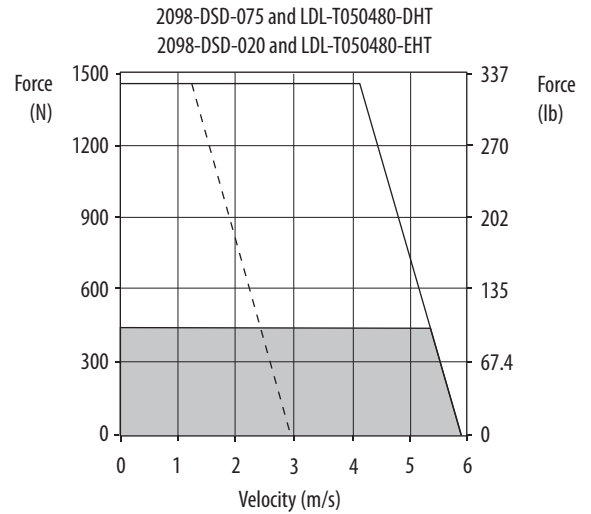
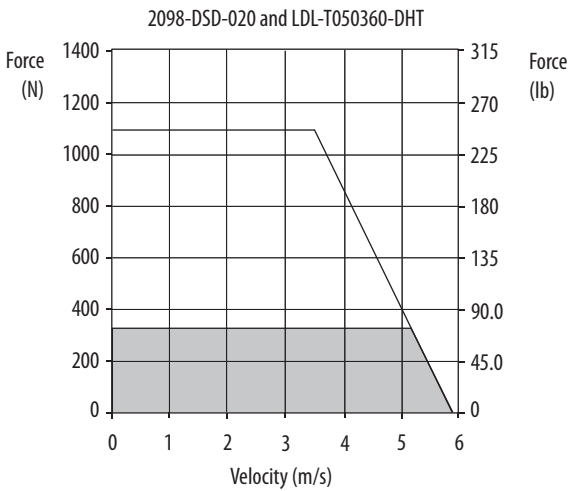
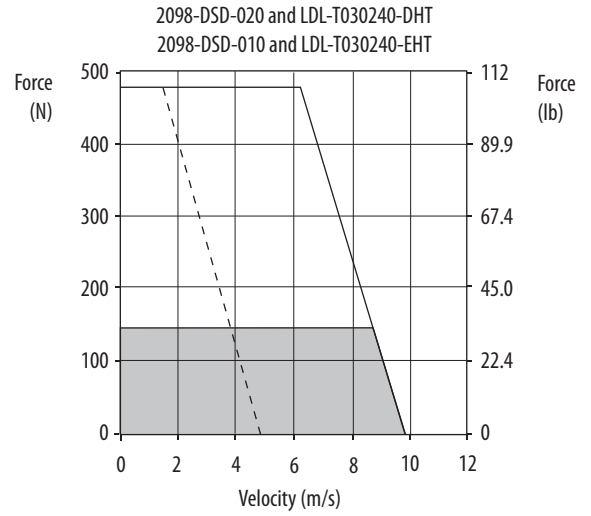
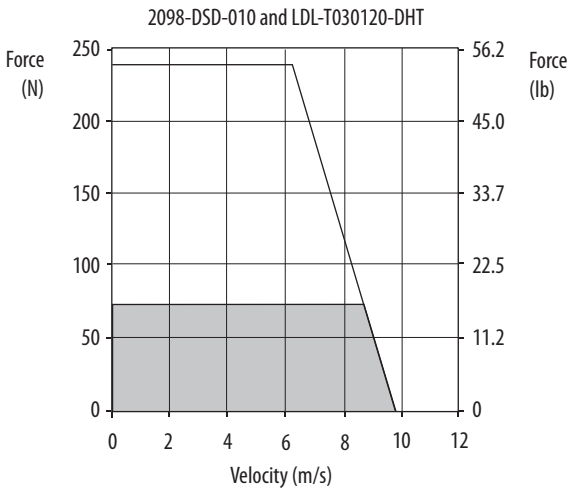


Ultra3000 (200V class) Drives/LDL-Series Linear Motor Curves (continued)



- = Intermittent operating region (LDL-xxxxxx-DHT)
- = Intermittent operating region (LDL-xxxxxx-EHT)
- = Continuous operating region

Ultra3000 (200V class) Drives/LDL-Series Linear Motor Curves (continued)



= Intermittent operating region (LDL-xxxxxx-DHT)
 = Intermittent operating region (LDL-xxxxxx-EHT)
 = Continuous operating region

Additional Resources

These documents contain additional information concerning related products from Rockwell Automation.

| Resource | Description |
|------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Kinetix Motion Control Selection Guide, publication GMC-SG001 | Overview of Kinetix servo drives, motors, actuators, and motion accessories designed to help make initial decisions for the motion control products best suited for your system requirements. |
| Kinetix Rotary Motion Specifications, publication GMC-TD001 | Product specifications for MP-Series (Bulletin MPL, MPM, MPF, MPS), TL-Series, RDD-Series™, and HPK-Series™ rotary motors. |
| Kinetix Linear Motion Specifications, publication GMC-TD002 | Product specifications for Bulletin MPAS and MPMA linear stages, Bulletin MPAI, and TLAR electric cylinders, and LDC-Series and LDL-Series linear motors. |
| Kinetix Servo Drives Specifications, publication GMC-TD003 | Product specifications for Kinetix Integrated Motion over the EtherNet/IP network, Integrated Motion over SERCOS interface, EtherNet/IP networking, and component servo drive families. |
| Kinetix Motion Accessories Specifications, publication GMC-TD004 | Product specifications for Bulletin 2090 motor and interface cables, low-profile connector kits, drive power components, and other servo drive accessory items. |
| Kinetix 6000 and Kinetix 6200/6500 Drive Systems Design Guide, publication GMC-RM003 | System design guide to determine and select the required (drive specific) drive module, power accessory, connector kit, motor cable, and interface cable catalog numbers for your drive and motor/actuator motion control system. Included are system performance specifications and torque/speed curves (rotary motion) and force/velocity curves (linear motion) for your motion application. |
| Kinetix 300/350 Drive Systems Design Guide, publication GMC-RM004 | |
| Kinetix 3 Drive Systems Design Guide, publication GMC-RM005 | |
| Kinetix 2000 Drive Systems Design Guide, publication GMC-RM006 | |
| Kinetix 7000 Drive Systems Design Guide, publication GMC-RM007 | |
| Kinetix 6200 and Kinetix 6500 Safe Speed Monitoring Servo Drives Safety Reference Manual, publication 2094-RM001 | Information on wiring, configuring, and troubleshooting the safe-speed features of your Kinetix 6200 and Kinetix 6500 drives. |
| Kinetix 6200 and Kinetix 6500 Safe Torque-off Servo Drives Safety Reference Manual, publication 2094-RM002 | Information on wiring, configuring, and troubleshooting the safe torque-off features of your Kinetix 6200 and Kinetix 6500 drives. |
| Kinetix Safe-off Feature Safety Reference Manual, publication GMC-RM002 | Information on wiring and troubleshooting your Kinetix 6000 and Kinetix 7000 servo drives with the safe-off feature. |
| System Design for Control of Electrical Noise Reference Manual, publication GMC-RM001 | Information, examples, and techniques designed to minimize system failures caused by electrical noise. |
| EMC Noise Management DVD, publication GMC-SP004 | |
| ControlLogix Selection Guide, publication 1756-SG001 | Information to determine which ControlLogix controller fits your application and the product specifications to help design a ControlLogix system and select the appropriate components. |
| CompactLogix Selection Guide, publication 1769-SG001 | Information to determine which CompactLogix™ controller fits your application and the product specifications to help design a CompactLogix system and select the appropriate components. |
| Integrated Architecture Recommended Literature Reference Manual, publication IASIMP-RM001 | This document provides lists of technical publications for Integrated Architecture™ products. These lists are not all-inclusive, but they do include the most-commonly accessed publications for the related products. |
| Industrial Ethernet Media Brochure, publication 1585-BR001 | Information to determine which Bulletin 1585 Ethernet cable fits your application and the product specifications to help select the appropriate components. |
| Motion Analyzer software download from http://www.ab.com/motion/software/analyzer.html | Comprehensive motion application sizing tool used for analysis, optimization, selection, and validation of your Kinetix Motion Control system. |
| Rockwell Automation Configuration and Selection Tools, website http://www.ab.com | Online product selection and system configuration tools, including AutoCad (DXF) drawings. |

You can view or download publications at <http://www.rockwellautomation.com/literature/>. To order paper copies of technical documentation, contact your local Allen-Bradley distributor or Rockwell Automation sales representative.

Notes:

Important Information

Solid-state equipment has operational characteristics differing from those of electromechanical equipment. Safety Guidelines for the Application, Installation and Maintenance of Solid State Controls (publication [SGI-1.1](#) available from your local Rockwell Automation sales office or online at <http://www.rockwellautomation.com/literature/>) describes some important differences between solid-state equipment and hard-wired electromechanical devices. Because of this difference, and also because of the wide variety of uses for solid-state equipment, all persons responsible for applying this equipment must satisfy themselves that each intended application of this equipment is acceptable.

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